



Foundations for Model-Based Design

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MPSOC 2005 Margaux, France July 11, 2005





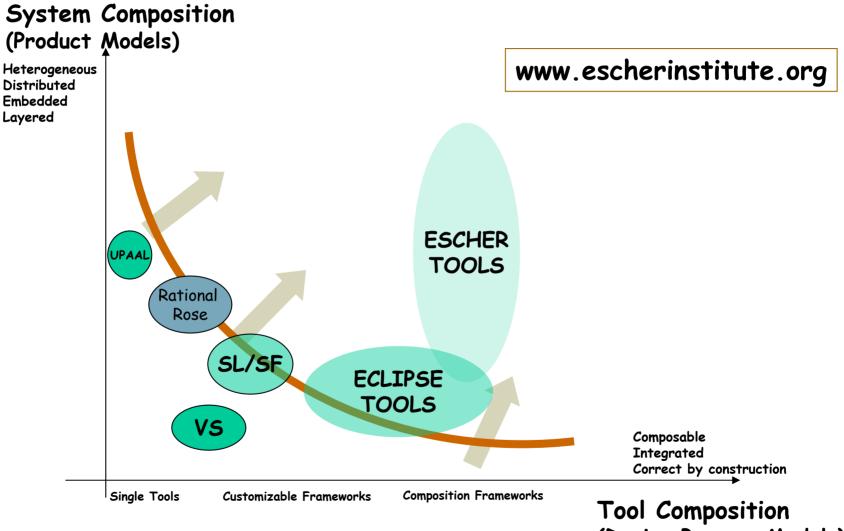
- Introduction to model-based design
- System Composition Dimension
 - Layers
 - Approaches
 - Languages
- Tool Composition Dimension
 - Layers
 - Building Tool Chains
- Metamodeling and Metaprogrammable Tools
- Semantics





- Building increasingly complex networked systems from components
 - Naïve "plug-and-play" approach does not work in embedded systems (neither in larger nonembedded systems)
 - Model-based software design focuses on the *formal representation, composition, analysis and manipulation of models* during the design process.
- Approaches with differences in focus and details
 - MDA: Model Driven Architecture
 - MDD: Model-Driven Design
 - MDE: Model-Driven Engineering
 - MIC: Model-Integrated Computing





(Design Process Models)





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System Composition Dimension: Core Modeling Aspects



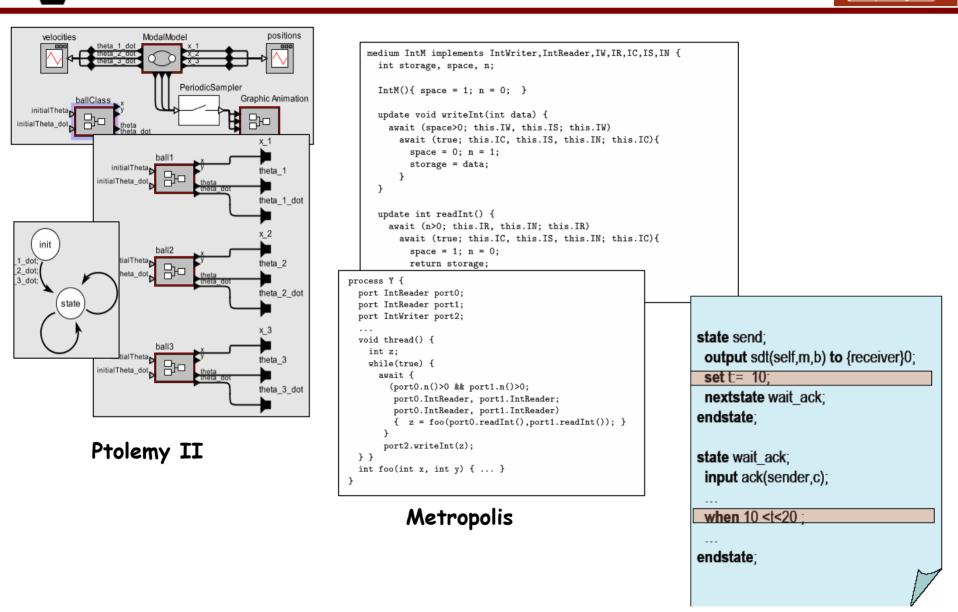
Component Behavior	 Modeled on different levels of abstraction: Transition systems (FSM, Time Automata, Cont. Dynamics, Hybrid), fundamental role of time models Precise relationship among abstraction levels Research: dynamic/adaptive behavior
Structure	Expressed as a system topology : • Module Interconnection (Nodes, Ports, Connections) • Hierarchy • Research: dynamic topology
Interaction	 Describes interaction patterns among components: Set of well-defined Models of Computations (MoC) (SR, SDF, DE,) Heterogeneous, but precisely defined interactions Research: interface theory (time, resources,)
Scheduling / Resource Allocation	Mapping/deploying components on platforms: • Dynamic Priority • Behavior guarantees • Research: composition of schedulers

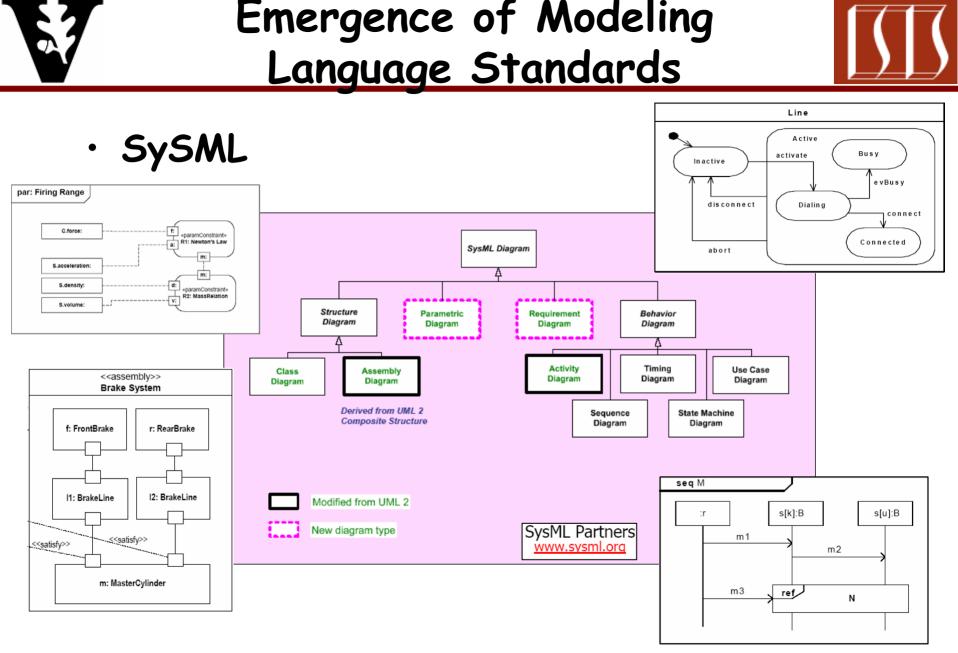
Examples for Research Approaches

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	Ptolemy II (Lee, UCB)	Metropolis (ASV ¹ , UCB)	IF (Sifakis, Verimag)
Component Behavior	Java Code/ Behavioral Models	Process (Hierarchical, Active Components)	Process (Hierarchical Timed Automaton)
Structure	Hierarchical Module Interconnection	Netlists (port, interface, connection)	Dynamically Created Channels
Interaction	Heterogeneous Models of Computation + Directors	Medium (port, parameter, useport)	Asynchronous Interactions: - P2P - Unicast - Multicast
Scheduling / Resource Allocation		Scheduler (port, parameter)	Dynamic Priorities

Modeling Formalisms Are Different





· Others (UML-2; RT-UML, SLML, AADL, ...)



Current Status of System/SW Modeling Languages



- The number of new standards is growing driven by competing consortiums and .org-s
- Intended scope ranges from "unified" to "specific".
- Many views them as programming languages
 - Wait for the "Unified One" to ensure reusability of tools
 - Slow down deployment because of the lack of standards
 - Wait for executable models
- Modeling and analysis tools are not integratable (closed camps emerge protected by a "standard").
- Semantics is largely neglected or left to undocumented interpretations of tool developers.





- Increasing acceptance of metamodeling and Domain-Specific Modeling Languages based on standard metamodels (Meta Object Facility, MOF)
- Emergence of **metaprogrammable tools**
- Desire for solving the "semantics problem"
- Better understanding of the role of precise model transformations in modelbased generators and in building domainspecific tool chains from reusable tools

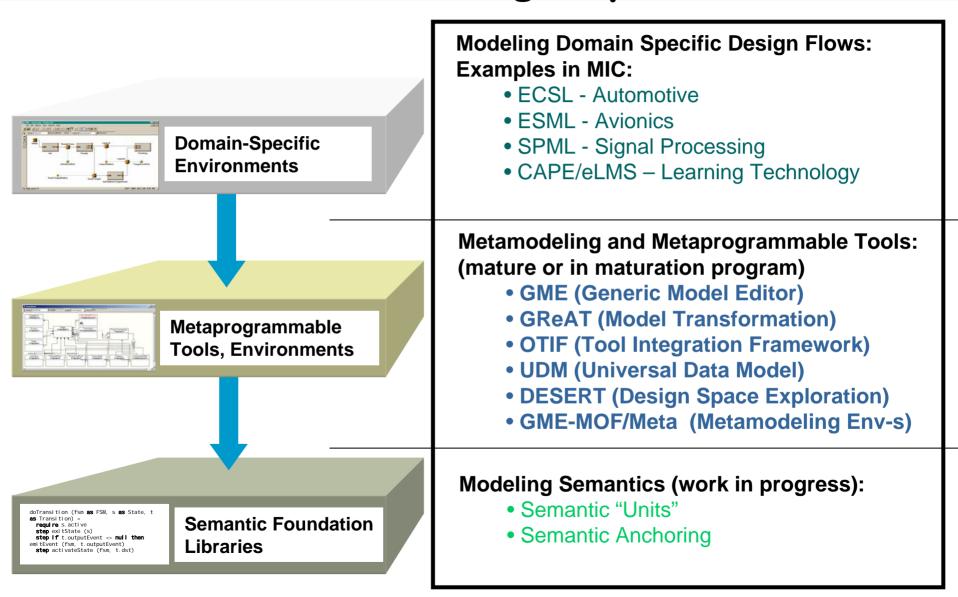




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Tool Composition Dimension: Core Modeling Aspects





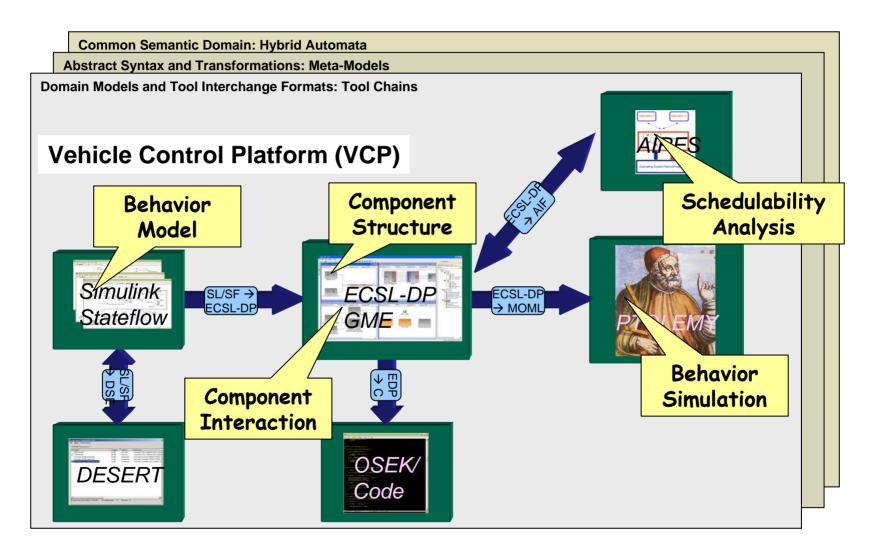


Interrelation with System Composition

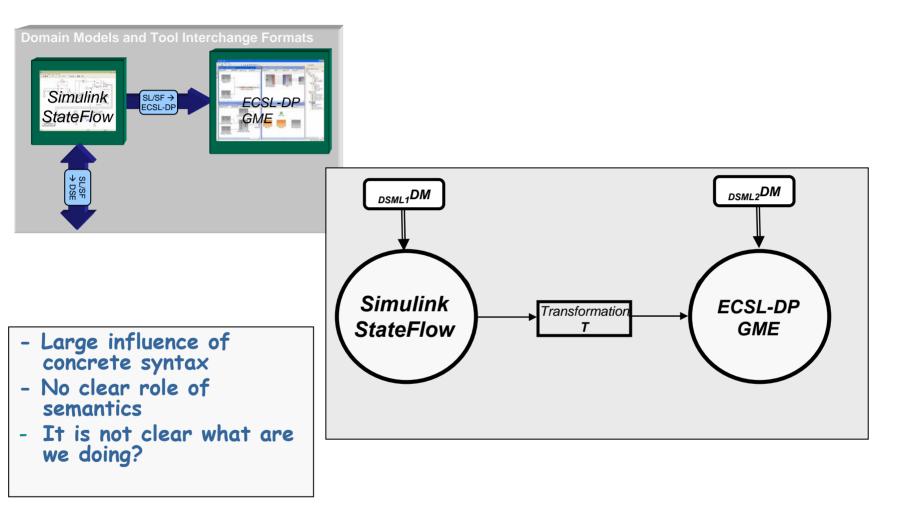


Component Behavi	 State Automaton Timed Automaton Hyprid Automaton 	Abstract Syntax + Semantic Anchoring	Behavior Modeling View
Structure	- Set-Valued Semantics	Abstract Syntax + Semantic Anchoring	Structural Modeling Views
Interaction	- Tagged Signal Model - State Automaton . imed Automaton 	Abstract Syntax + Semantic Anchoring MPOSITION PLATFO	Interaction Modeling Views RMS
Scheduling / Resource Allocation	ME - Transition Systems With Poiority		
	Semantic Foundation;	Metaprogrammable Tools, Environments	Domain-Specific Tools, Tool Chains





Constructing Tool Chains: Modeling and Transformations

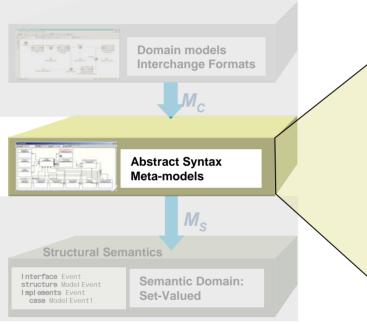






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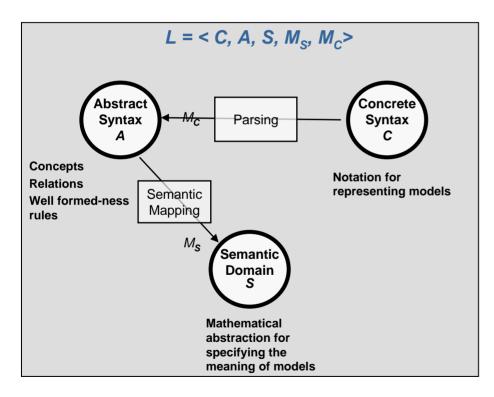
Metamodeling Layer Objectives



- Metamodeling
- Model Data Management
- Model Transformation
- Tool Integration

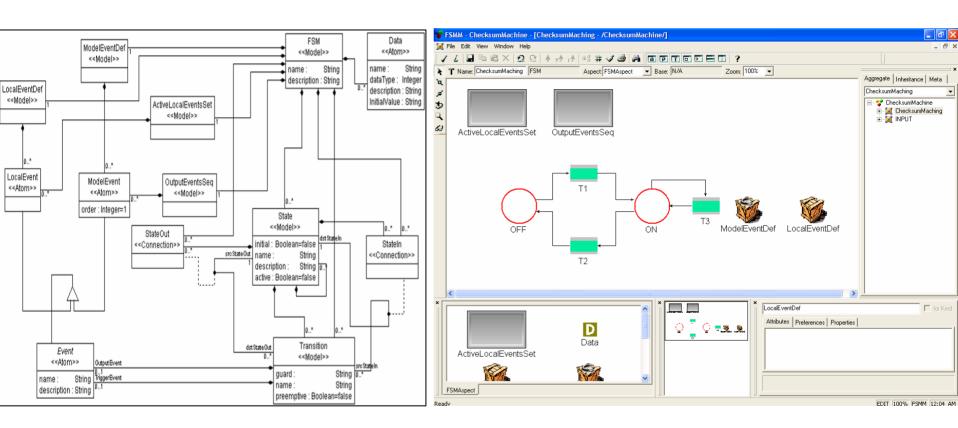
Modeling and Domain Specific Modeling Languages

Domain Specific Modeling Language (DSML)



- **Model**: precise representation of artifacts in a modeling language L
- Modeling language: defined by the notation (C), concepts/relations and integrity constraints (A), the semantic domain (S) and mapping among these.
- Metamodel: formal (i.e. precise) representation of the modeling language L using a metamodeling language L_{M} .

Modeling Example: <u>Metamodel and Models</u>



Metamodel:

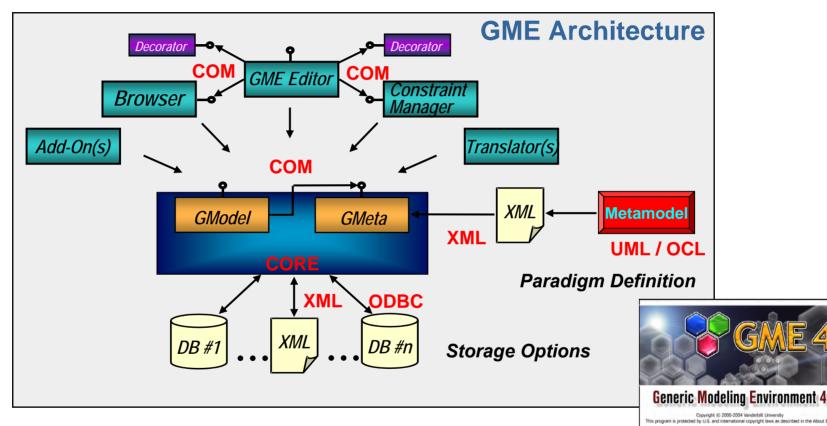
- Defines the set of admissible models
- "Metaprogramms" tool

Model:

- Describes states and transitions
- Modeling tool enforces constraints

Metaprogrammable <u>Modeling Tool: GME</u>





- Configuration through UML and OCL-based metamodels
- Extensible architecture through COM
- Multiple standard backend support (ODBC, XML)
- Multiple language support: C++, VB, Python, Java, C#

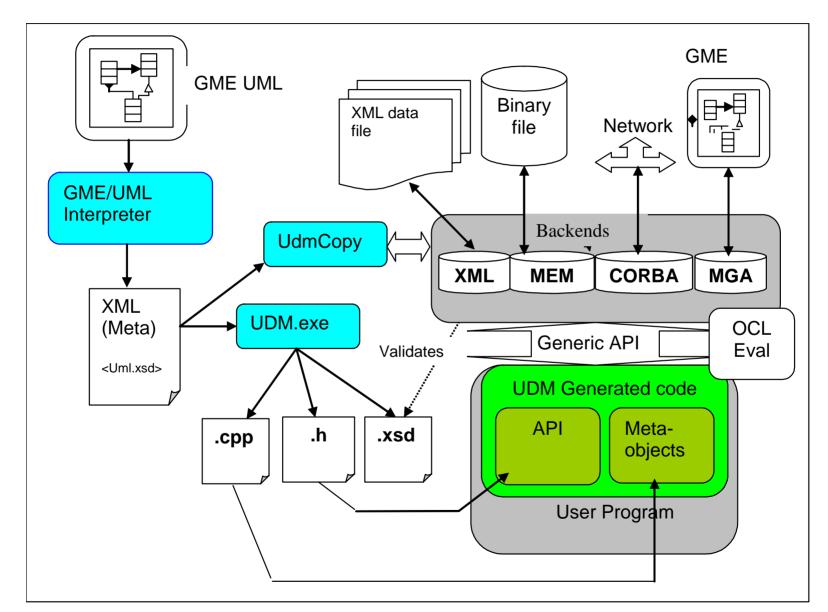




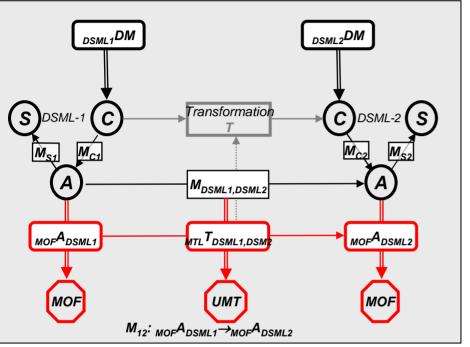
- To have a conceptual view of data/metadata that is independent of the storage format.
- Such a conceptual view should be based on standards such as UML.
- Have uniform access to data/metadata such that storage formats can be changed seamlessly at either design time or run time.
- Generate a metadata/paradigm specific API to access a particular class of data.

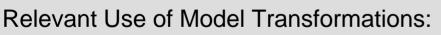
Model Data Management: The UDM Tool Suite





Model Transformation: The "Workhorse" of MIC

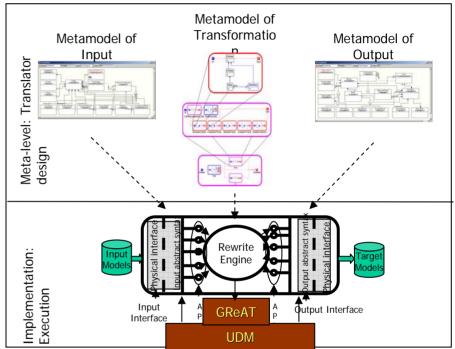




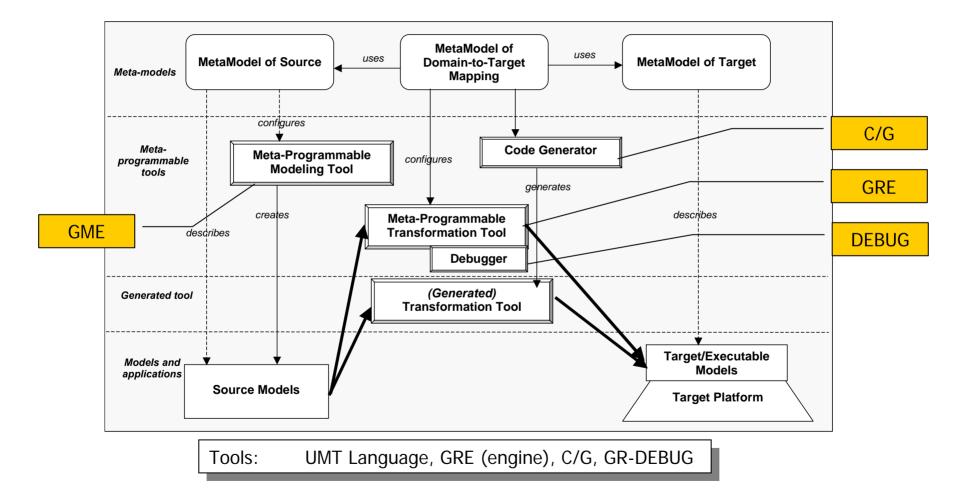
- Building integrated models by extracting information from separate model databases
- Generating models for simulation and analysis tools
- Defining semantics for DSML-s

MIC Model transformation technology is:

- Based on graph transformation semantics
- Model transformations are specified using metamodels and the code is automatically generated from the models.

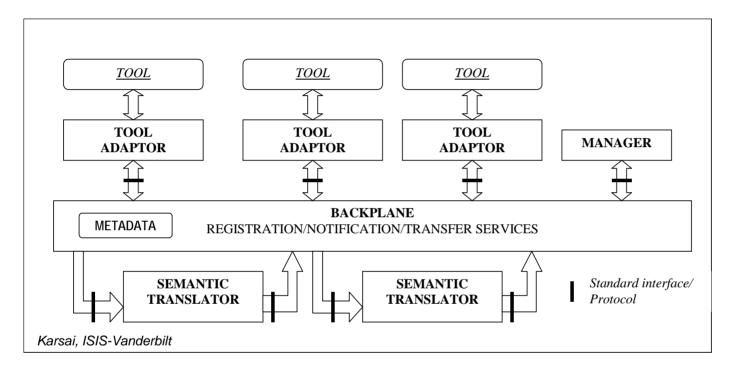


Model Transformation: The GReAT Tool Suite



Open Tool Integration Framework: OTIF





RFP is Discussed at MIC PSIG OMG

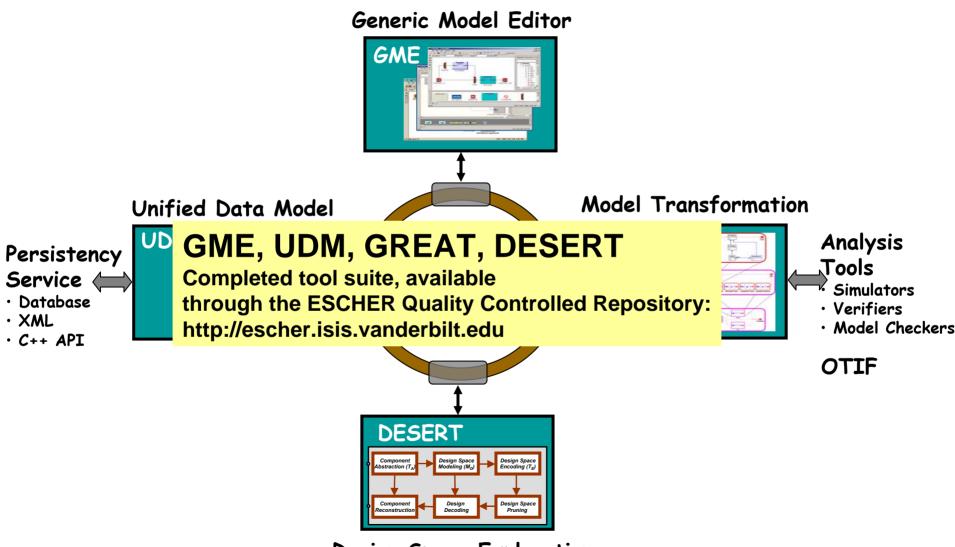
- Share models using Publish/Subscribe Metaphor
- Status:

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- Completed, tested in several tool chains
- Protocols in OMG/CORBA
- CORBA as a transport layer
- Integration with ECLIPSE is in progress

http://www.isis.vanderbilt.edu/Projects/WOTIF/default.html

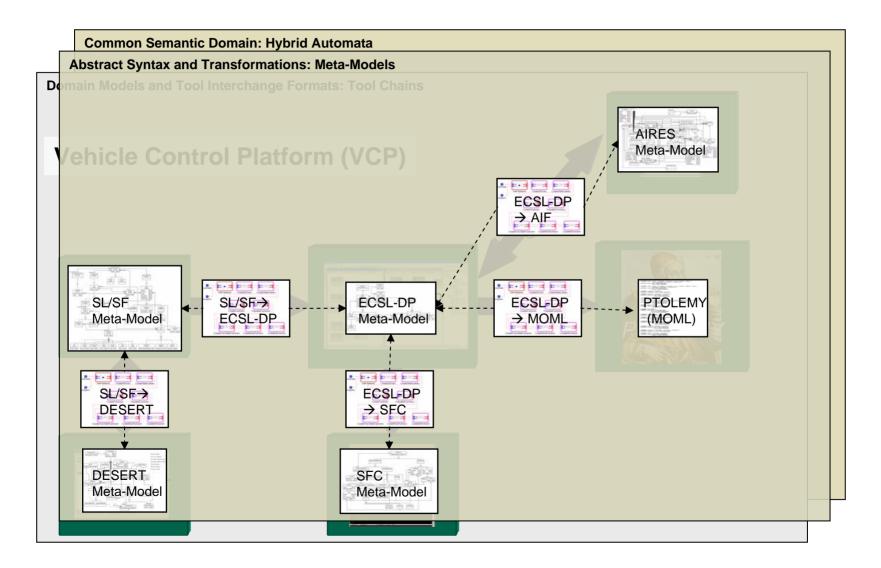
MIC Metaprogrammable Tool Suite



Design Space Exploration

"Backplane View" of the VCP Tool Chain

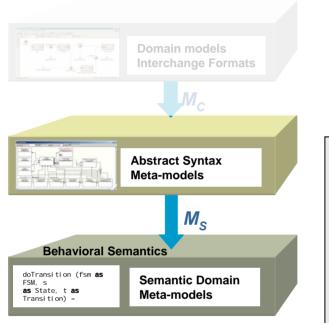




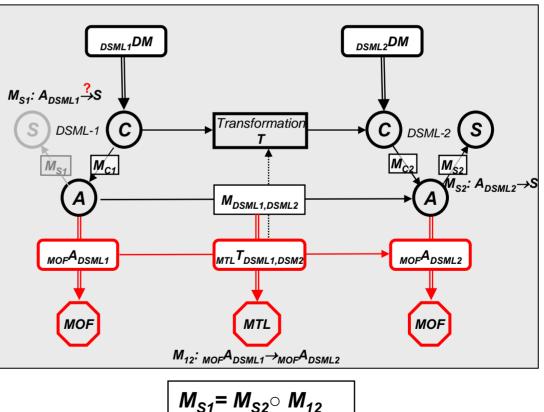




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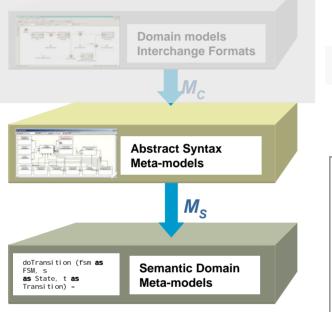


Transformational Specification of Behavioral Semantics



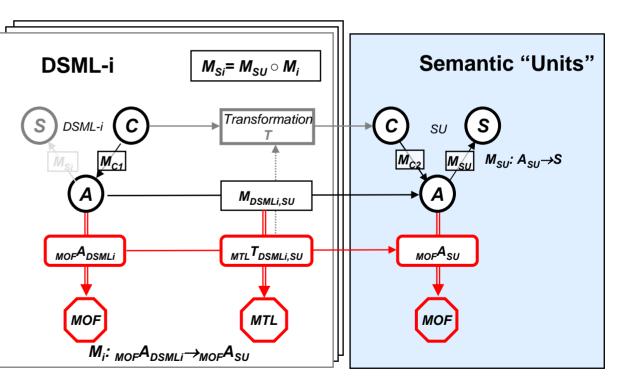


Semantic Anchoring



- The "Semantic Units" are selected common semantics such as MoC-s
- -DSML-s or their aspects are anchored to the common semantics using transformations
- The "Semantic Units" are specified in a formal framework

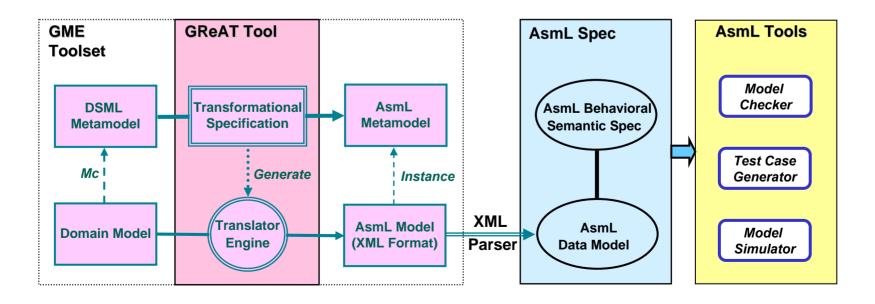
Semantic Anchoring of DSML-s



Semantic Anchoring Infrastructure



- Semantic Unit
 - A well-defined operational semantics for core Models of Computation and Behaviors (e.g. FSM).
- Semantic Anchoring
 - Define the semantics a DSML through specifying the transformation specification to a semantic unit.

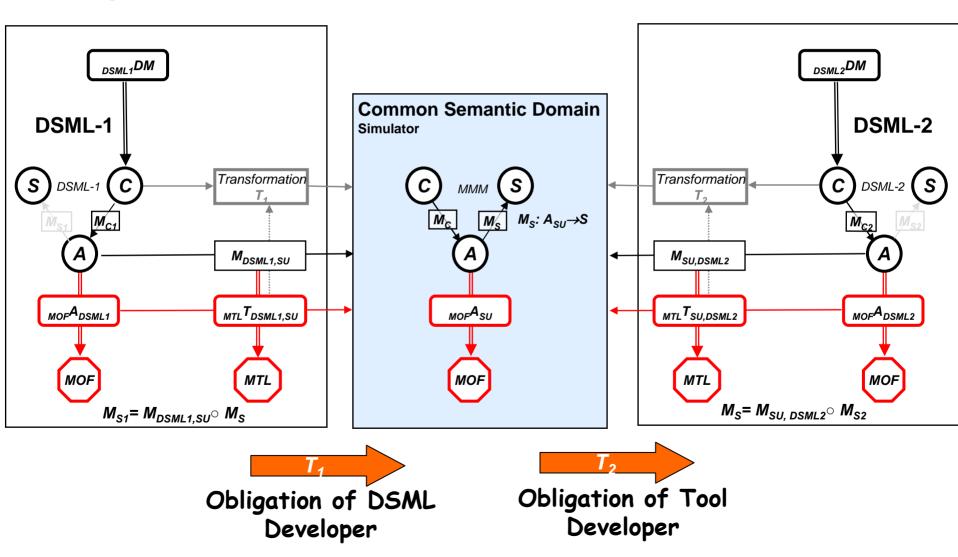






Modeling Tool

Analysis Tool





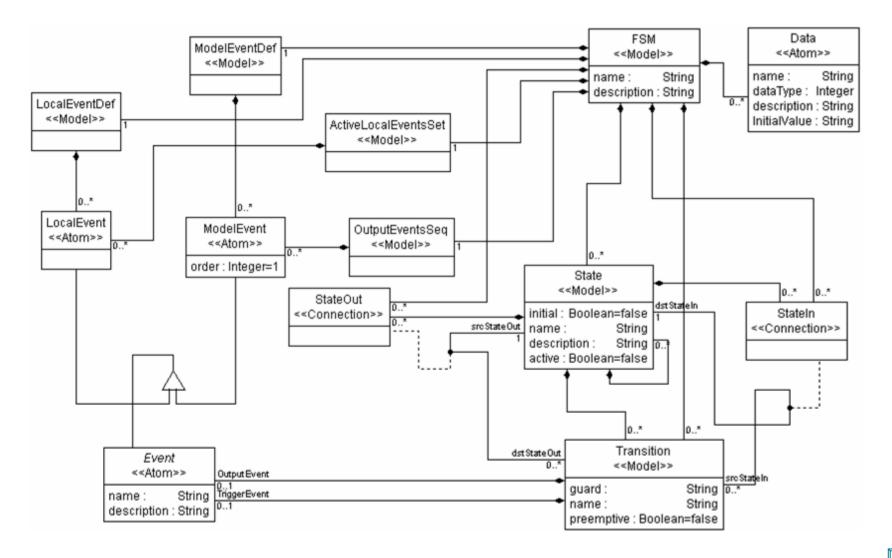


- "Plug-and-Play" component technology is not sufficient for embedded software of nontrivial size
- Model-based design addresses core issues: it integrates systems and software engineering
- Active research programs in system and tool chain composition have made significant progress in the past five years
- New frontier: explicit semantics



FSM Metamodel

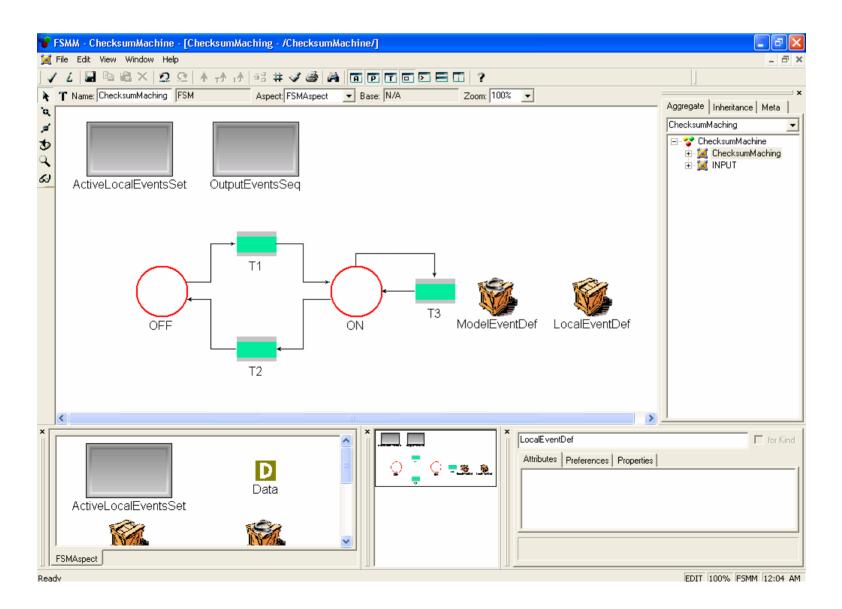






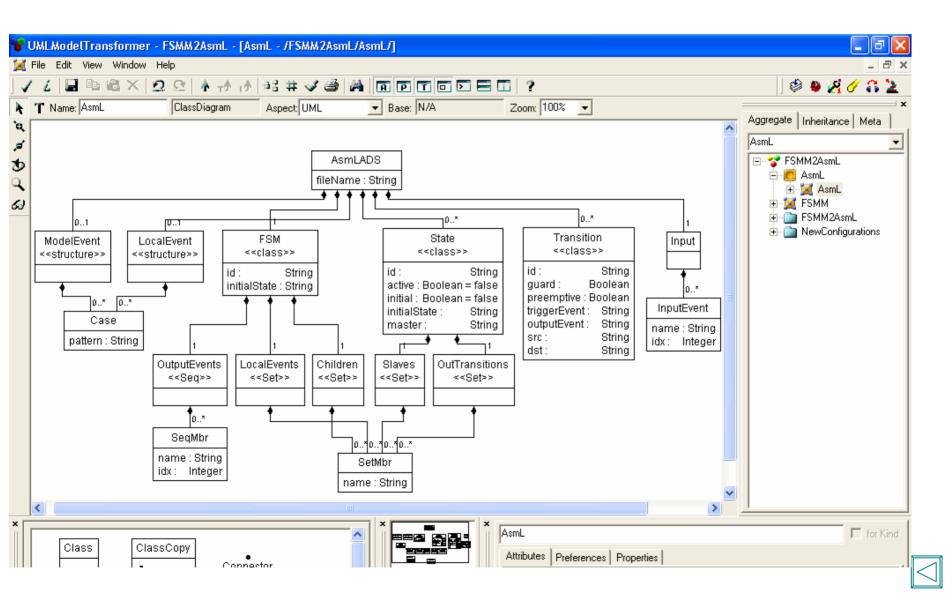
FSM Model





Metamodel for AsmL Abstract Data Model







AsmL Abstract Data Model

structure State id as String initial as Boolean structure Transition id as String structure Event id as String class StateAutomaton S as Set of State T as Set of Transition F as Set of Event Connections as Map of <Transition, (State, State)> TriggerEvent as Map of <Transition, Event?> OutputEvent as Map of <Transition. Event?> var CurrentState as State var OutputEvents as Seq of Event = [] GetOutTransitions (s as State) as Set of Transition **let** trans = {t | t **in** T **where** Connections(t).First = s}

```
return trans
GetEnabledTransitions (e as Event) as Set of Transition
let trans = GetOutTransitions(CurrentState)
let enabledTrans = {t | t in trans where TriggerEvent(t) = e or TriggerEvent(t) = null}
```

```
DoTransition(t as Transition)

step

if OutputEvent(t) <> null then

OutputEvents := OutputEvents + [OutputEvent(t)]

WriteLine ("OutputEvent " + OutputEvent(t).id)

step CurrentState := Connections(t).Second

step WriteLine ("Do transition " + t.id)

React(e as Event)

step until fixpoint
```

```
step until fixpoint
let trans = GetEnabledTransitions(e)
if Size(trans) ⇔ 0 then
choose t in trans
DoTransition(t)
```

return enabledTrans

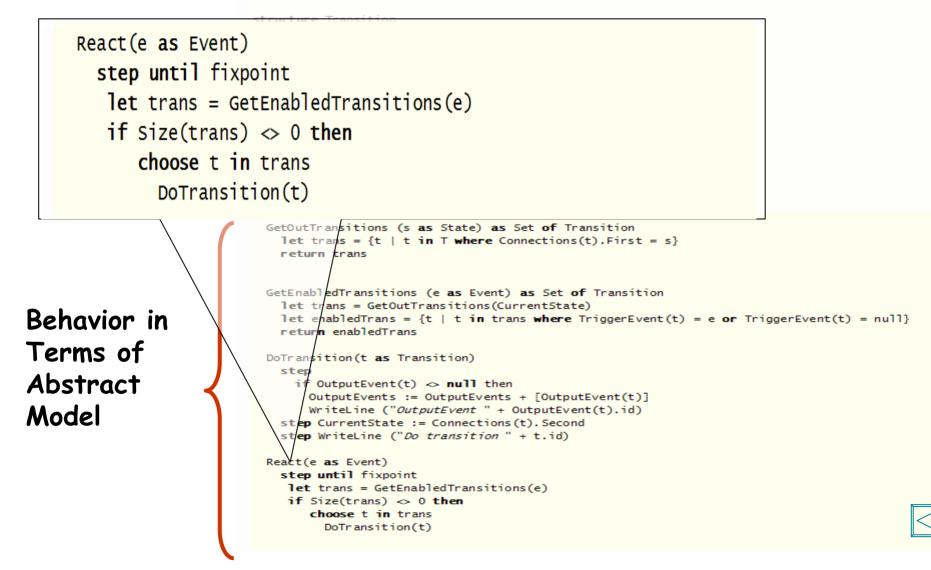
Abstract Model



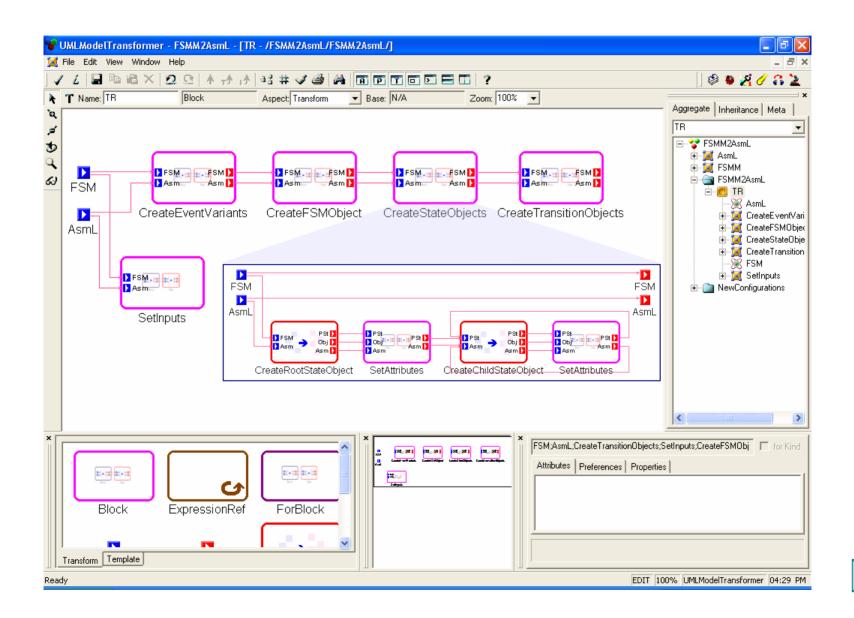
AsmL Behavioral Semantic Specifications



structure State
 id as String
 initial as Boolean



Transformational Specifications





AsmL Data Model in XML Format



- <AsmLADS _id="id988" fileName="" xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance" xsi:noNamespaceSchemaLocation="UDM\AsmL.xsd"> - <FSM id="ChecksumMaching" _id="id9d5" initialState="OFF"> + <Children id="id9f4"> <LocalEvents id="id9e5" /> <OutputEvents id="id9e0" /> </FSM> + <Input id="id98b"> + <LocalEvent id="id9bf"> + <ModelEvent id="id9ad"> - <State id="OFF" _id="ida17" active="false" master="" initial="true" initialState=""> + <OutTransitions id="ida5b"> <Slaves id="ida3d" /> </State> + <State id="ON" _id="ida18" active="false" master="" initial="false" initialState="ZERO"> + <State id="ZERO" _id="ida74" active="false" master="ON" initial="false" initialState=""> + <State id="ONE" id="ida75" active="false" master="ON" initial="false" initialState=""> <Transition id="T11" _id="idade" dst="ONE" src="ZERO" quard="true" preemptive="false" outputEvent="" triggerEvent="LocalEvent.one" /> <Transition id="T12" _id="idadf" dst="ZERO" src="ONE" quard="true" preemptive="false" outputEvent="" triggerEvent="LocalEvent.one" /> <Transition id="T13" _id="idae0" dst="ZERO" src="ZERO" quard="true" preemptive="false" outputEvent="" triggerEvent="LocalEvent.zero" /> <Transition id="T14" _id="idae1" dst="ONE" src="ONE" quard="true" preemptive="false" outputEvent="" triggerEvent="LocalEvent.zero" /> <Transition id="T1" _id="idb0e" dst="ON" src="OFF" quard="true" preemptive="false" outputEvent="ModelEvent.start" triggerEvent="" /> <Transition id="T2" _id="idb0f" dst="OFF" src="ON" quard="true" preemptive="false" outputEvent="" triggerEvent="ModelEvent.stop" /> <Transition id="T3" _id="idb10" dst="ON" src="ON" guard="true" preemptive="false" outputEvent="" triagerEvent="ModelEvent.reset" />
- </AsmLADS>





