Mapping biochemical applications onto microfluidic-based biochips

Jan Madsen with Elena Maftei, Paul Pop Embedded Systems Engineering MPSoC Symposium, August 4, 2009

DTU Informatics

Department of Informatics and Mathematical Modeling

Outline

- Motivation & relation to MPSoC
- Biochip architectures
- The mapping problem

Motivation

- Biotech
 - DNA analysis
- Medicine
 - Clinical diagnosis
 - Therapeutics
- Ecology
 - Monitoring the quality of air/water/food
- Pharmacy
 - Screening
 - Synthesis of new drugs

Motivation



- Automation
- Integration
- Miniaturization

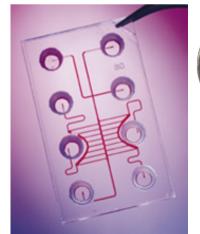




Miniaturization

Microfluidics

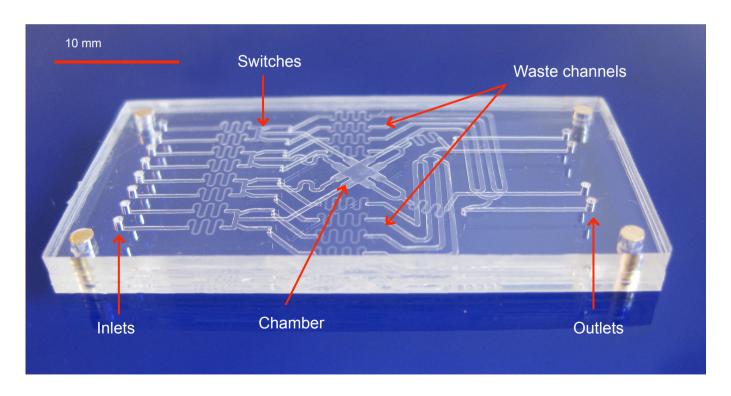




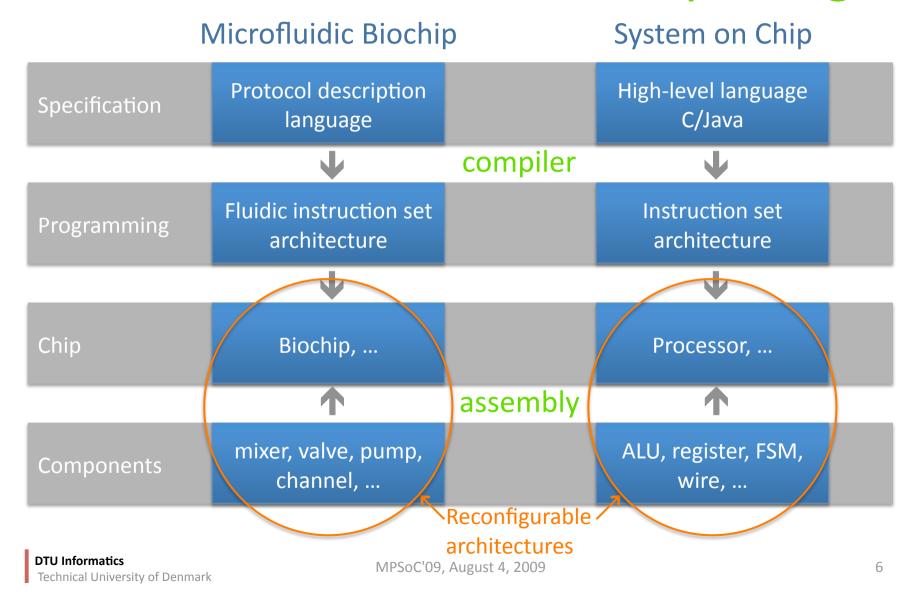


Microfluidic biochip?

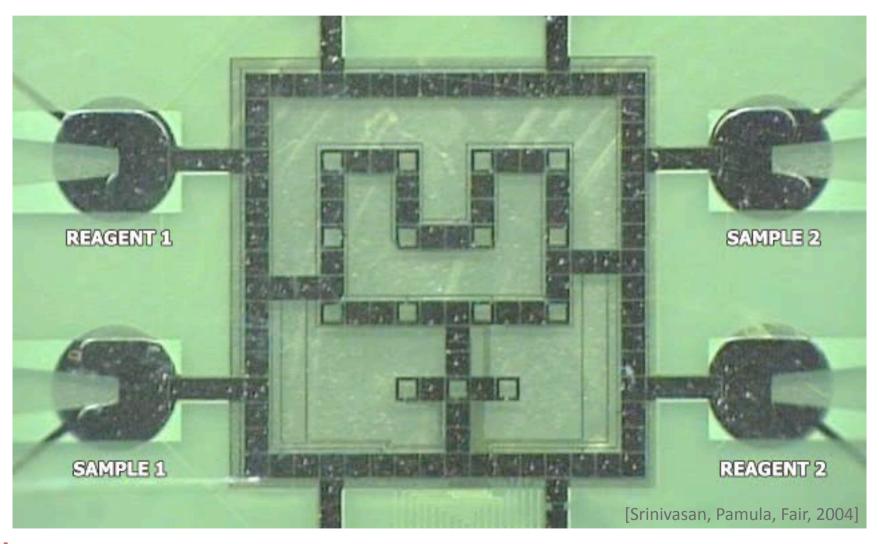
 Manipulations of continuous liquid through fabricated micro-channels



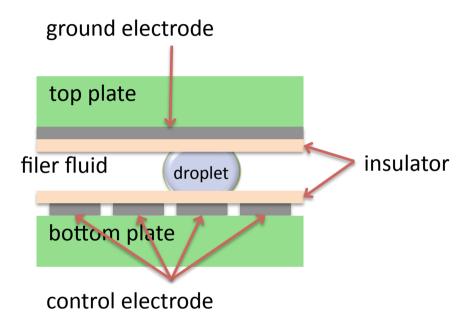
Biochip design

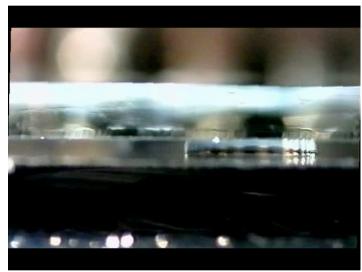


Digital microfluidic biochip



Digital microfluidic biochip





Speed: 12-25 cm/s

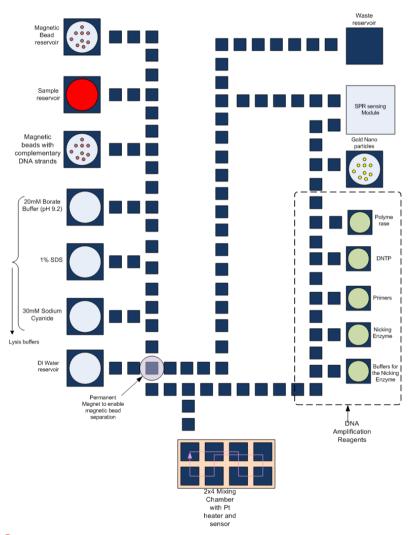
Size of electrode: 0.15 cm

Cell-to-cell transport: ~0.01 s

Biochip architecture?

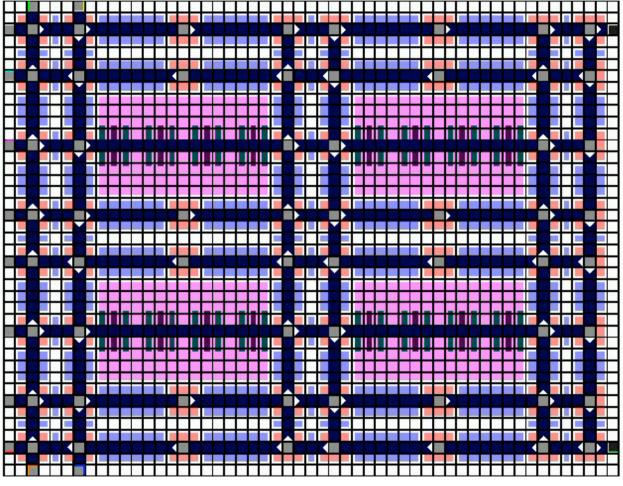
- Application specific architecture
 - Spatial and temporal assignment done at designtime
- General purpose architecture
 - Spatial assignment done at design-time
 - Temporal assignment done at run-time
- Reconfigurable architecture
 - Spatial and temporal assignment done at run-time

Application specific biochip



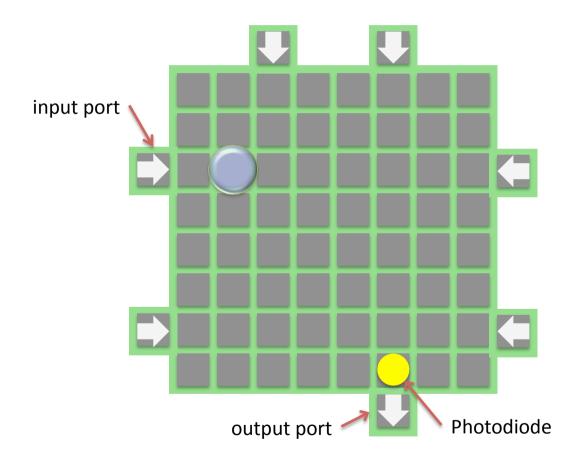
- Biochip for malaria detection
- Operation:
 - Infected cell isolation
 - Cell Lysis
 - DNA extraction
 - DNA amplification using PCR
 - Optical detection using SPR

General purpose biochip



[Griffith, Akella, 2005]

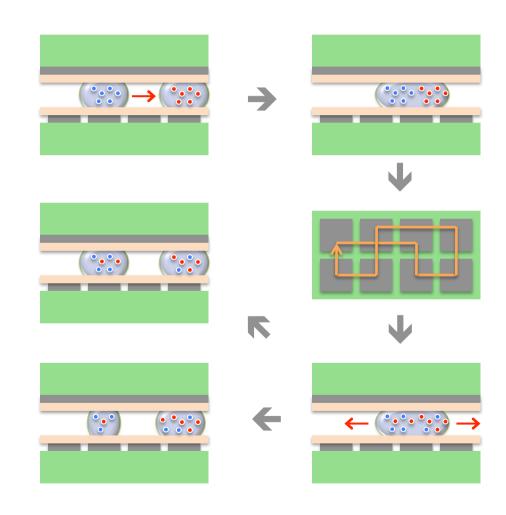
Reconfigurable biochip



Biochemical operations

- Transport
- Merging
- Mixing
- Splitting
- Diluting
- Detection

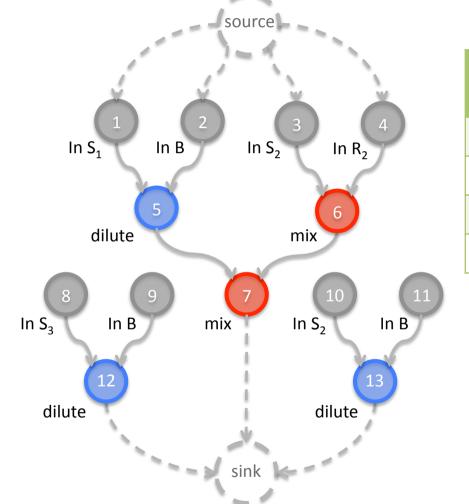
•



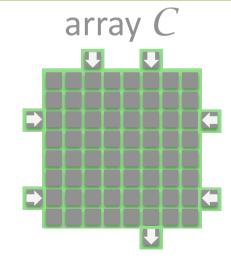
application G

Biochemical application





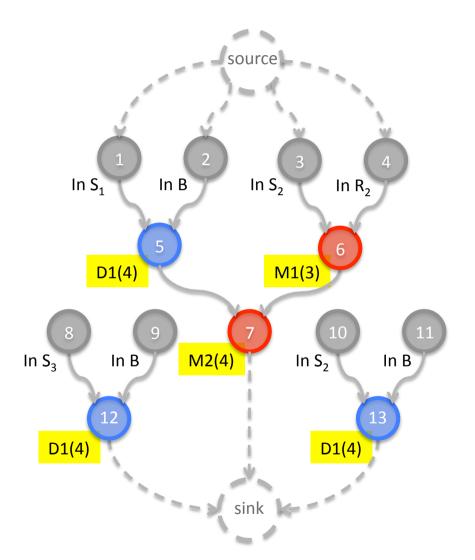
module	Operation	Area (cells)	Time (sec)
M1	Mixing	2x4	3
M2	Mixing	2x2	4
D1	Dilution	2x4	4
D2	Dilution	2x2	5

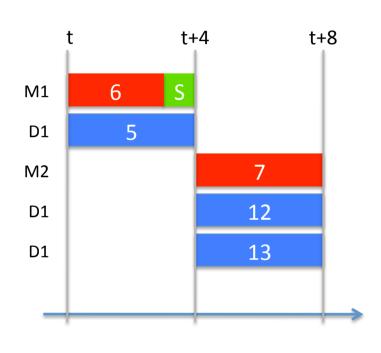


Mapping biochemical applications onto microfluidic biochips

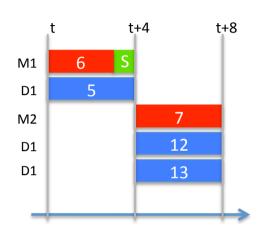
- Allocation \mathcal{A}
 - Determine modules \mathcal{M}_k from library \mathcal{L}
- ullet Binding ${\mathcal B}$
 - Assign each operation O_i to a module \mathcal{M}_k
- Schedule S
 - Determine start time t_i^{start} of each operation O_i
- Placement ${\mathcal P}$
 - Place modules on the $m \times n$ array
- Synthesis Ψ
 - Given $<\!\!\mathcal{G},~\mathcal{C},~\mathcal{L}\!\!>$, find $~\Psi=<\!\!\mathcal{A},\mathcal{B},\!\!S,\!\!P\!\!>$ which minimize the schedule length $\delta_{\mathcal{G}}$

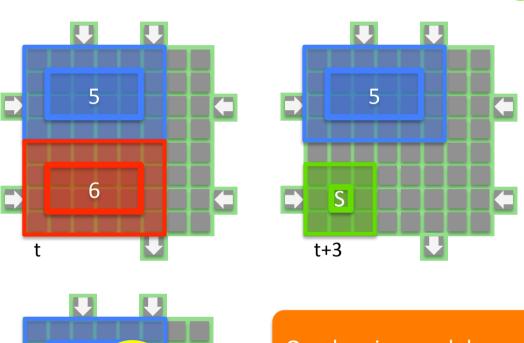
Scheduling

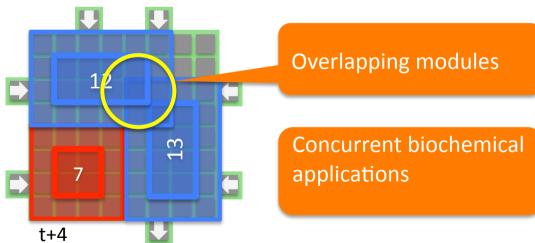




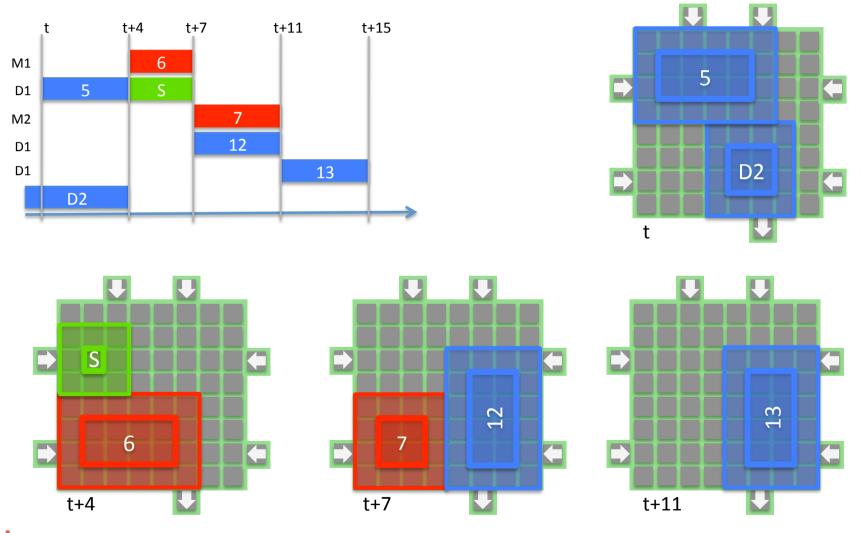
Scheduling



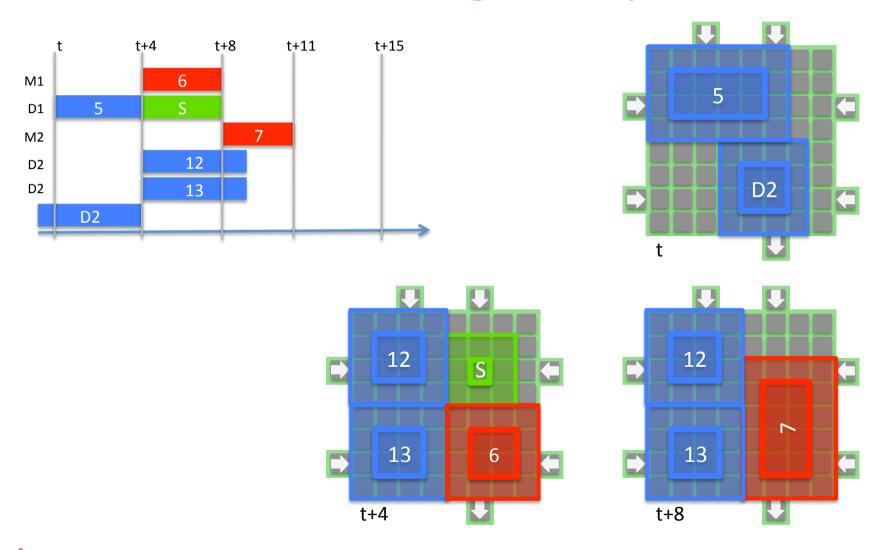




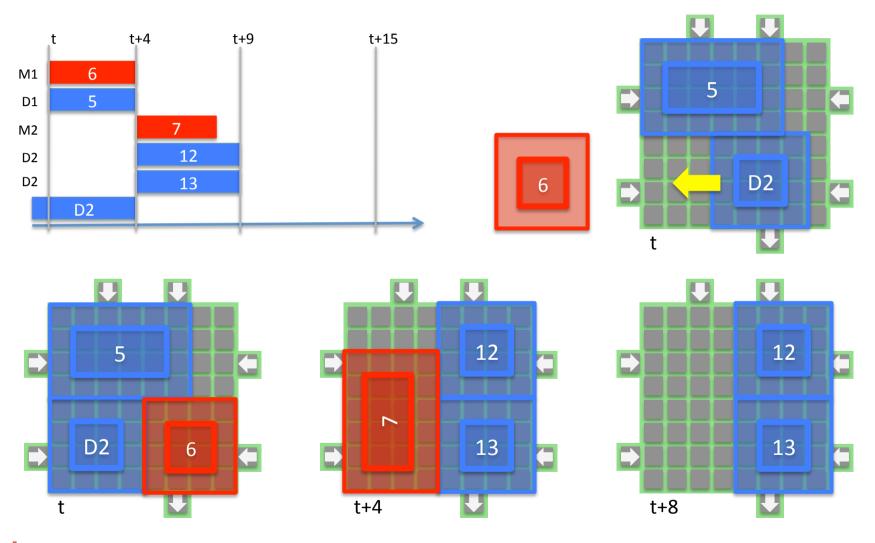
Scheduling with placement



Scheduling with placement



Scheduling with dynamic placement



Summary

- Biochip architectures
- Synthesis of digital microfluidic biochips
- Run-time resource management leads to considerable better results
- Integration with MPSoC to allow online monitoring and feedback
- Conditional biochemical operations

Acknowledgements

Elena Maftei & Paul Pop, DTU Informatics

Krish Chakrabarty, Duke University

The ProCell project

THANK YOU FOR YOUR ATTENTION