

Philips

Parallel Programming Models for Heterogeneous MPSoCs

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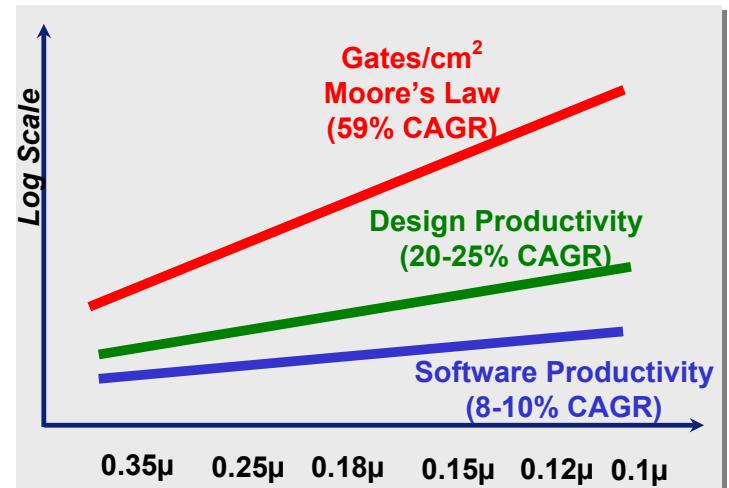
MPSOC'05
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Outline

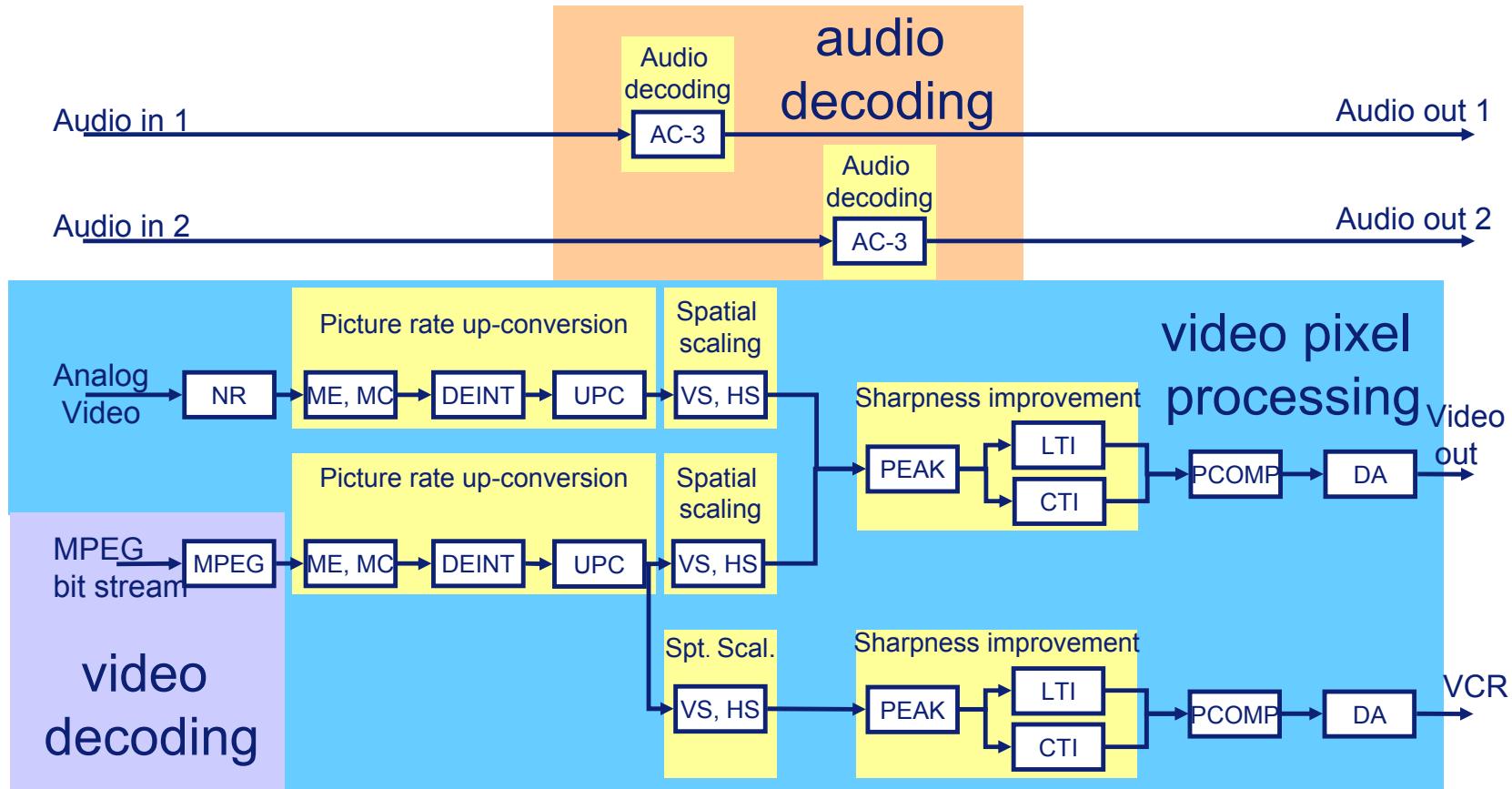
- Introduction
- Task Transaction Level interface: TTL
 - Abstract interface for streaming in MPSoCs
- Programming TTL multiprocessors
 - Constraint-driven code transformations
- Design cases
 - Sea-of-DSP
 - Smart Camera
 - Cake / Wasabi
- Conclusion

MPSoC Design

- Need for MPSoCs:
 - Implement advanced functionalities
 - Low cost
 - Power efficient
 - Flexible
- Increasing complexity of MPSoCs:
 - Increasing design efforts
 - SW effort overtaking HW effort
 - Increasing time-to-market
- Productivity increase through:
 - Raise level of abstraction
 - Structured design
 - IP reuse
 - EDA support



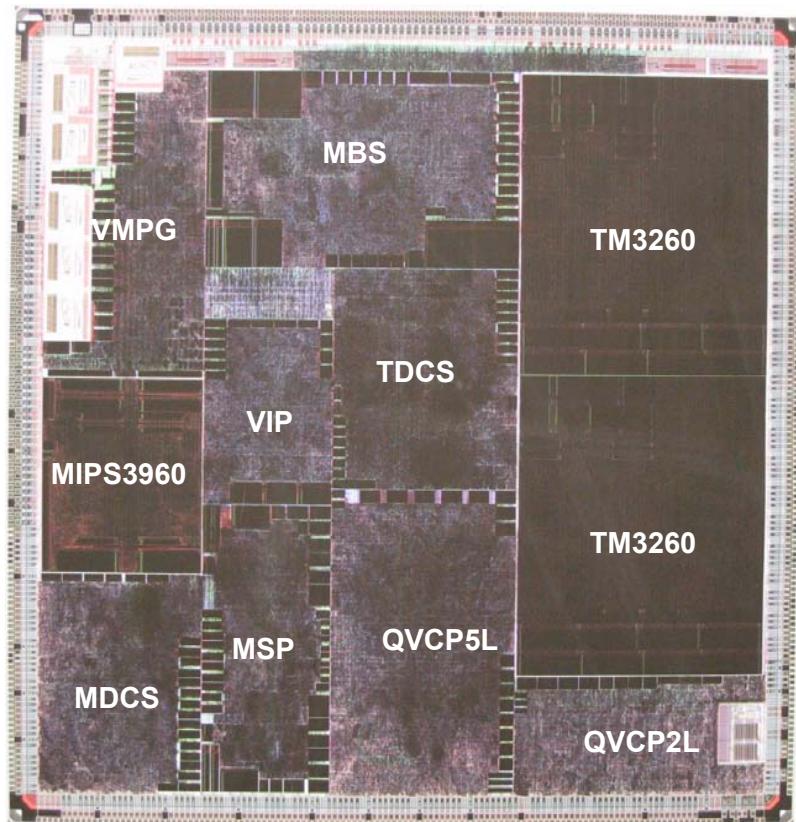
Example TV application



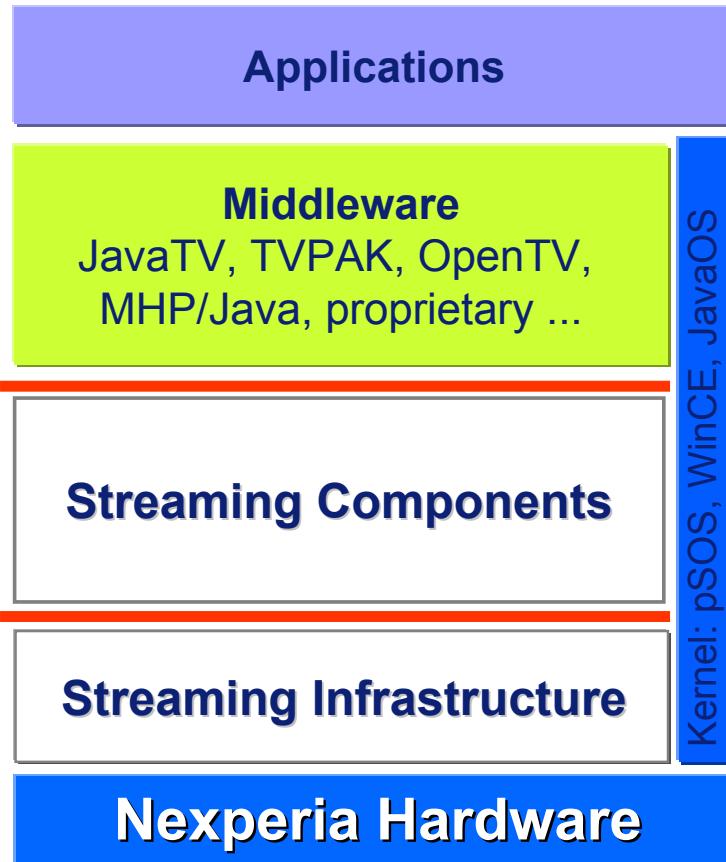
Many task graphs like this have to be supported

Example MPSoC Hardware

- Philips's advanced set-top box and digital TV SoC (Viper2)
- 0.13 μm
- 50 M transistors
- 100 clock domains
- > 60 IP blocks

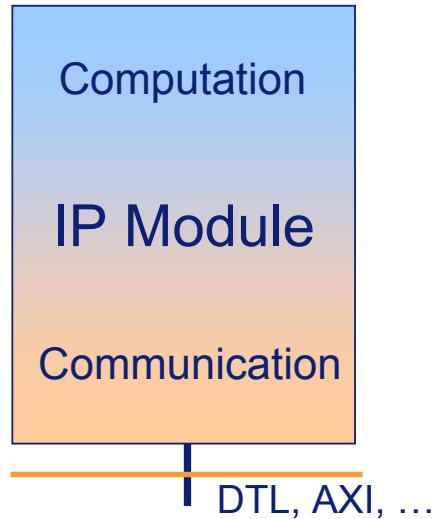


Example MPSoC Software Stack



MPSoC Integration

- Current practice
 - Ad hoc approaches
 - Low-level interfaces
- Examples
 - Synchronization via low-level primitives
 - Interrupts, MMIO, semaphores
 - Data access services partly in IP
 - Buffering, DMA control, address generation
- Consequence
 - Part of IP is specific for underlying communication infrastructure
 - IP just wants the next pixel or block or ...
 - But also knows about burst transfers, interrupts, semaphores,

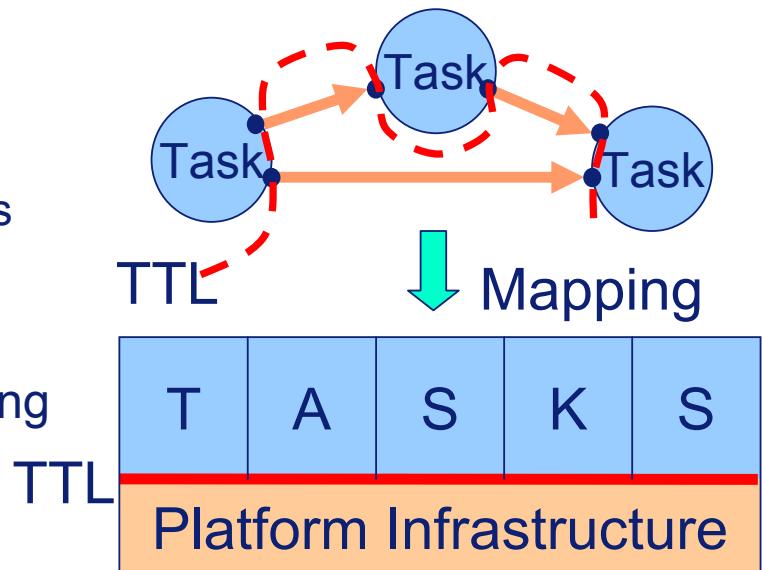


MPSoC Integration

- Low-level interfaces
 - Hardware / software IP designer must deal with low-level issues
 - Increases design effort
 - Same problems solved again and again: error prone
 - IP becomes specific for particular use
 - Hampers reusability
 - IP integrator must deal with low-level issues
 - Increases design effort
 - Infrastructures cannot evolve
 - Changes in infrastructure affect hardware / software IP

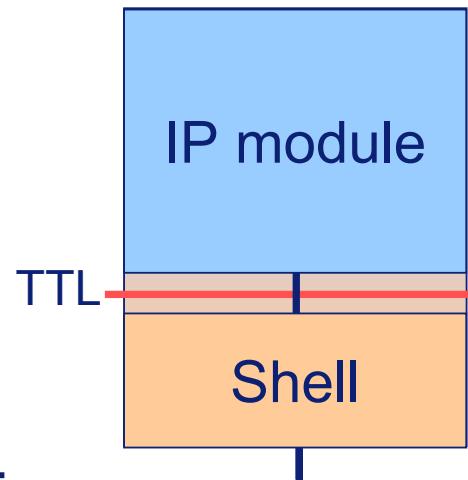
Interface Centric Design: TTL

- Aim: Improve MPSoC integration
- Means: Raise level of abstraction
- TTL Task Transaction Level interface:
 - Parallel application models
 - Executable specifications
 - Platform interface
 - Integration of HW and SW tasks
- Mapping technology
 - Structured design & programming
 - Based on TTL



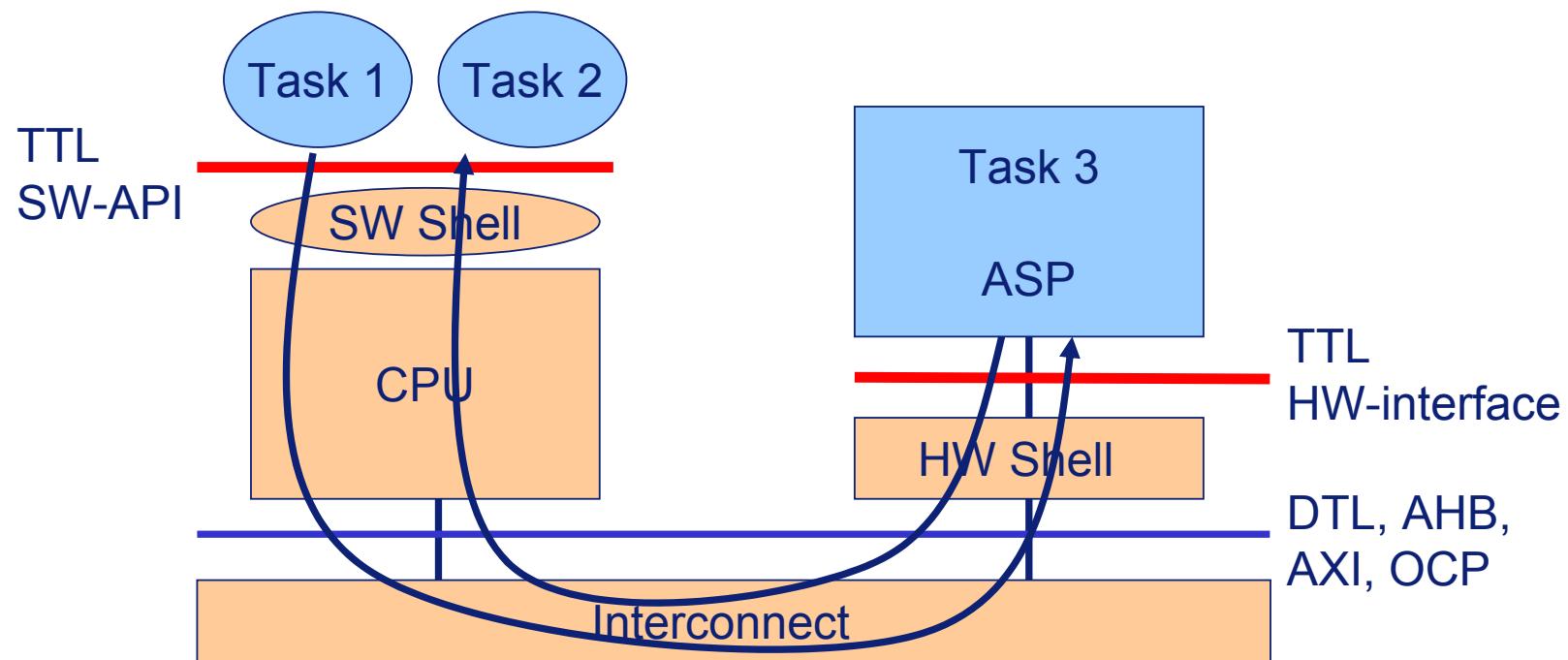
TTL Requirements

- Well-defined semantics for application modeling
 - Focus: stream processing applications
 - Make concurrency and communication explicit
- High-level interface
 - Make high-level services available
 - Inter-task communication
 - Multi-tasking
 - Easy to use for IP development
 - Facilitate reuse and integration of IP
 - Provide implementation freedom
- Allow efficient and cheap implementations
 - E.g. supporting fine grain synchronization for on-chip memory
- Support integration of hardware and software tasks



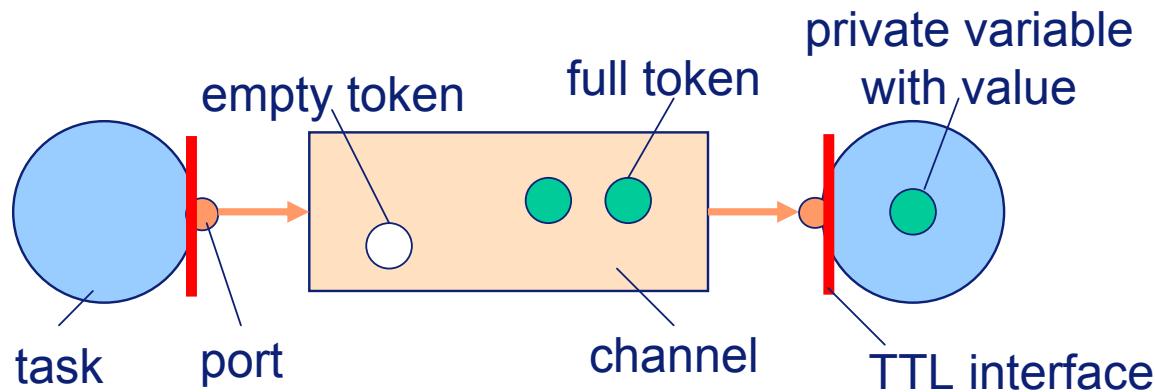
TTL in Example Architecture

- Platform interface for integration of HW and SW tasks
 - Enable communication in heterogeneous MPSoCs



TTL Inter-Task Communication

Logical model and terminology



- Communicating tasks are organized as task graph
- Tasks communicate by invoking TTL interface functions on their ports
- Uni-directional channels with reliable ordered communication
- Arbitrary data types, but single type per channel
- Support for multi-cast

Example: Message Passing Interface

Producer side

- `write(port, data, ...)`
 - Write data into channel connected to port

Consumer side

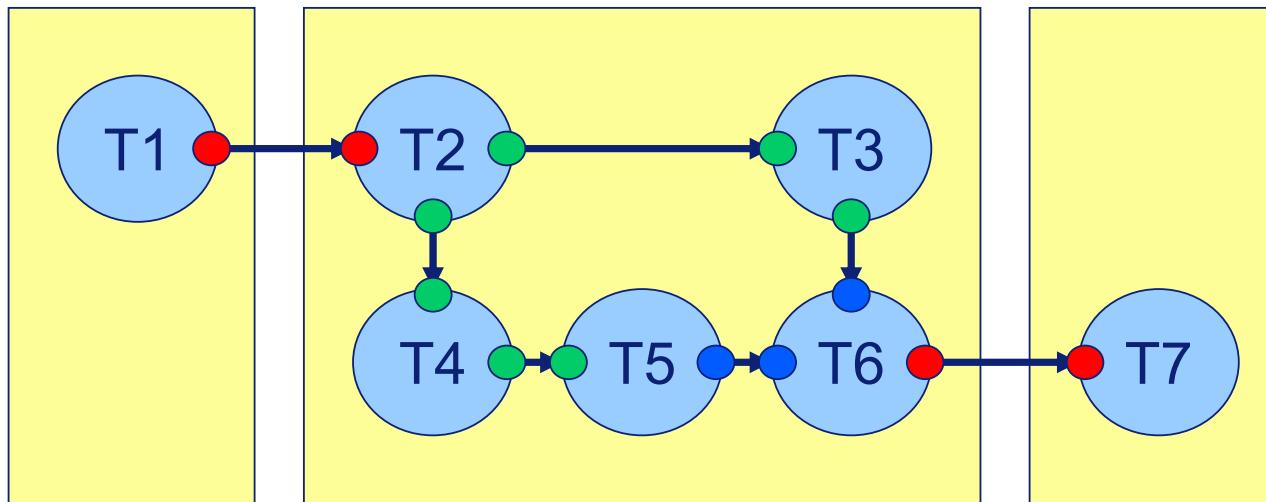
- `data = read(port, ...)`
 - Read data from channel connected to port
- Abstract interface for tasks
- Right interface ?
 - Appropriate for modeling application ?
 - Appropriate for implementation on architecture ?

TTL Interface Types

- Different needs for communication arising from:
 - Different applications
 - In-order – out-of-order
 - Different implementation styles
 - Hardware – software
 - Shared memory – message passing
- Support set of interface types
 - Each interface type offers narrow interface
 - Easy to use
 - Simple to implement
 - Each interface type supports particular communication style
 - Offer multiple interface types in one framework
 - **Based on single model for interoperability**

TTL Interface Types

- TTL offers a number of different interface types
- Allow selection of interface type per port of task
- Enable interoperability by allowing mix & match



TTL Interface Types

Acronym	Full name
CB	Combined Blocking
RB	Relative Blocking
RN	Relative Non-blocking
DBI	Direct Blocking In-order
DNI	Direct Non-blocking In-order
DBO	Direct Blocking Out-of-order
DNO	Direct Non-blocking Out-of-order

Interface Type CB

Producer side

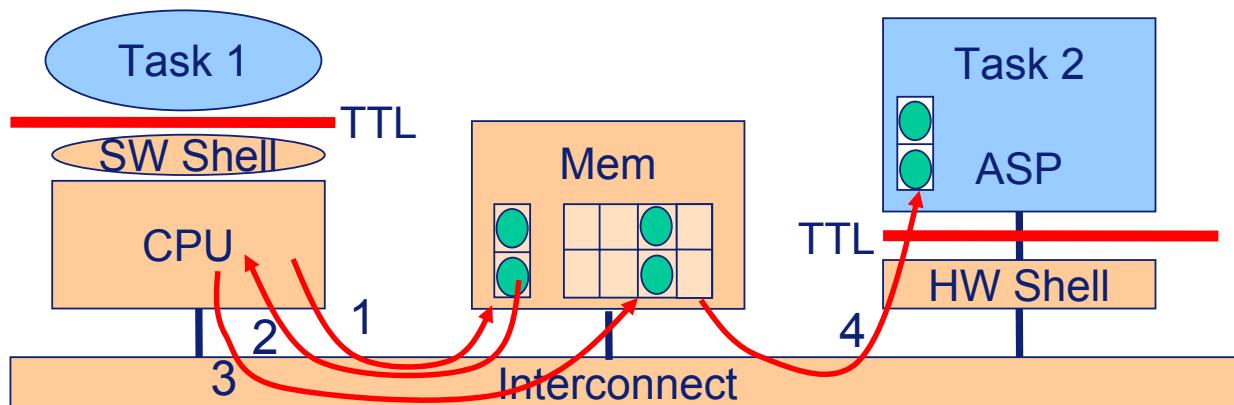
- `write(port, vector, size)`
 - Write vector of size values into channel

Consumer side

- `read(port, vector, size)`
 - Read vector of size values from channel
- Most abstract TTL interface type
- Blocking semantics
- Combined synchronization and data transfer
- Vector operations
- Based on earlier work on YAPI for KPN style modeling

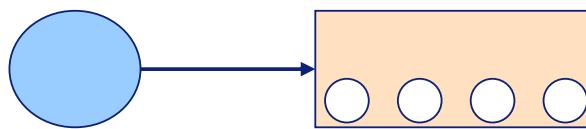
Pros / Cons Interface Type CB

- + Easy to use
- + Reusable tasks
- Copying overhead if private variables not in local buffers
 - Smart compiler may help in some cases
- If local buffers:
 - Large tokens / vectors → large local buffers
 - Small tokens / vectors → large synchronization overhead

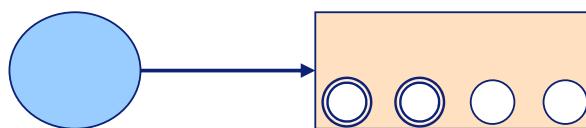


Separate Synchronization and Data Transfer

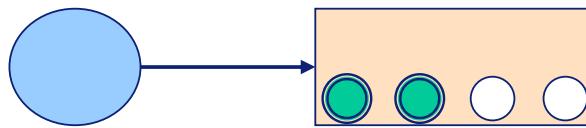
Producer



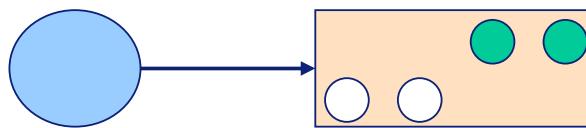
acquireRoom (2)



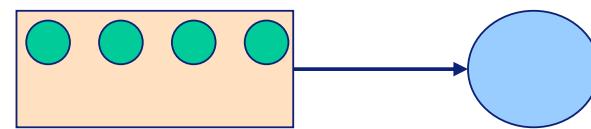
store/dereference



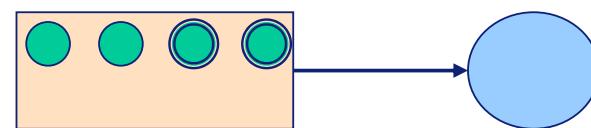
releaseData (2)



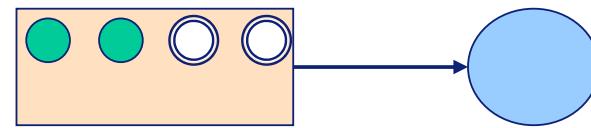
Consumer



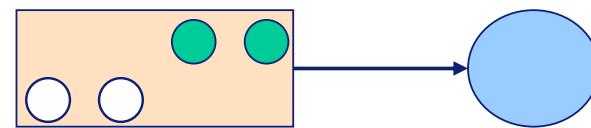
acquireData (2)



load/dereference



releaseRoom (2)



Interface Types RB and RN

Producer side

- `reAcquireRoom(port, count)` (RB)
- `tryReAcquireRoom(port, count)` (RN)
 - Acquire count empty tokens, blocking (RB) / non-blocking (RN)
- `store(port, offset, vector, size)`
 - Store vector of size values into the tokens with offset..offset+size-1 to the oldest acquired token
- `releaseData(port, count)`
 - Release count oldest acquired tokens as full tokens
- Separate synchronization and data transfer
- Vector operations
- Re-acquire operations do not change state of the channel

Pros / Cons Interface Types RB / RN

- + Coarse grain synchronization with fine grain data transfer
 - Low synchronization overhead with small local buffers
- + Out-of-order data accesses
 - Reduce cost of private variables
- + Load only subset of tokens from channel
 - Reduce cost of data transfers
- Less abstract than CB
 - Increases programming effort
 - Makes tasks less reusable
- Inefficiencies upon data transfers
 - Function call, access to channel admin, address calculations
- Copying may still occur

Interface Types DBI and DNI

Producer side

- `acquireRoom(port, &token)` (DBI)
- `tryAcquireRoom(port, &token)` (DNI)
 - Acquire empty token, blocking (DBI) / non-blocking (DNI)
- `token->field = value;`
 - Assign value to (part of) token
- `releaseData(port)`
 - Release oldest acquired token as full token
- Separate synchronization and data transfer
- Direct access to data via token references (pointers)
- Scalar operations only
- Tokens are released in same order as they are acquired

Pros / Cons Interface Types DBI / DNI

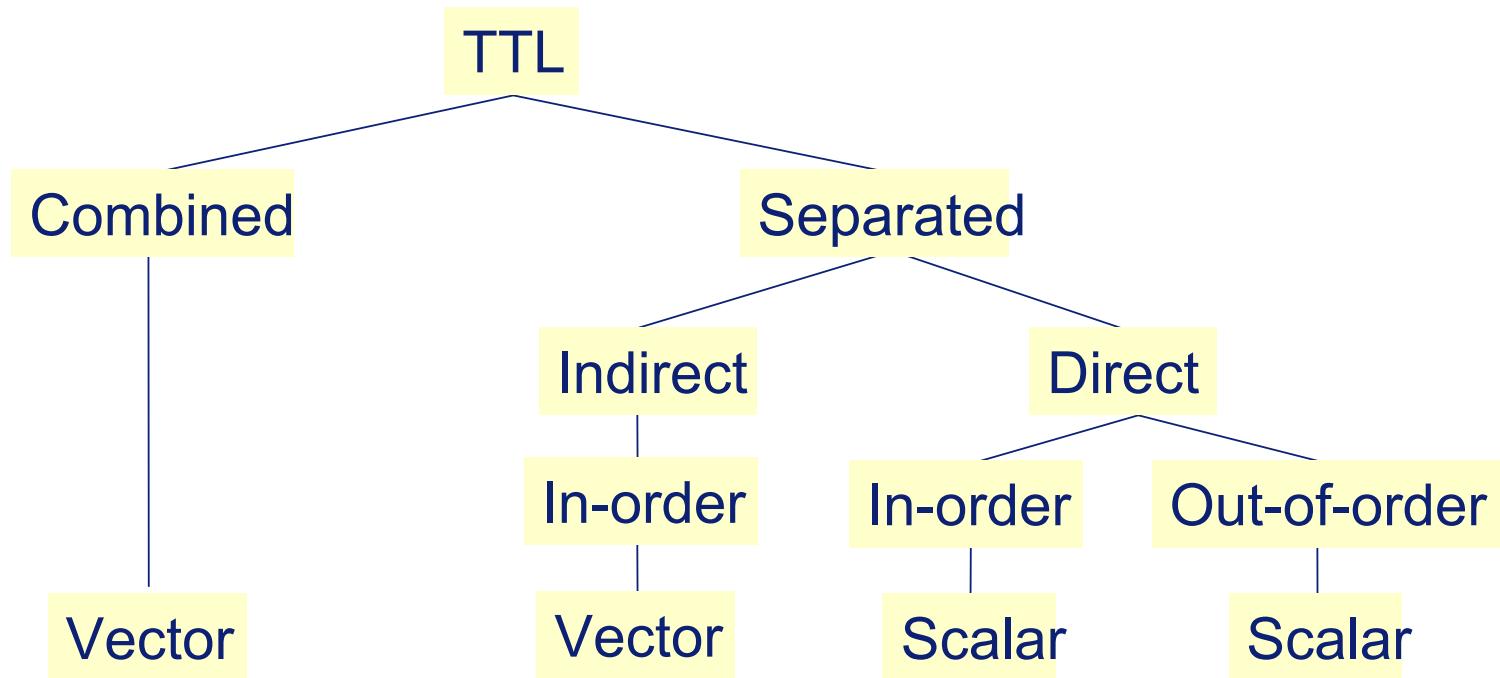
- + Coarse grain synchronization with fine grain data transfer
- + Out-of-order data accesses for acquired token(s)
- + Load only part of token from channel
- + Direct data accesses
 - Efficient data transfers
- Less abstract than CB / RB / RN
 - Exposes memory addresses
 - Makes tasks less reusable
- No vector operations
 - Would complicate interface / expose channel implementation

Interface Types DBO and DNO

Producer side

- `acquireRoom(port, &token)` (DBO)
 - `tryAcquireRoom(port, &token)` (DNO)
 - Acquire empty token, blocking (DBO) / non-blocking (DNO)
 - `token->field = value;`
 - Assign value to (part of) token
 - `releaseData(port, &token)`
 - Release token as the next full token
-
- + Out-of-order release supports efficient use of memory
 - More complex implementation of the channel

TTL Interface Types



CB

RB / RN

DBI / DNI

DBO / DNO

Use of TTL Interface Types

- Select appropriate interface types for platform and targeted applications
 - Based on platform architecture and characteristics of applications
- Interface types offer different communication styles
 - Allow designer to trade “ease of design” for “efficiency of implementation”
- Automated communication refinement
 - Mapping technology can automate design optimization
 - TTL → TTL transformations on task code
- Why single TTL for multiple platforms ?
 - Share TTL-based design technology
 - Reuse IP modules across platforms

TTL Multi-Tasking Interface

TTL offers three task types:

1. Process

- Own thread of execution
- No explicit interaction with scheduler
- Implicit task switching and state saving

2. Co-routine

- Explicit interaction with scheduler via **suspend()** function
- Implicit state saving

3. Actor

- Fire-exit tasks that return to scheduler
- State saving to be performed by task

TTL APIs and Implementations

- TTL interface is available as:
 - C++ API
 - C API
 - Hardware interface
- Generic run-time environment
 - Functional modeling and verification of TTL application models in C++ / C
- Platform implementations
 - Sea-of-DSP
 - Smart Camera
 - Cake / Wasabi

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Problem

How to efficiently program applications on platforms using the TTL interface?

- Efficient = cost + performance + effort
- The cost and performance of TTL interface functions varies on different platforms
- The cost and performance of different TTL interface types varies on one platform

Example IQ→IZZ Using CB

```

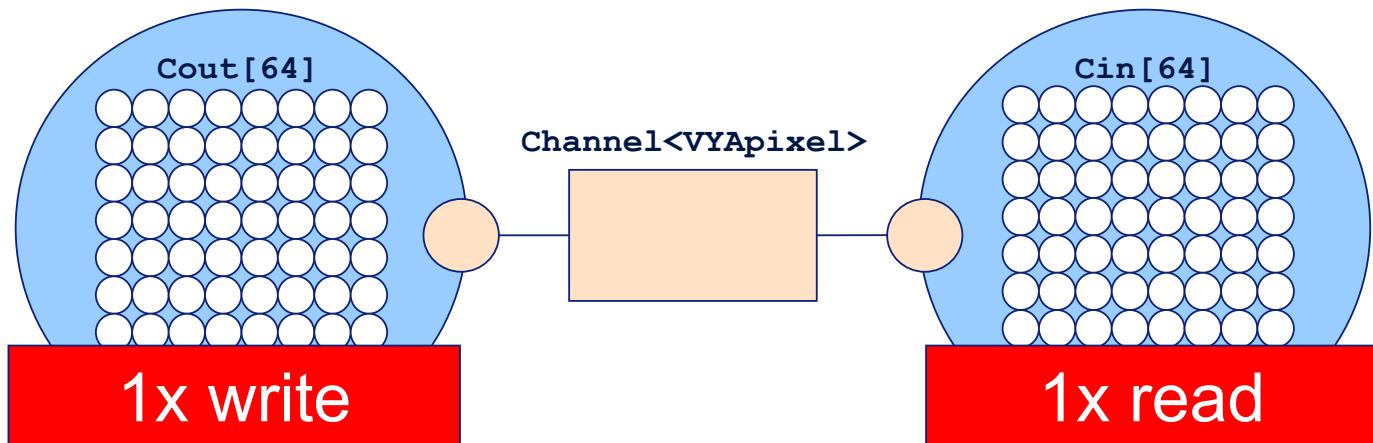
01 void IQ::main()
02   while (true)
03     for(int j=0; j<vi; j++)
04       for(int k=0; k<hi; k++)
05         VYApixel Cout[64];
06         for(int l=0; l<64; l++)
07           VYApixel Cin;
08           read(CinP, Cin);
09           Cout[l] = QT[t][l]*Cin;
10           write(CoutP, Cout, 64);

```

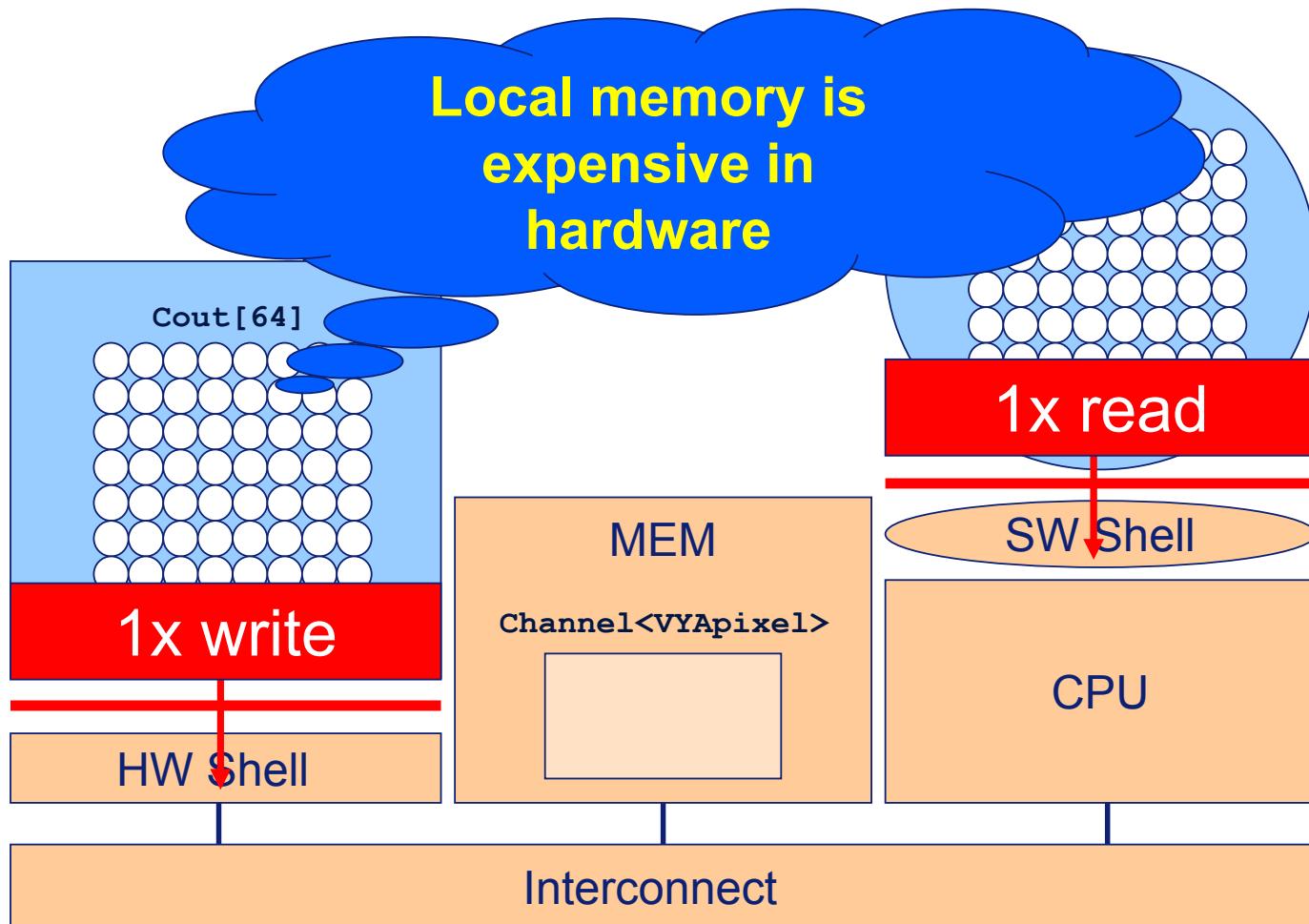
```

01 void IZZ::main()
02   while (true)
03     VYApixel Cin[64];
04     VYApixel Cout[64];
05     read(CinP, Cin, 64);
06     for(int i=0; i<64; i++)
07       Cout[zigzag[i]] = Cin[i];
08     write(CoutP, Cout, 64);

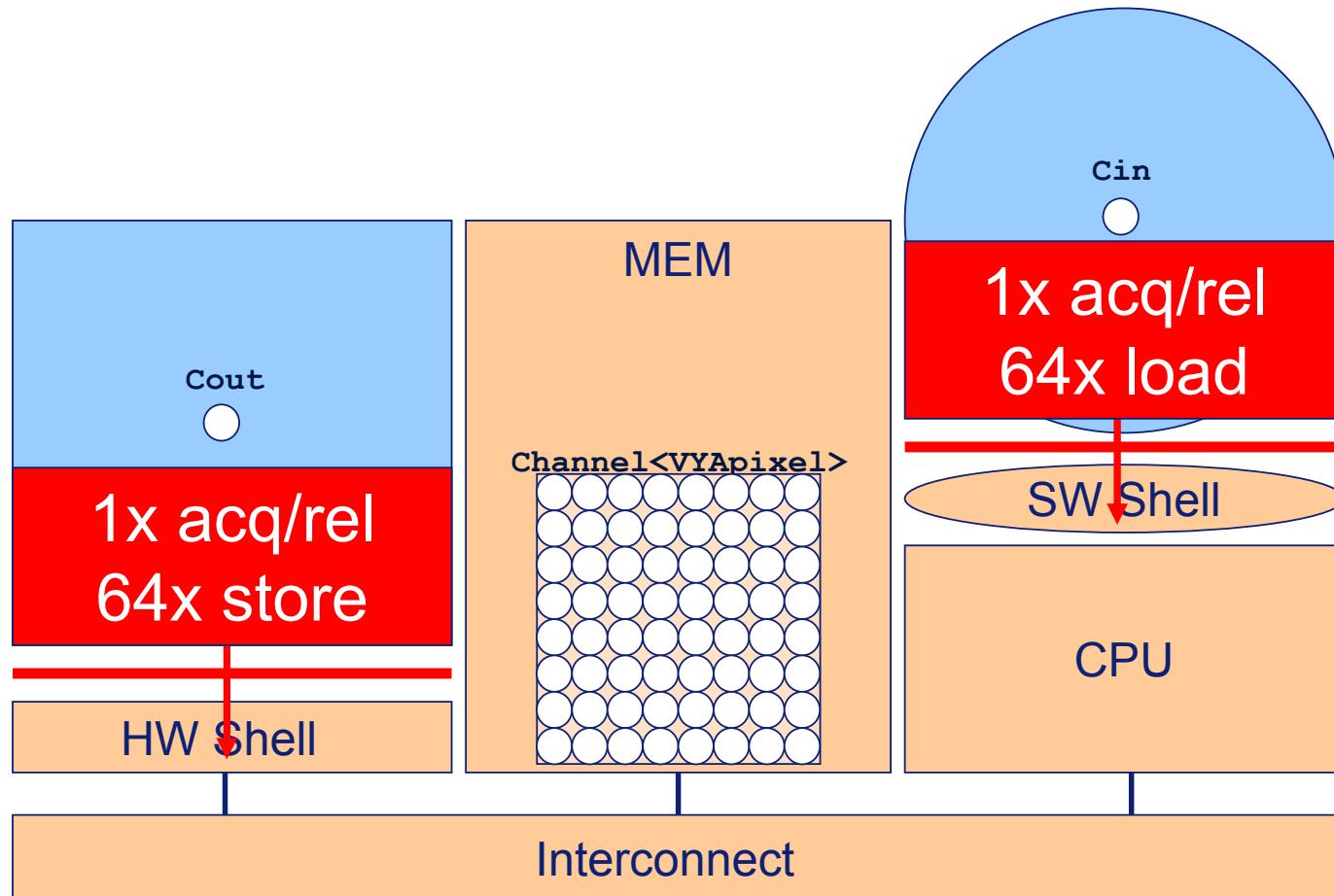
```



Efficiency of IQ→IZZ Using CB (HW)



Transform IQ→IZZ Using RB (1)



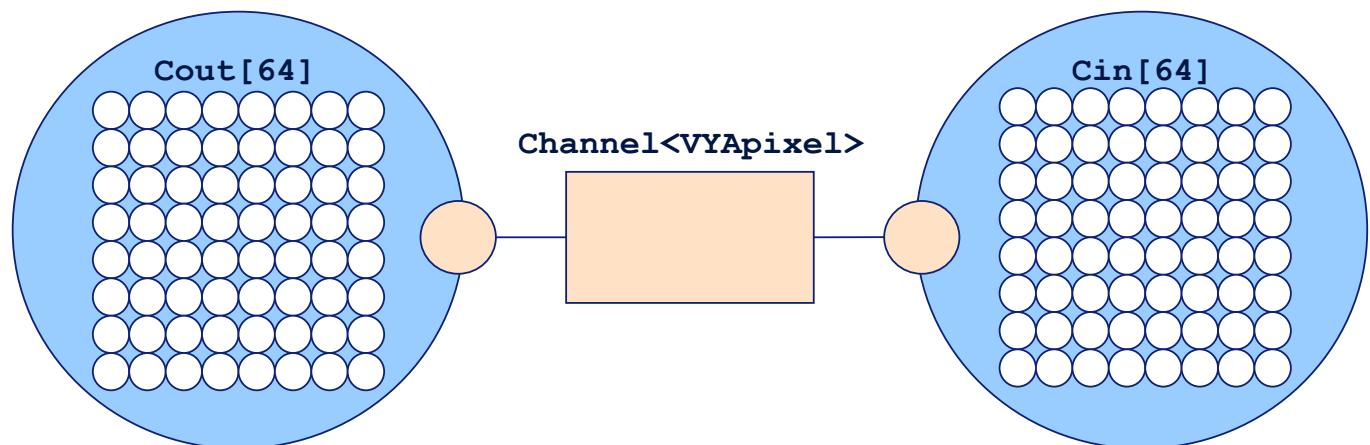
Transform IQ→IZZ Using RB (2)

```
01 void IQ::main()
02     while (true)
03         for(int j=0; j<vi; j++)
04             for(int k=0; k<hi; k++)
05                 VYApixel Cout[64];
06                 for(int l=0; l<64; l++)
07                     VYApixel Cin;
08                     read(CinP, Cin);
09                     Cout[l] = QT[t][l]*Cin;
10                     write(CoutP, Cout, 64);
```

- remove declaration
- acquire 64 tokens

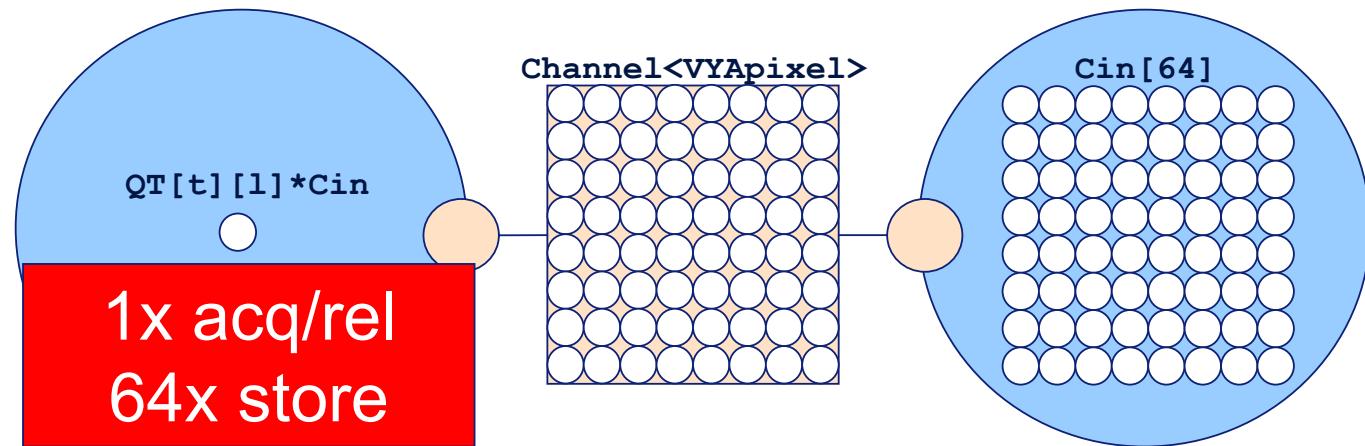
- add store operation

- release 64 tokens



Transform IQ→IZZ Using RB (3)

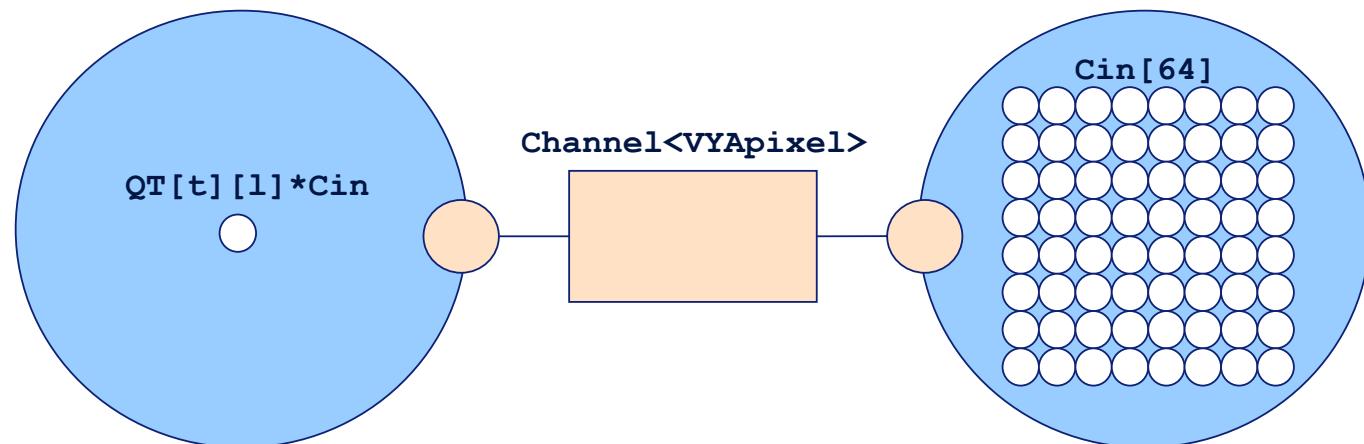
```
01 void IQ::main()
02 while (true)
03   for(int j=0; j<vi; j++)
04     for(int k=0; k<hi; k++)
05       reAcquireRoom(CoutP, 64);
06       for(int l=0; l<64; l++)
07         VYApixel Cin;
08         read(CinP, Cin);
09         store(CoutP, l, QT[t][l]*Cin);
10         releaseData(CoutP, 64);
```



Transform IQ→IZZ Using RB (4)

- remove declaration
- acquire 64 tokens
- load value of **Cin[i]**
- release 64 tokens

```
01 void IZZ::main()
02     while (true)
03         VYApixel Cin[64];
04         VYApixel Cout[64];
05         read(CinP, Cin, 64);
06         for(int i=0; i<64; i++)
07             Cout[zigzag[i]] = Cin[i];
08         write(CoutP, Cout, 64);
```



Transform IQ→IZZ Using RB (5)

```

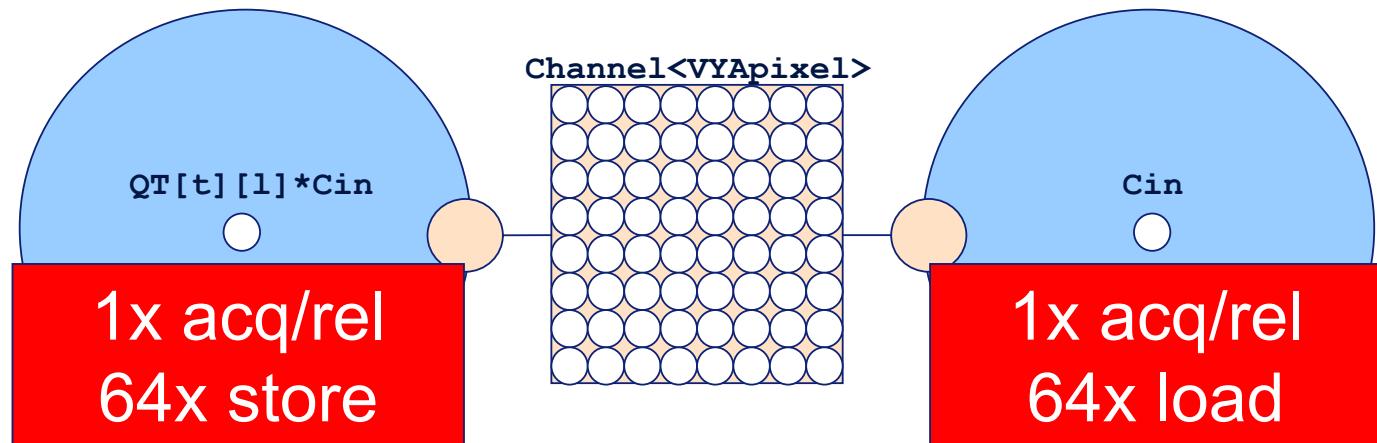
01 void IQ::main()
02 while (true)
03 for(int j=0; j<vi; j++)
04 for(int k=0; k<hi; k++)
05 reAcquireRoom(CoutP, 64);
06 for(int l=0; l<64; l++)
07 VYApixel Cin;
08 read(CinP, Cin);
09 store(CoutP, l, QT[t][l]*Cin);
10 releaseData(CoutP, 64);

```

```

01 void IZZ::main()
02 while (true)
03 VYApixel Cout[64];
04 reAcquireData(CinP, 64);
05 for(int i=0; i<64; i++)
06 VYApixel Cin;
07 load(CinP, i, Cin);
08 Cout[zigzag[i]] = Cin;
09 write(CoutP, Cout, 64);
10 releaseRoom(CinP, 64);

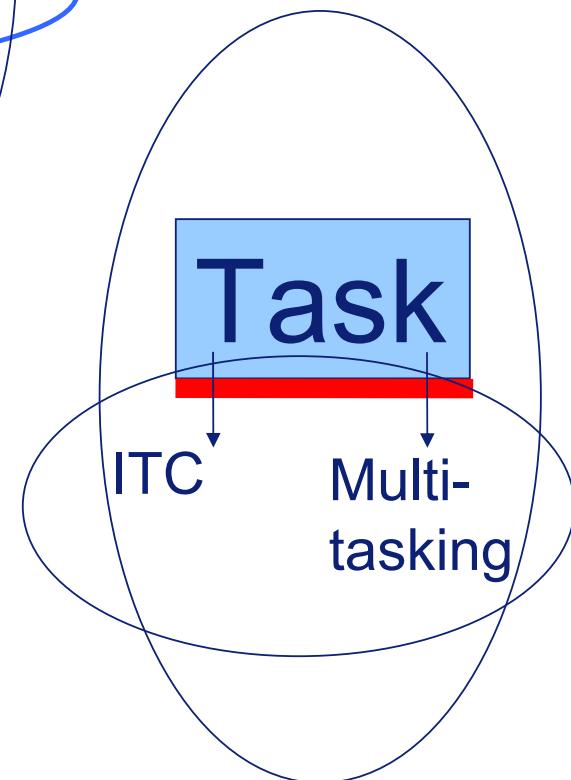
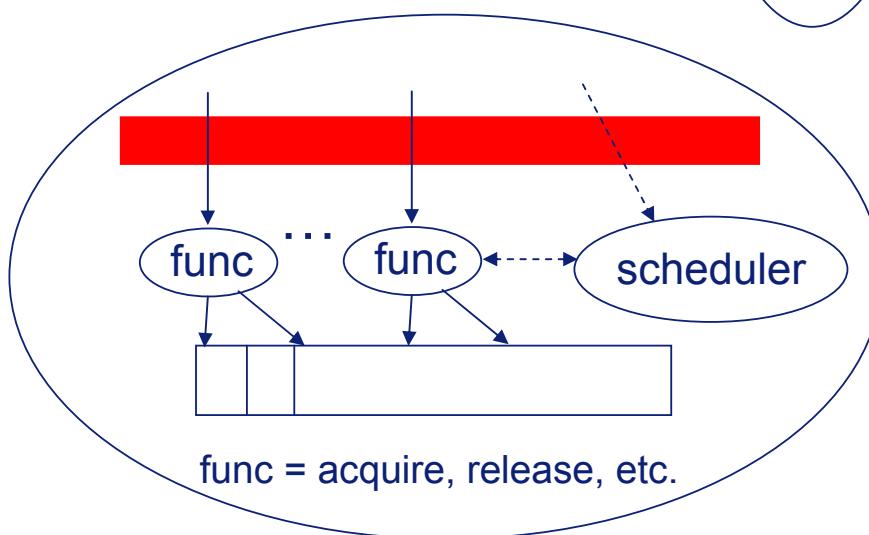
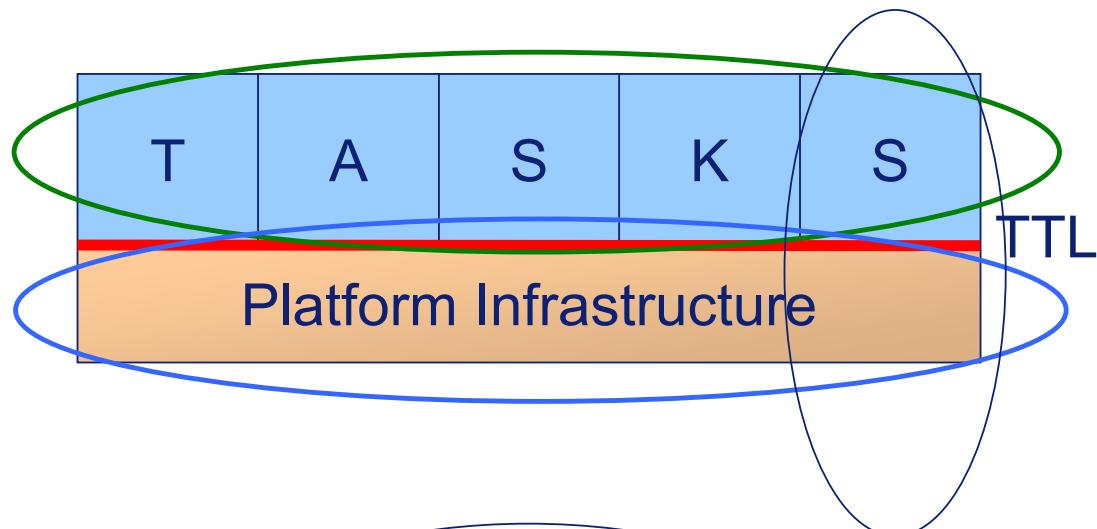
```



Outline

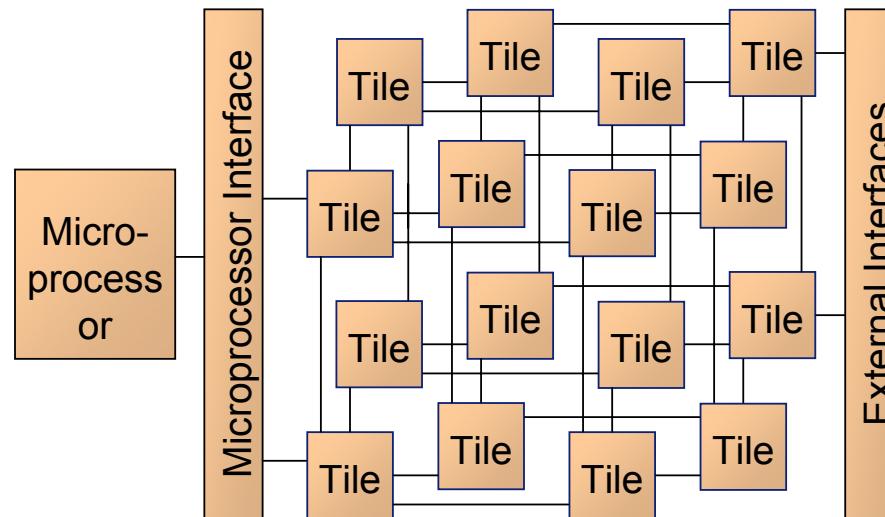
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Implementation of TTL

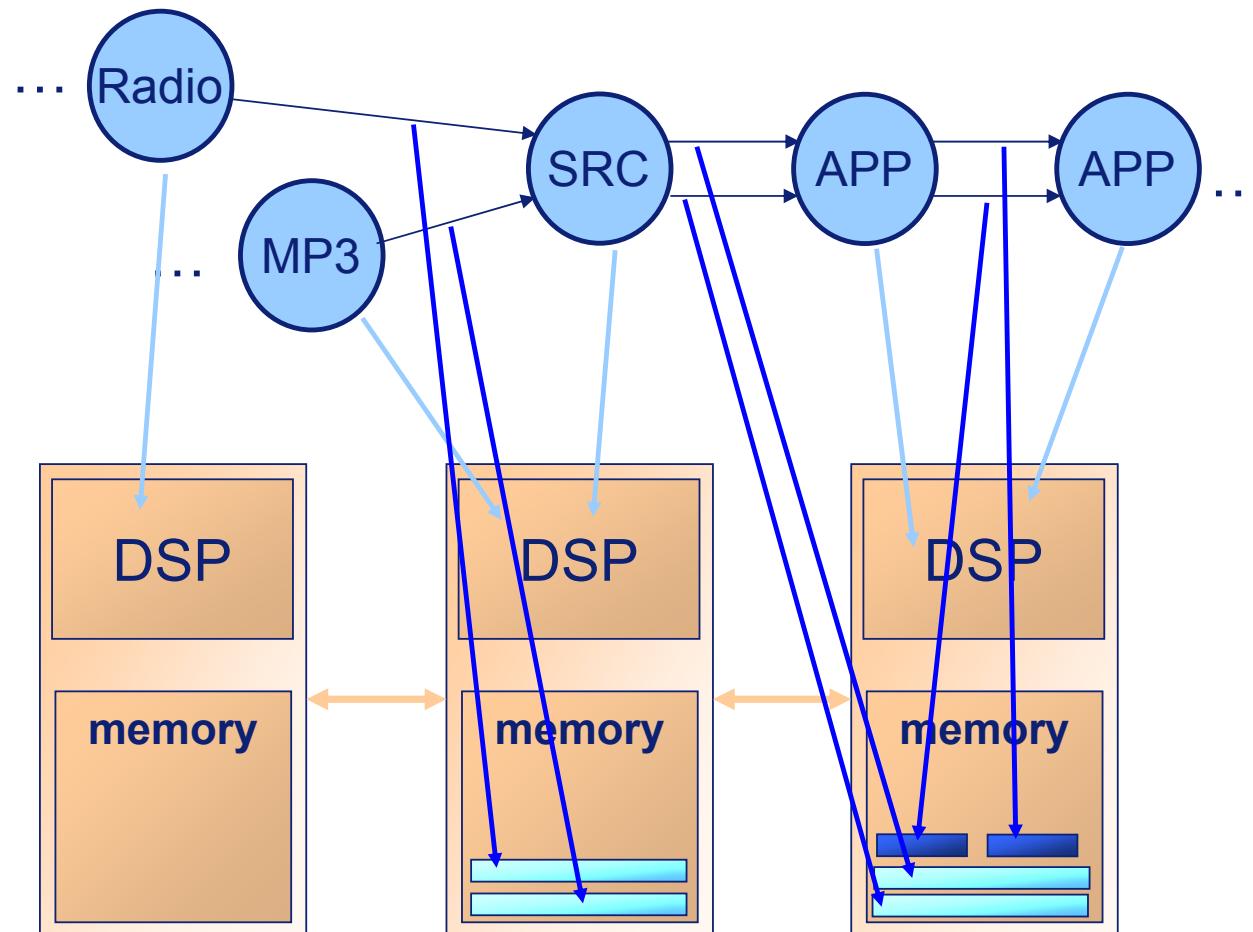


Sea of DSP Architecture

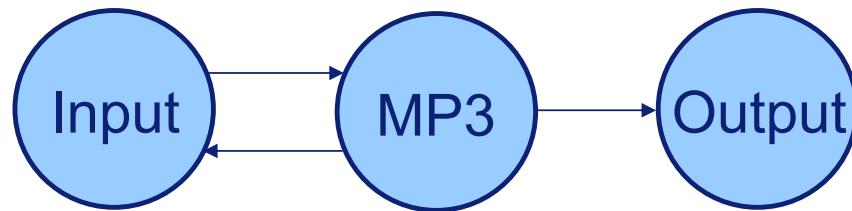
- Scalable and power-efficient
- Tile = DSP + Memory + DMA + inter-tile communication
- Any number of tiles is possible
- Memory mapped write-only inter-tile communication
- No general shared memory
- No OS on tiles



Mapping on Sea of DSP

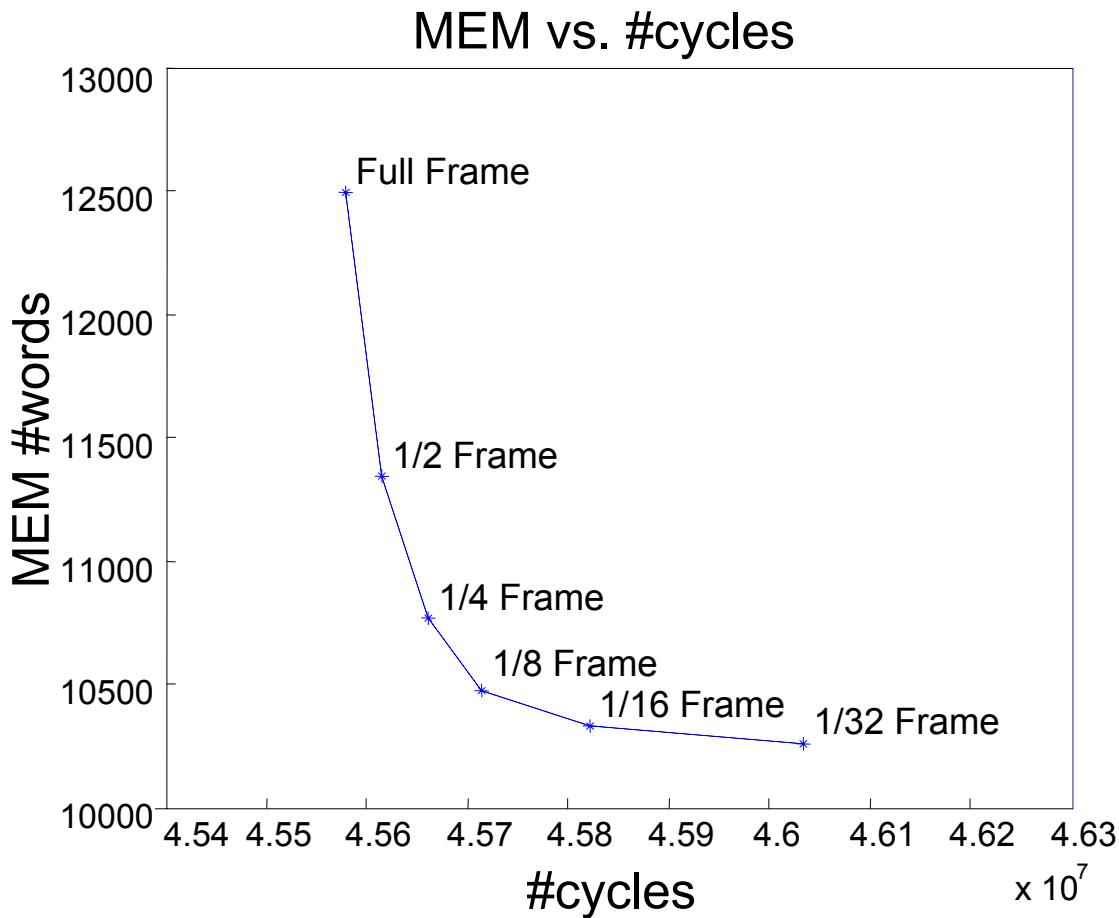


Results for Different Interface Types



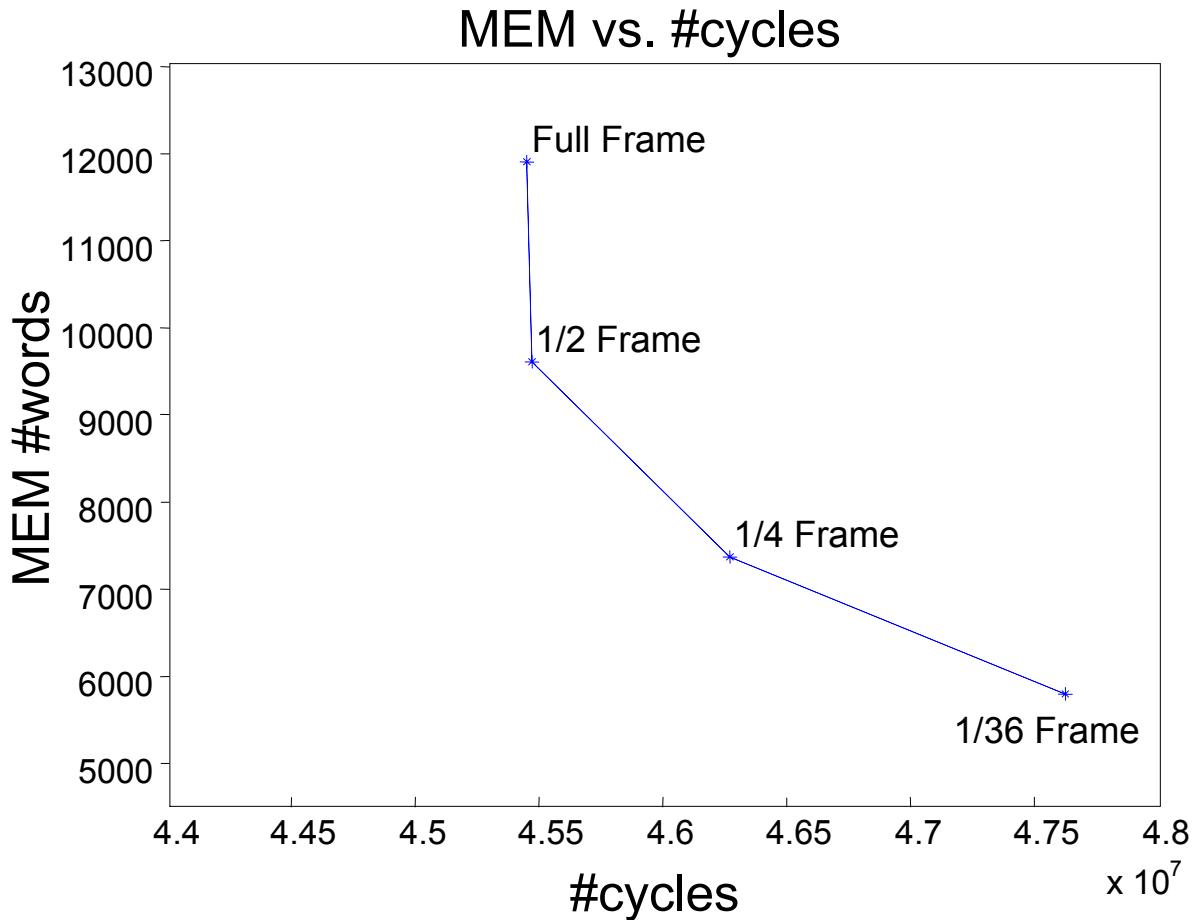
TTL IF Type	#Cycles	Part in TTL	#Memory words
CB	45579603	2.9%	12493
RB	45551243	2.8%	12494
RN	45505950	2.2%	12365
DBI	45152454	1.1%	9162
DNI	45108086	0.5%	9041

Results for Varying Channel Size (CB)



- Task code not modified
- Possible with CB
- Only channel buffer has been reduced in size

Results: Sub-frame Decoding (RN)



- Channel buffer and private buffers are reduced in size
- Task code must be modified
- Possible with all interface types

Smart Cameras Application Areas

Surveillance



Consumer



Automotive

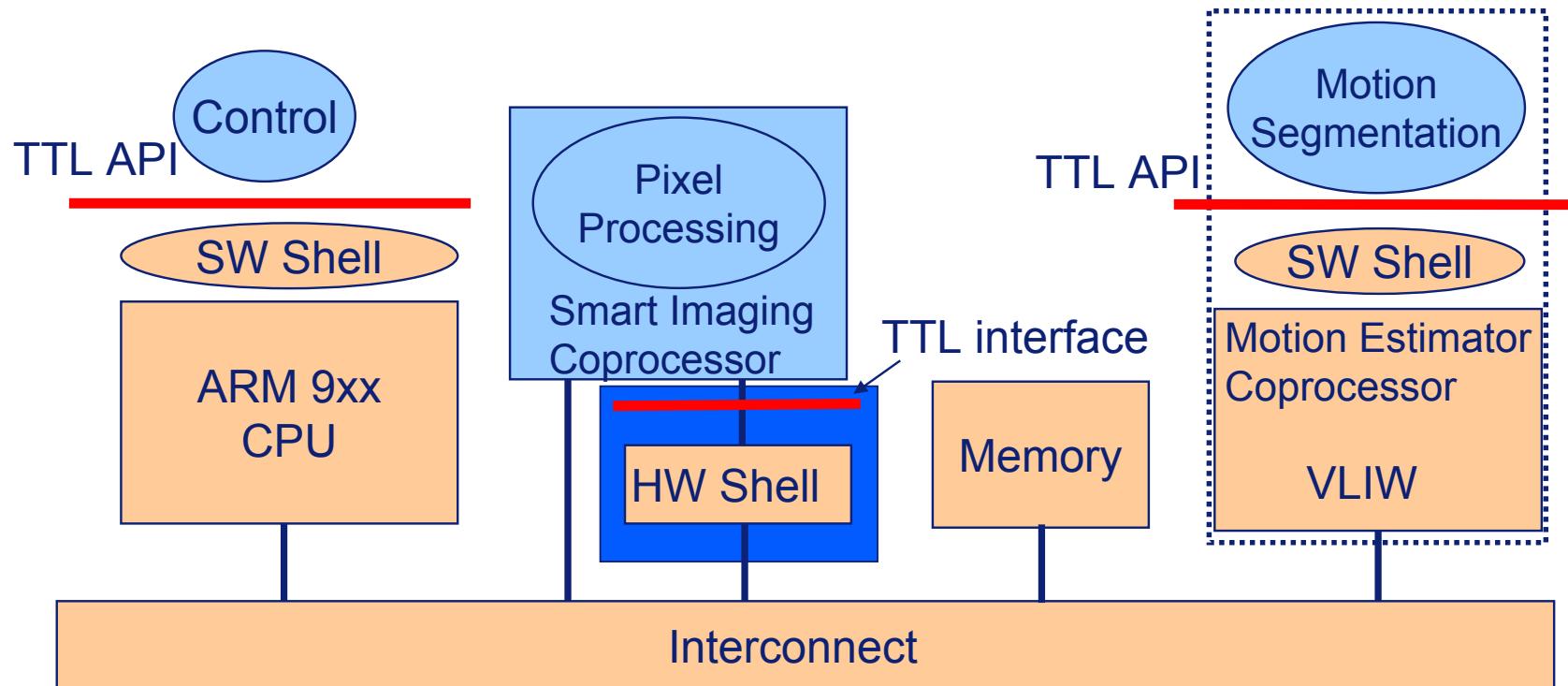


Mobile



EC funded CAMELLIA project (IST-34410)

Architecture of Smart Imaging Core

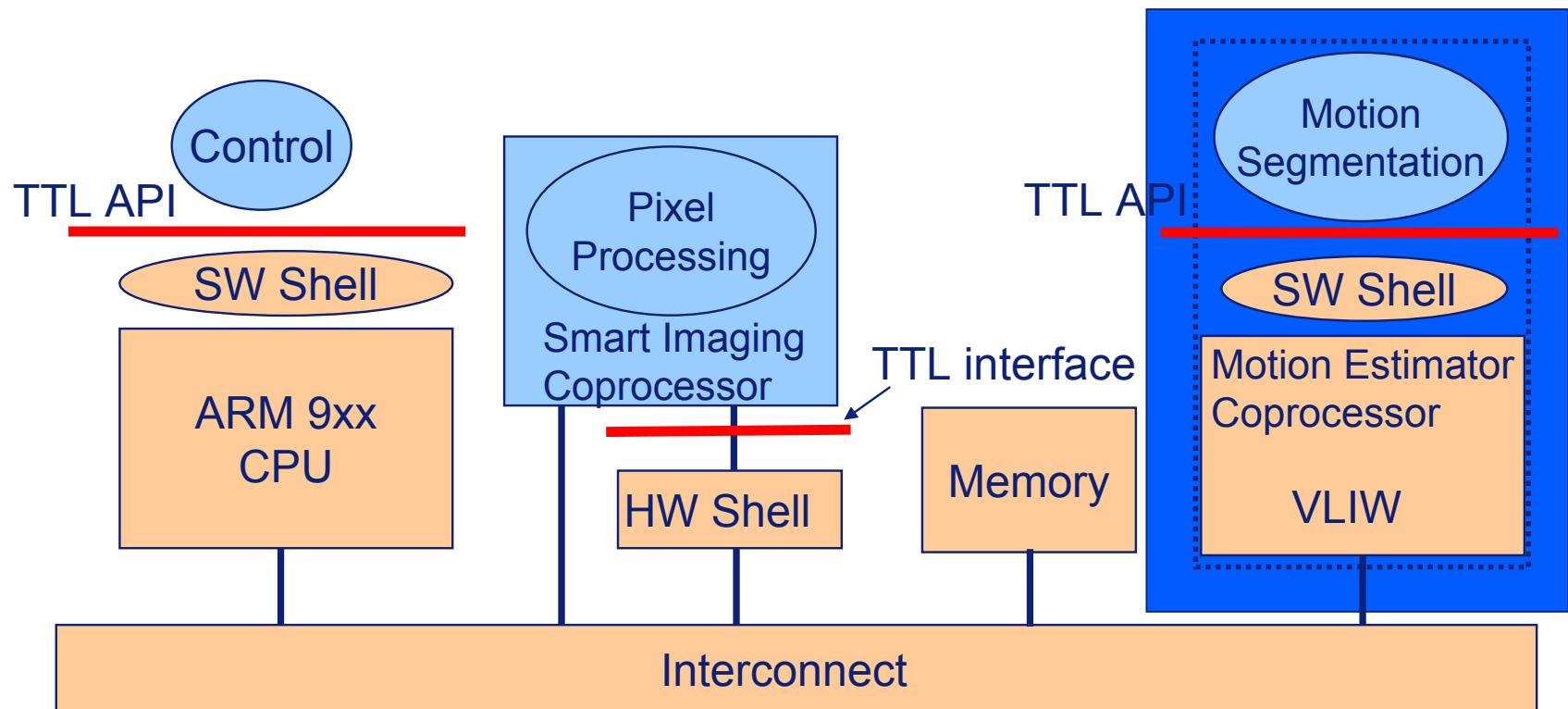


- Enable efficient software – hardware communication
- Make all processors “self-synchronizing”

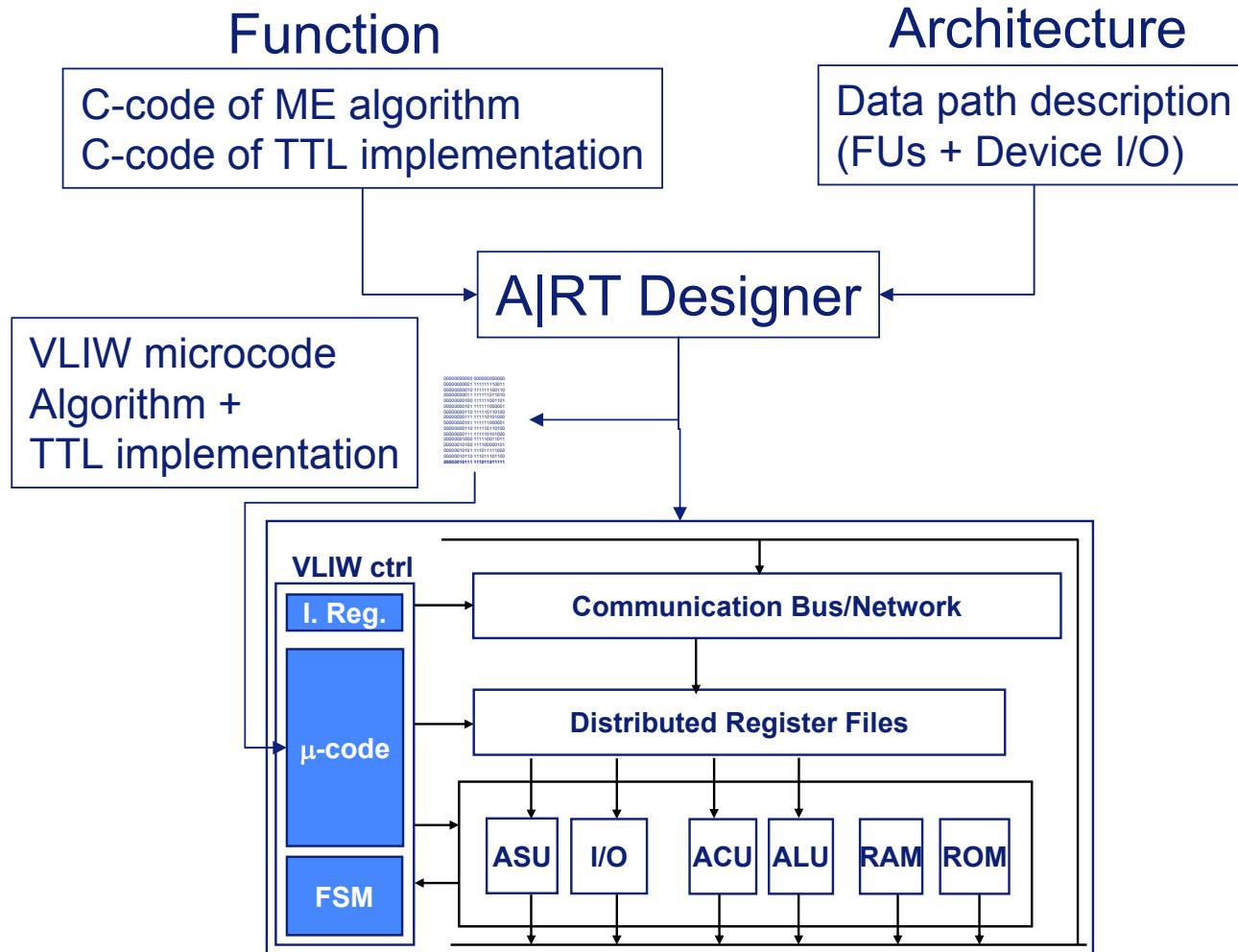
TTL shell performance

- HW Shell (channel administration local)
 - reAcquireRoom/Data 5 cycles
 - releaseRoom/Data 7 cycles
 - load 5 + 2n cycles
 - store 5 + n cycles

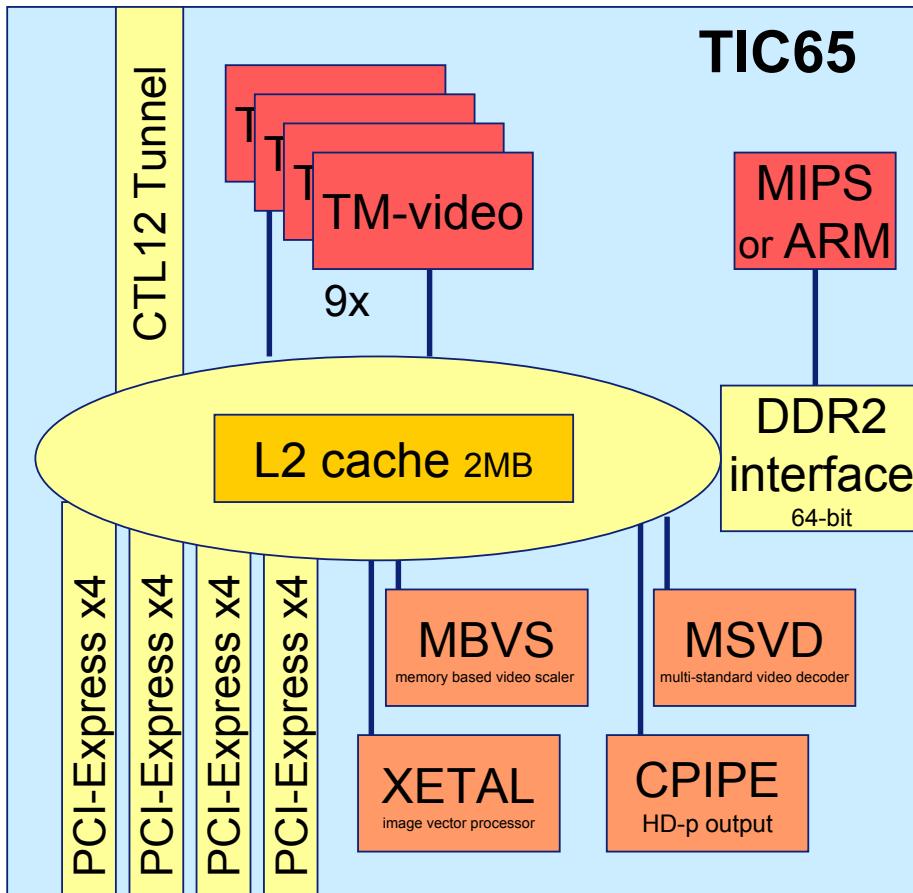
Architecture of Smart Imaging Core



TTL Implementation for ME



Cake / Wasabi



- Hybrid multiprocessor with homogeneous bias
- First silicon early 2006

TTL Implementation on Cake / Wasabi

	MIPS	Trimedia
Cycles per sync operation (TTL on top of TRT run-time system)	20 (MIPS - MIPS)	20 (TM - TM)
Code size TTL (CB + DBI)	5 kB	14 kB
Lines of code TTL (CB + DBI)	773	773
Code size TTL (all IF types)	12 kB	29 kB
Lines of code TTL (all IF types)	1529	1529

Task-Level Interface Standardization

Industry-wide standardization needed

- Reuse of function-specific hardware and software IP
 - Enable eco-system of IP providers
- EDA for system-level design
 - Support development of function-specific IP
 - Support integration of IP

Conclusion

TTL supports structured and efficient design and integration of hardware and software tasks in MPSoCs

- High-level interface for ease of programming
 - Decreases design effort for task programmer
 - Facilitates reuse and integration of IP
 - Provides implementation freedom for platform infrastructure
- Enabler for automated mapping
 - Automated transformations support design optimizations
 - Closes gap between specification and implementation
 - Decreases design effort for system integrator
- Efficient implementation on range of platforms
 - Different architectures
 - In hardware and software
- Need for standardization

