

# Control System for Large-Scale Sensor Network

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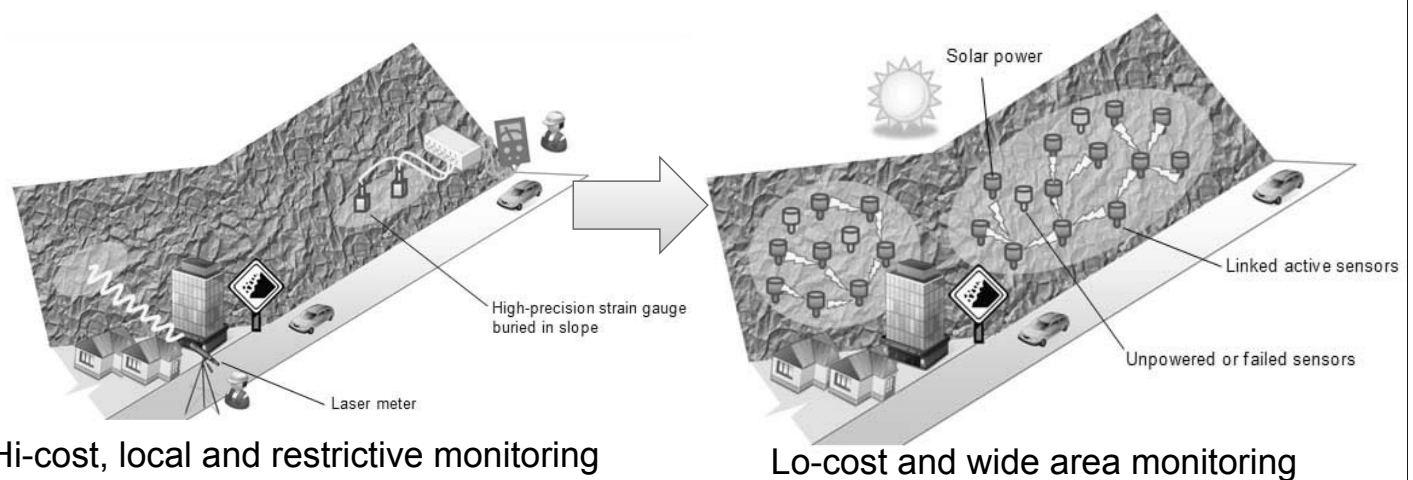
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## Background ~ Our mission

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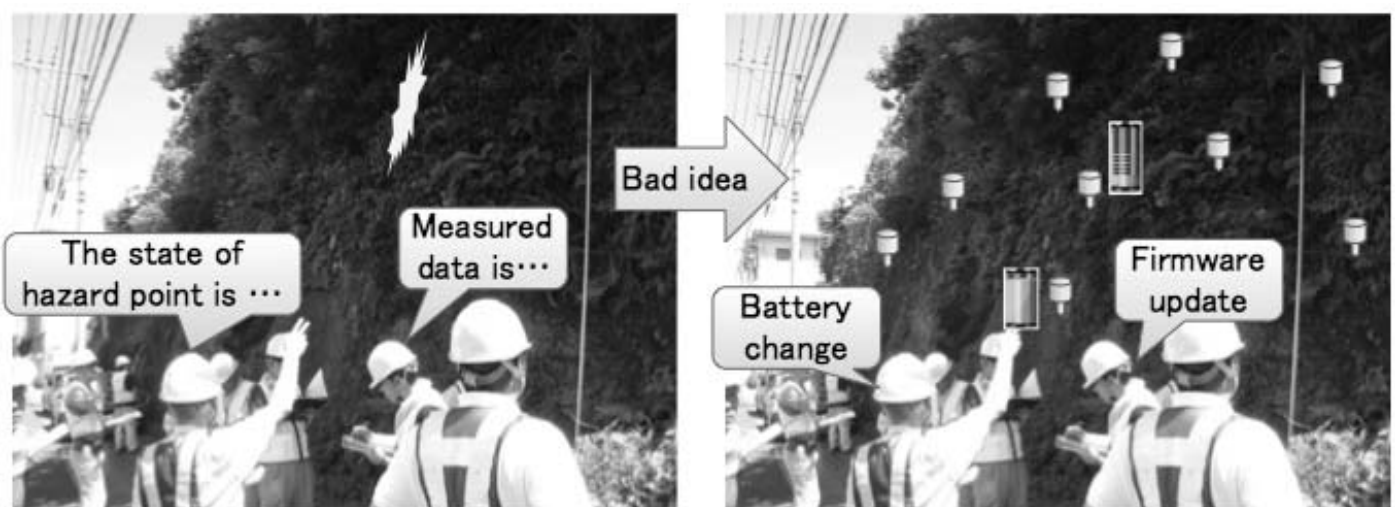
Existing technologies for environmental monitoring have not spread to here and there... difficulty of installing, running cables, replacing batteries, and cost.

They have only been deployed over small areas, and the promise of effectively collecting data in a grid over a wide area has not yet been realized.



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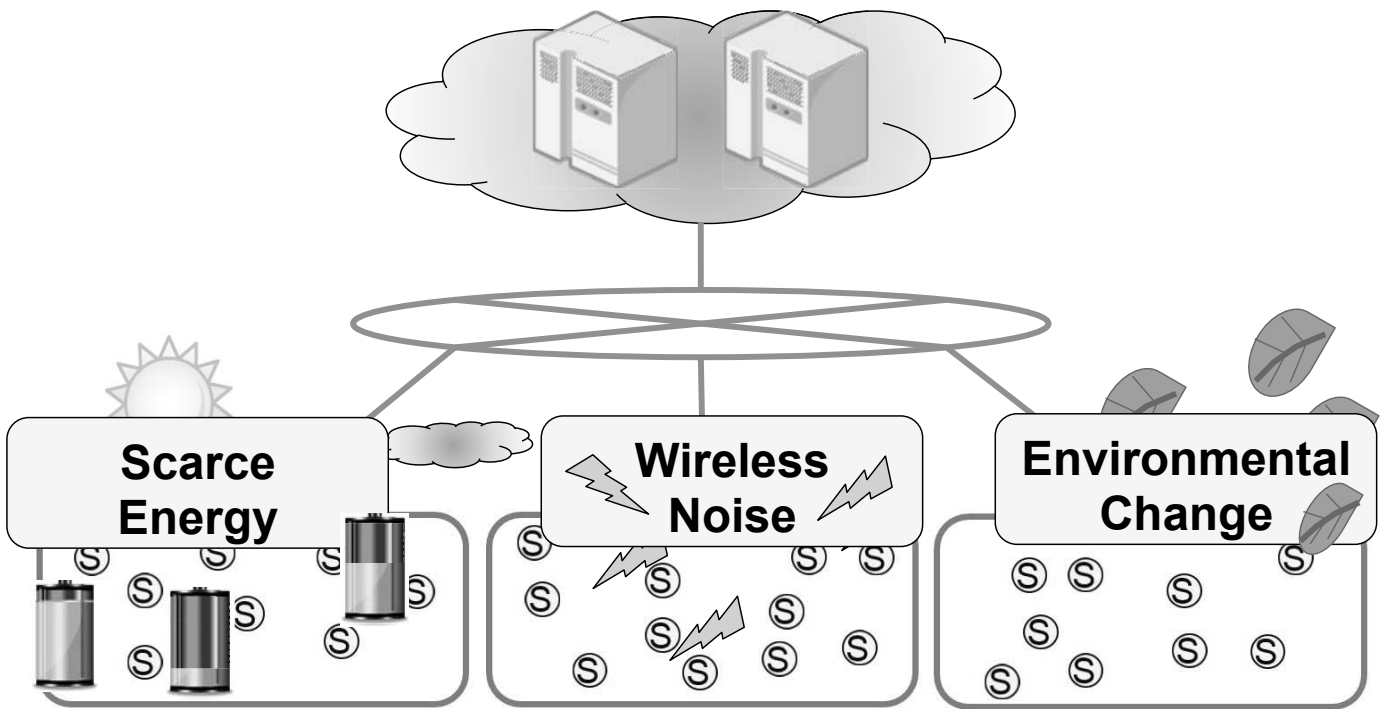
- Distributed control system for large number of sensors
  - Wireless communication and topology between sensors
  - Low power consumption control of sensor
- Flexibly corresponding scheduling method
  - Power scheduler : Variations in the environment power harvesting
  - Network scheduler : Data aggregation and communication quality
- System architecture design and implementation
  - Lo-cost sensor : Compact and small hardware devices
  - Maintenance-free sensor : Minimization of software implementation



Visual confirmation.  
The field measurement by luxurious  
measuring instrument.

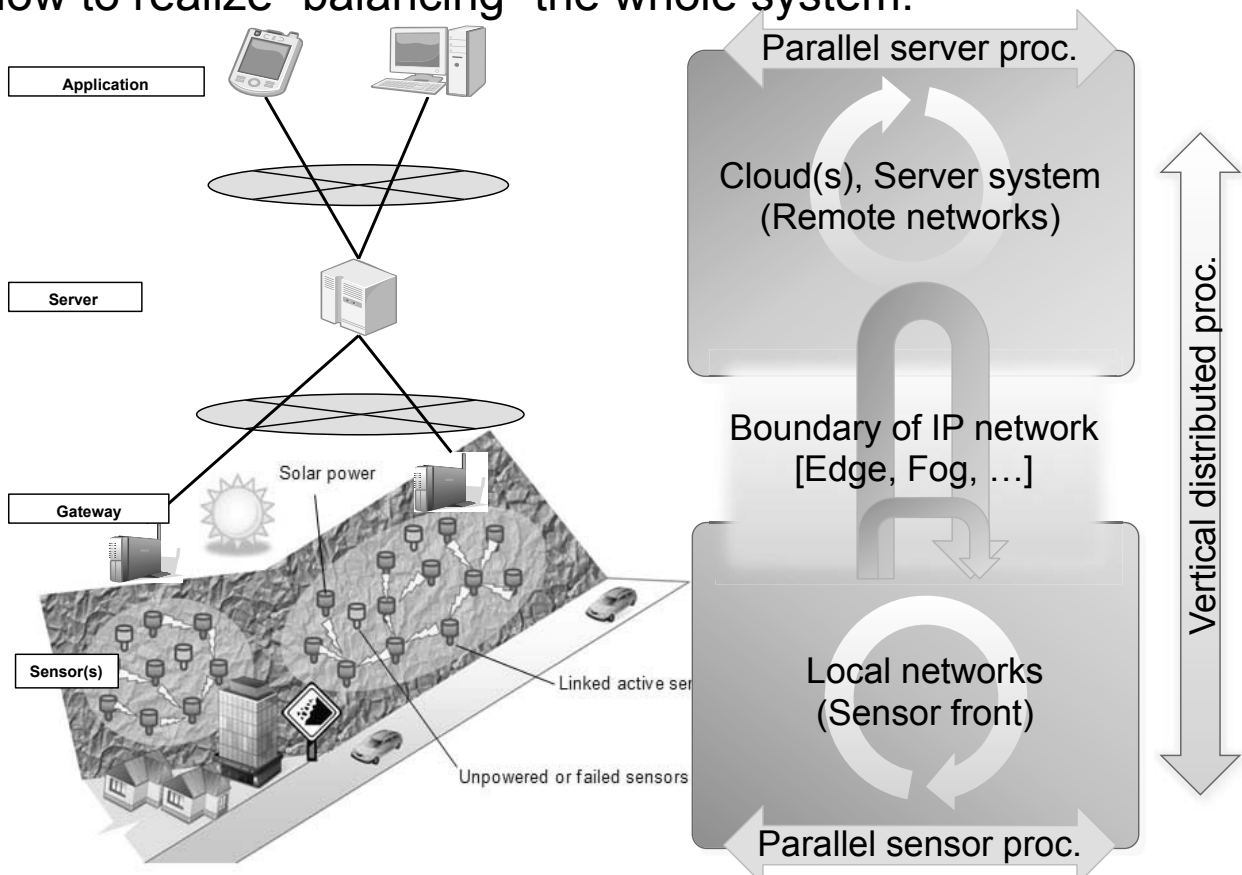
Inspection of the installed sensor.  
Battery exchange.

Even if hardware is fully optimized, a sensor network undergoes influence of a natural environment.



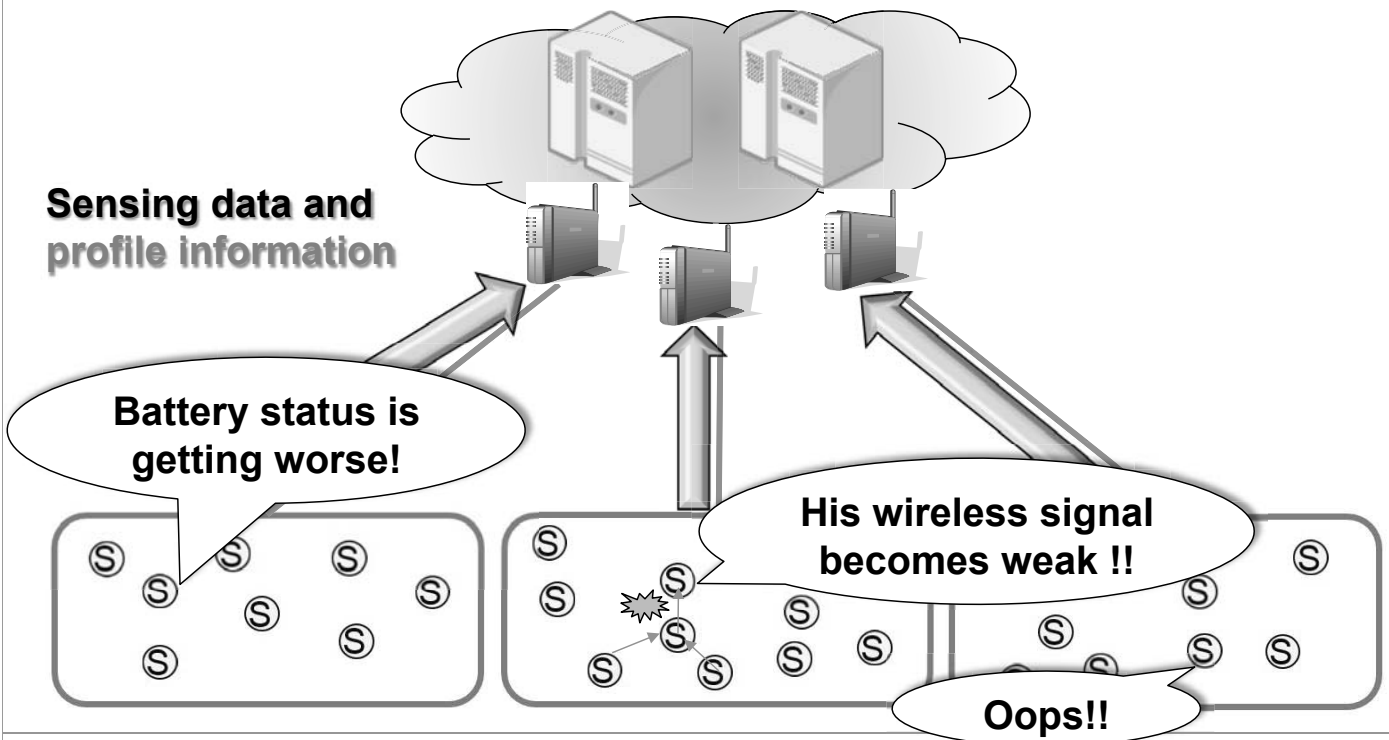
## Proposed system

■ How to realize “balancing” the whole system.



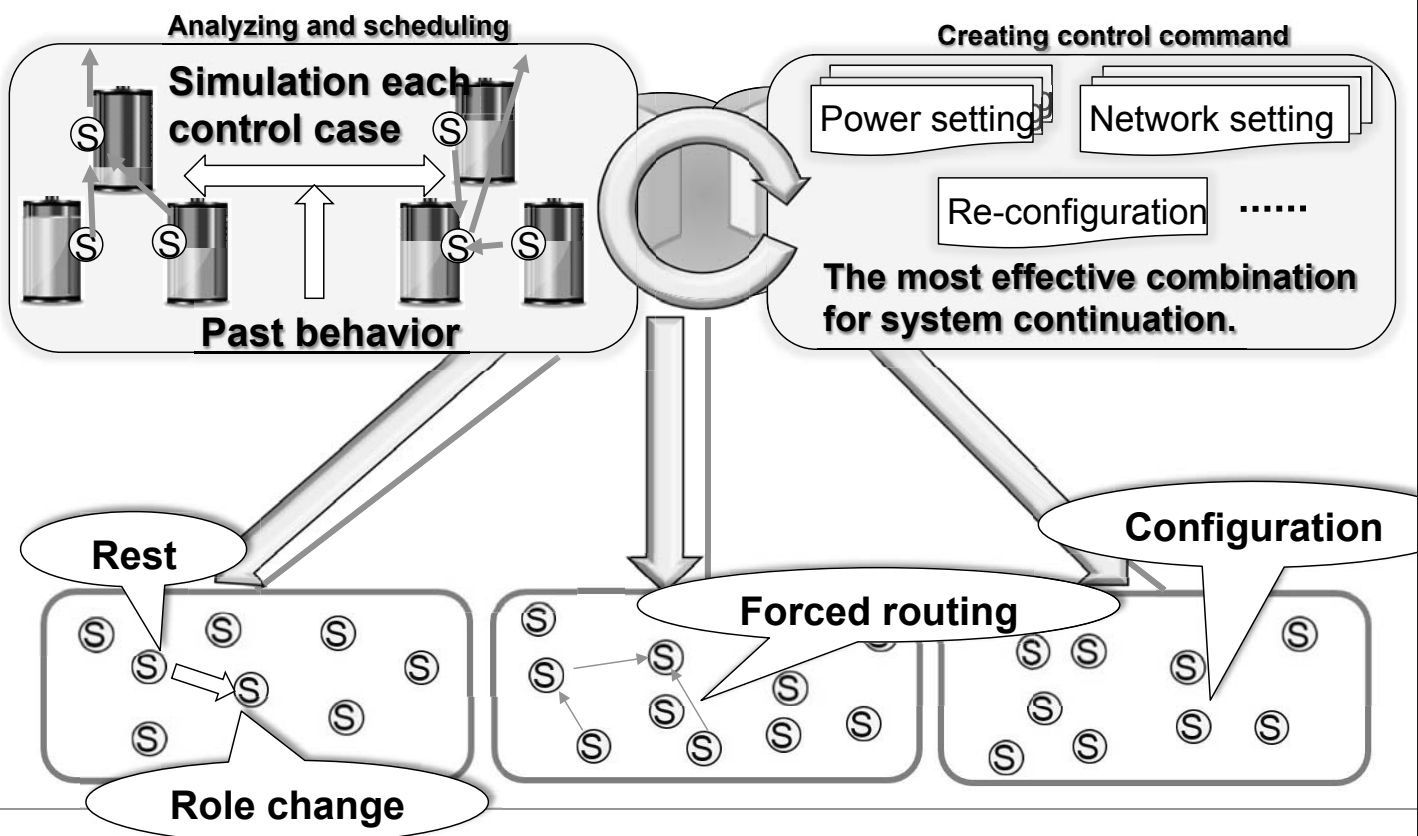
# Proposed software

A system collects not only sensed data, but also profiling information of sensor hardware.

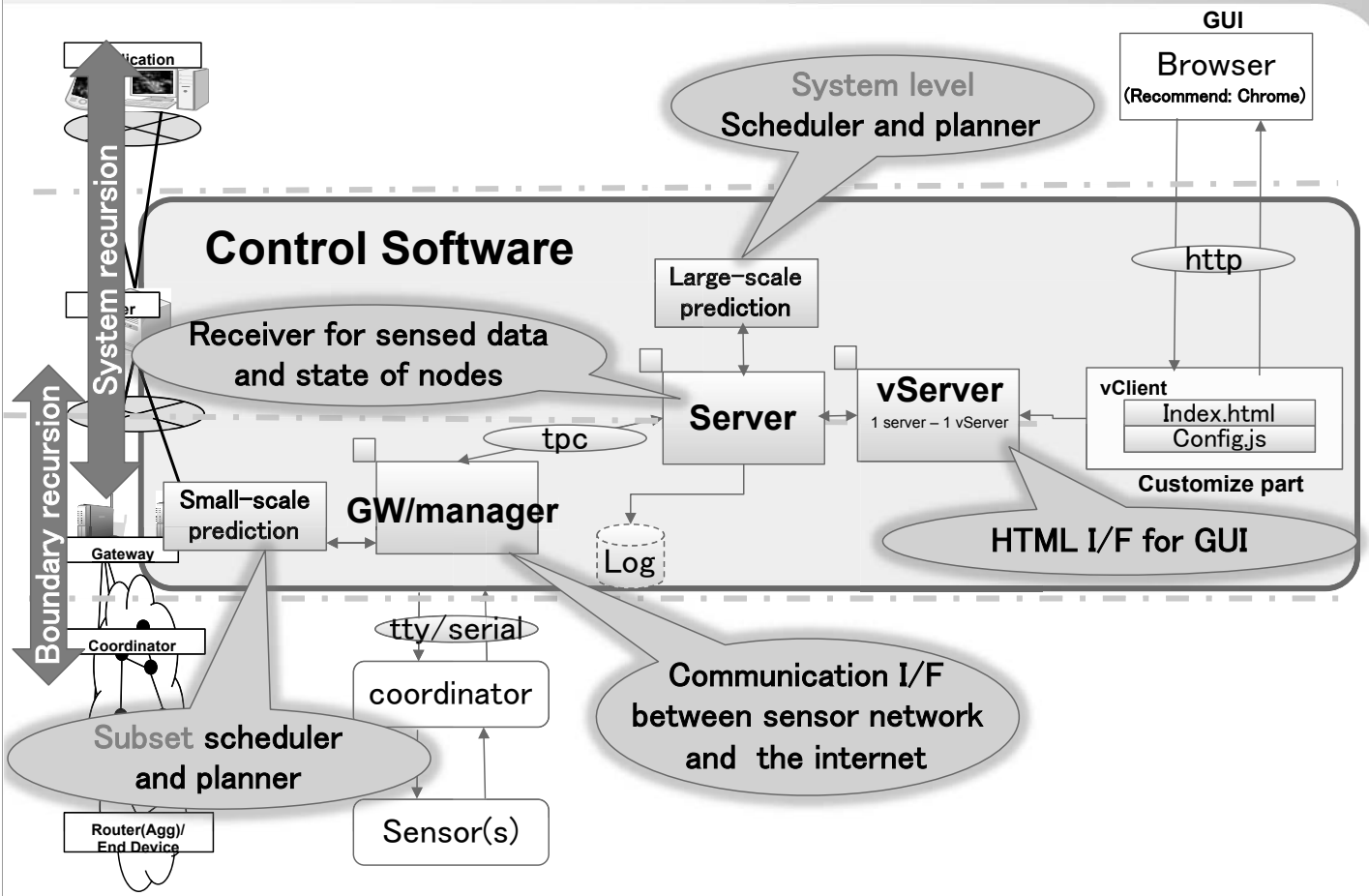


# Proposed software

A system compares the past information with profile information and schedules a sensor.

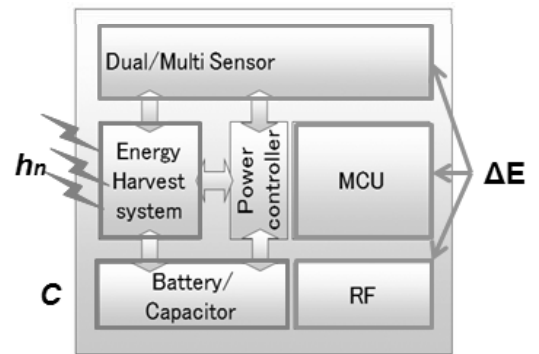
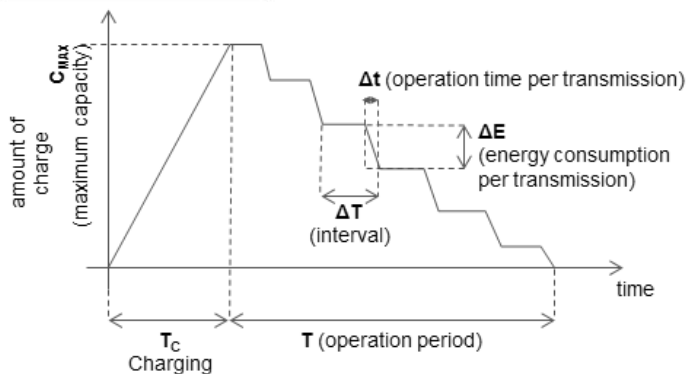


# Implementation (System overview)

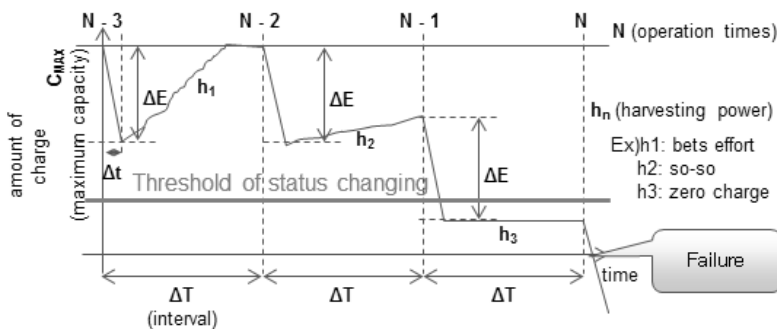


## Ex. Probabilistic model power scheduler(MPSoC2014)

### Theoretical model



### Actual model



### Consideration on the Large scale prediction

$p = 100\%$  is not necessary.  
Value of " $p$ " or " $N$ " is most important.

It is less than  $C_{max}$ .

Expectation  $(h_1, h_2, h_3, \dots)$

$$P_{possibility} \left[ \sum_{n=0}^N \int_0^{\Delta T} h_n dt - N\Delta E > 0 \right] \geq p\%$$

$$h_n = H(x, y, z, \dots)$$

: Function of harvesting power

Uncertain parameters  
Depend on environments.

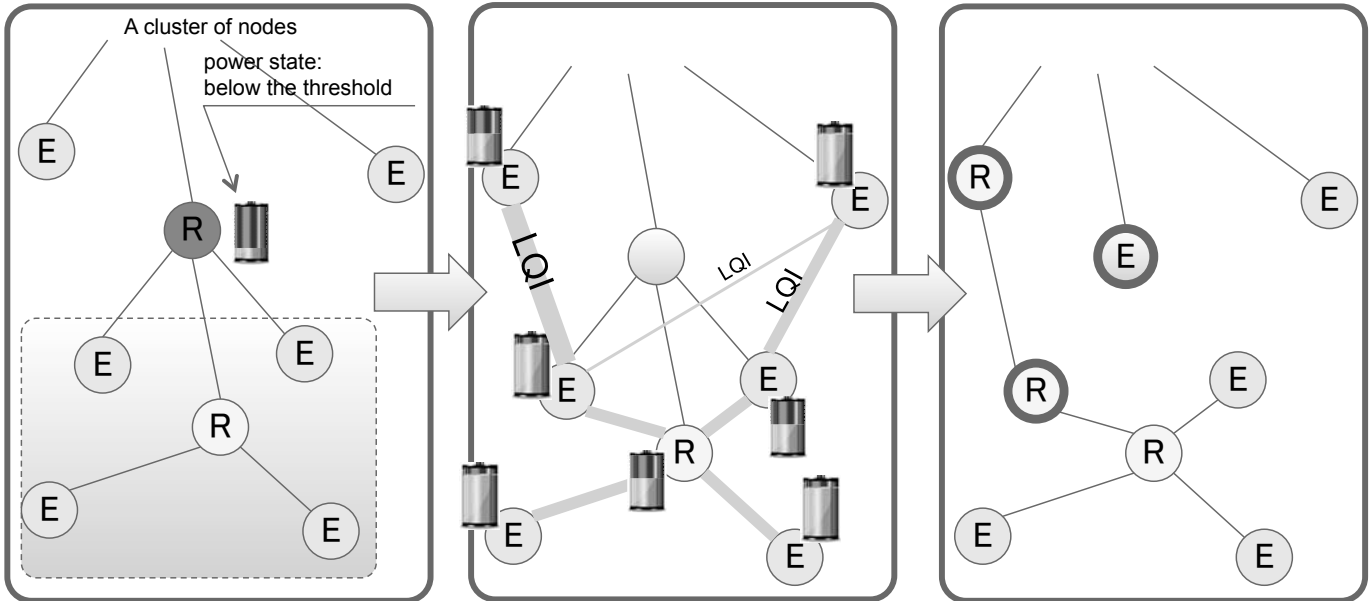
Default threshold is 25% remaining power amount to the inflection point.

# Ex. Network and power scheduler

Children and grandchildren will disconnect when "R" becomes power off.

Search surrounded node's power status and LQI value. System refers to the movement situation of the past and relocate the appropriate "Router" which has no partiality.

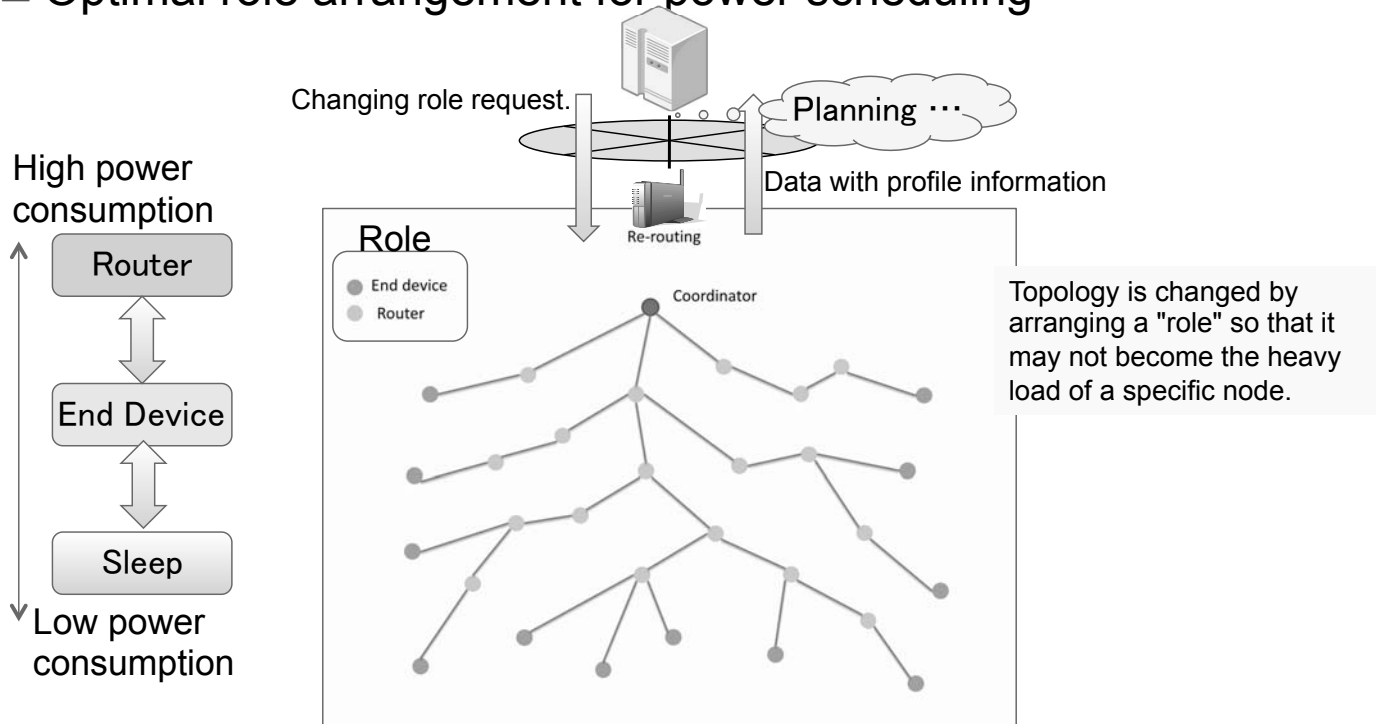
The system only changes the role of "R" and "E". The system layer DO NOT specify the concrete network. After "Construct" operation, local system (Zigbee) autonomously construct the topology.



GUI has I/F which operates role change manually to control safety and certainly.

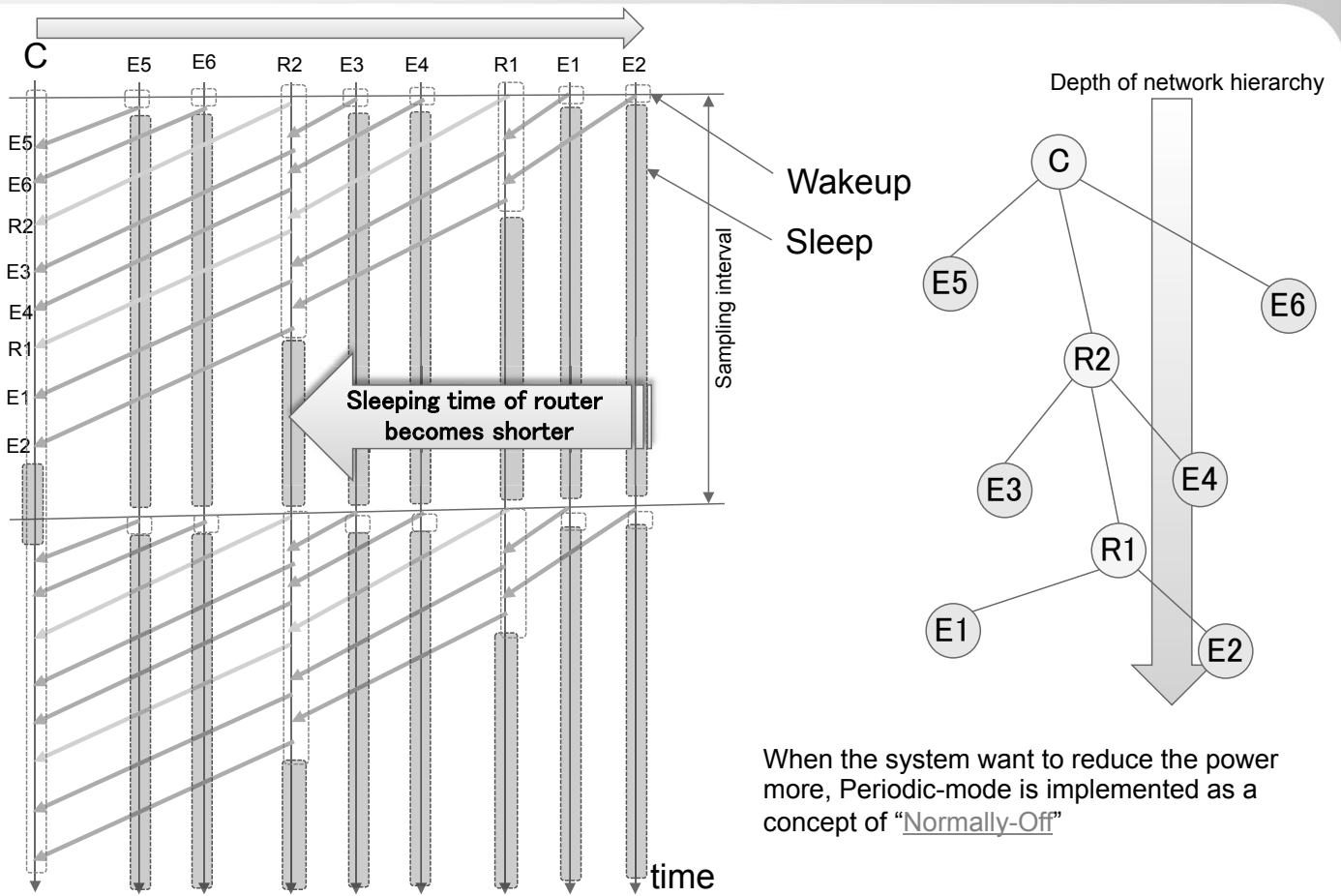
# Ex. An image of sensor network status

## ■ Optimal role arrangement for power scheduling



When the power of the "End Device" is exhausted, it sleeps, but even a few days darkness it acts continuously by low-power designed hardware and a optimal battery capacity.

# Ex. Subset scheduler (Periodic control)



# Specs of the prototype sensor

	Spec.	Note
Wireless	IEEE802.15.4 (Zigbee)	Emission range :Max 100m
Solar panel	200mW	5cm x 10cm
Battery	3.7V 3200mAh	Li-ion
Sensor	Pressure 3 axis gravity Temperature	Underground water pressure Angle and vibration
Monitoring	Sampling: Every 3-10min Distance :30-50m	
Node software	Footprint : 8KByte ROM 2K/RAM 6K	(10MHz CPU) Command interpreter Iterative processing Sequential processing Sleep
Power consumption	Peak: 130mW Idle : 3mW	

In the comparison study, requiring battery replacement every 13-15 month at three times the battery capacity.

# Field experiment

Side slope of freeway



Pre-construction field



Deep mountain area



Old stone wall



Hundreds of nodes have been running over one year without maintenance.


# Field experiment



Prototype sensor







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