St. Petersburg State University of Aerospace Instrumentation Institute for High-performance Computer and Network Technologies

Parallel Programming Model for Distributed Architecture MPSoC.

Prof. *Yuriy Sheynin*, Director, Doctor of Science

190 000 St. Petersburg Bolshaya Morskaya str., No 67 Fax: +7 812 3157778 E-mail: sheynin@online.ru

Distributed Architecture MPSoC

- Heterogeneous distributed scalable architectures with coarse-grained cores are the trend in embedded application specific MPSoC
- Programming of coarse-grained heterogeneous MPSoC remains a challenging task
- It requires new parallel programming paradigms and computational models for application specific MPSoC -- Parallel Programming Model (PPM)

What is a **Distributed Architecture**?

- Distributed control a Computing Module (Node) has its own independent local control ("program counter")
- Distributed memory a local memory in Computing Module (Node) with a separate address space. No global address space
- Message-passing interaction between Computing Modules (Nodes)

It could be called *Network Architecture* also, if it would not pull us too far into similarities with Internet ...

Parallel Programming Model incorporates

- Programmer's vision of the Computing Platform : – a generalized representation of the computer (Abstract Machine) he is programming
- Programmer's vision of a Parallel Computation (principles of operation and control)
 - parallel computation paradigm and model
- Programmer's vision of Parallel Programming itself

 Parallel programming methodology and Parallel
 programming language



MPSoC as a platform for applicationspecific parallel computations

MPSoC as a specific parallel computer is *an entity for implementation of co-operating processes*. Nature and features of systems of processes should define concepts and approach for a computer design and programming.

Core question:

What types of parallel computations are generated by the application-specific MPSoC workload ?

- Parallelism level and granularity
- Fixed / Static / Dynamic

MPSoC Parallelism Levels

3 levels of MPSoC Parallelism:

- Task-level parallelism (tlp) To be used in:
 - Parallel Algorithms development;
 - Parallel source code programming;
- Procedure-level parallelism (plp) To be used in:
 - Parallel source code programming;
 - Source code translation and linking;
 - Parallel program optimization;
 - Parallel object code mapping to MPSoC PEs
- MCA engines' units parallelism (mup) To be used in:
 - Procedure program optimization and local parallelization;
 - Multiple Procedure programs mapping to MPSoC PEs

Static vs Dynamic parallel computations

Static computation

- + Low control overheads
- + Low response time
- Excess MPSoC resources (PEs, memory, I/O) expenditure
- Excess power consumption
- Scheduling for maximum function processing time → overrated processing time, underrated performance
- Problems of computation adaptation to varying tasks, MPSoC components faults

Dynamic computation

- Higher control overheads
- Higher response time
- + Judicious MPSoC resources expenditure (memory, PEs)
- + Economical power consumption
- + Scheduling for actual function processing time → increased performance
- Natural computation adaptation to varying tasks, to MPSoC components faults

Rational parallel computations in application-specific MPSoCs - a combination of static and dynamic computations

Dynamic computations are parallel computations, which set of components and links between them depend on data values and change in the cause of computation

A formal Parallel Computation Model that covers both static and dynamic parallel computations is required

Asynchronous Growing Processes (AGP-model) - dynamic parallel computation model, that covers static parallel computations as its particular cases

Formal models are required for:

- Parallel Programming Language semantics specification
- Parallel algorithms and programs optimization, verification and debugging
- Mapping parallel programs to distributed heterogeneous MPSoC structure
- Tolerant control of distributed parallel computations in MPSoC
- Methodology for balancing parallel software with MPSoC features and characteristics

Asynchronous Growing Processes (AGP-models)

Schema – Partially-interpreted Schema - Program



AGP-model features and ideas (informally)

- Parallel program scheme is represented by a directed graph.
 Vertexes represent operators and data-objects.
- *All* interactions of processes are *explicitly* represented in the parallel program scheme. Processes interact through data-objects. Thus it can be controlled and verified at the level of parallel program scheme.
- Data, which are accessed by several operators, are explicitly represented in parallel program scheme as *data-objects*. Thus, data shared by several processes are in the frame of the model, as well as buffered data between a pair of operators (like in data-flow graphs)
- Control of computation in the AGP-model is defined in correspondence with MPSoC distributed architecture features. Control is *distributed*, *parallel* and *asynchronous*. It helps to fill MPSoC resources with computations and to pull high-parallel computations through limited MPSoC resources.

AGP-model features and ideas (informally), *continued*

 Parallel program scheme is transformed, in general, at every computation step – Dynamic parallel computation.
 The araph itself is changing, not, only its marking (as in data flow, computations or

The *graph itself* is changing, not only its marking (as in data-flow computations or Petri nets).

- Alternative computation (*if, case,* etc.) can be implemented as generation of alternative parallel program scheme fragments, instead of routing data to one of data-flow branches, which simultaneously occupy resources. Thus we can save MPSoC resources and power consumption.
- Static parallel computations can be represented as particular cases of dynamic computation.

It gives a way to seamless integration of dynamic and static parallel computations in a single formal model.

MPSoC Parallel programming concepts

We believe:

- Programs and algorithms should be developed as parallel ones from the beginning.
 Inherent parallelism of an application should be defined and extracted at user/application level
- Parallel programming (with a right language and right tools) is not more complicated then sequential programming
- Parallel program should be rather made correct automatically (correct by construction, verification), than debugged
- Sequential programs of processes should be absolutely encapsulated. No inter-process interaction directives inside a sequential program!

MPSoC Parallel programming concepts

Splitting programming into

- programming of a parallel program scheme and
- programming of interpretation of its nodes operators and data-objects
 Explicit programming of a parallel program scheme
- Two levels of programming languages:
 - new PPL for parallel computation scheme programming
 - conventional programming languages (C, Embedded C) for sequential process programs.

It corresponds well to the coarse-grain functions in application-specific MPSoCs.

Algorithmic completeness

- means for computations control in dependence of data values at the level of a parallel program scheme

Visa -- Parallel Programming Language for parallel program schemes programming

- The Visa language semantics is formally specified in terms of the AGPmodel
- Control operators are generators of program scheme fragments
- Program control of a computation through generation of different scheme fragments depending on data values. Dynamic and Static parallel computations unrolling.
- Visual (graphical) PPL for programming of a parallel program scheme. Parallel program scheme visual representation as a hierarchical diagram
- Visa Interactive language and visual programming tools
- Scalable language.
 Standard operators (library functions) and user definable operator types and data types (user-written C code for functions)



Conclusion

The Parallel Programming Model and the Visa PPLanguage give a way

- To work with static and dynamic parallel computations in MPSoC, with their manageable integration in particular application software for MPSoC
- To work with distributed memory paradigm (e.g. data-flow computations, message-passing) and with shared data
- To represent different programming styles and paradigms (MIMD, data parallel, data flow) in the single Programming Model, thus – integrate them in one software system
- To mate parallel scheme programming in new PPL with programming of its nodes in conventional programming languages
- To have manageable and adjustable granularity for application-specific MPSoC parallel computations.
- To build correct-by-construction parallel programs or to verify parallel program properties
- To reduce parallel program debugging to debugging of its sequential implementation

Conclusion

 Research is going on to get all these fine features and properties for wider classes of parallel software for MPSoC

