

MpSoC for Safety Critical Applications – from Multicore to Manycore

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Motivation

- MpSoCs are an efficient platform for systems integration
- due to physical resource sharing, safety critical systems integration becomes more challenging



ESP

MpSoC for Critical Applications



Mixed Critical MpSoC Certification/Qualification

- resulting multi-core ECU subject to highest safety standard involved
- high certification (or qualification, resp.) cost
 - must cover ALL applications and hardware
 - often qualified data of non-critical application not available
 - re-certification for any non-critical application update required
- alternative: isolation of different criticalities
 - requires certification/qualification of core components that control resources

- approve core components that control the resources used for any of the critical applications
 - basic software
 - communication
 - shared resources used for critical applications



Safety and Time Criticality

- many safety critical systems are also time critical



- virtualization/isolation used for functional isolation
- virtualization is not always sufficient for safety critical systems
 - competing accesses to shared resources requires temporal isolation/compensation



- dependencies can be used for "performance attack"

- uses memory arbitration
- · works even when timing is less critical
- approach: assign budgets and use formal analysis

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"Performance Attack" via Update



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- extend isolation to manycore systems
 - include NoC in function and performance isolation
- challenge:
 - guarantee performance for critical applications
 - minimize impact for non critical applications

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Considering the Network-on-Chip

- routers forward individual packets
 - shared by everyone: Lots of interference
 - arbitration on contention
- use QoS techniques to guarantee service to individual traffic streams
- existing QoS mechanisms serve guarantees first! best-effort traffic is "second-class citizen"
 - static allocation of time slots (e.g. Aethereal)
 - dynamic scheduling of VCs + priorities (e.g. MANGO, QNoC)
- not optimal for mixed-critical applications
 - best-effort is an important traffic class, but often *latency-sensitive*
 - BE traffic suffers from high latency
 - RT traffic has no benefit from reduced latency (deadline driven)



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Mixed Criticality: Best-effort and Real-Time Streaming



Solution: "Back Suction"

- prioritize RT traffic based on downstream buffer occupancy
- let sink control the priorization of RT traffic by creating a "suction" that pulls data towards the sink
- suction propagates backwards towards source
 - Threshold module at every virtual channel buffer monitors occupancy
 - limit rate (to guaranteed rate) at which sink may assert back suction



- mechanism provides throughput guarantees to individual real-time streams
 - proven by formal analysis
- BE latency is improved significantly
 - application runtime improves accordingly



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Functional Isolation and System Virtualization

- compose manycore system from tiles
 - existing IP components,
 e.g. LEON3-Sparc processor
 - individually qualified/certified or pre-certified
- network interface isolates tiles
 - provide controlled access to the rest of the system
 - transparent mapping of memory and peripherals
 - translate tile-local address space to system-wide addresses
- configuration unit
 - controls network interface
 - configured via central, trusted resource manager
 - monitors behavior of tiles to detect malfunctions



Manycore Research Platform

- European project RECOMP
 - reduce certification costs for MpSoC
 - TUBS: manycore research platform for mixed-critical applications
- FPGA based prototype recomp
 - based on SPARC LEON3 processor tiles
 - NoC with back suction
 - safety-functions in Network-Interface
 - system virtualization
 - power- and performance-monitoring
- German project ASTEROID (DFG Research Priority Program)
 - introduce platform redundancy for increased reliability requirements
 - redundancy in space and time (retransmission, checkpointing, rollback)
 - targeted to application and OS safety requirements
 - collaboration w. TU Dresden (L4 microkernel)

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System

Controller

Conclusion

- MpSoCs are used for safety critical applications
- mixed criticality is a challenge and a serious certification/qualification and maintenance cost driver
- research has started to look into manycore systems for mixed critical applications – many new challenges
- several European and national projects targeting MpSoC for mixed criticality - first results presented

Thank you!



RECOMP

- www.recomp-project.eu
- TUBS part www.ida.ing.tu-bs.de/en/research/projects/recomp
- for the challenge of MpSoC performance dependencies see
 - Mircea Negrean, Simon Schliecker, Rolf Ernst. "Response-Time Analysis of Arbitrarily Activated Tasks in Multiprocessor Systems with Shared Resources." In *Proc. of Design, Automation, and Test in Europe (DATE)*, Nice, France, April 2009.

for the manycore research platform

- Jonas Diemer and Rolf Ernst, "Back Suction: Service Guarantees for Latency-Sensitive On-Chip Networks," in Proceedings of the 4th ACM/IEEE International Symposium on Networkson-Chip (NOCS'10), May 2010
- Jonas Diemer, Rolf Ernst, und Michael Kauschke, "Efficient Throughput-Guarantees for Latency-Sensitive Networks-On-Chip," in Proceedings of the Asia and South Pacific Design Automation Conference (ASP-DAC 2010), January 2010

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