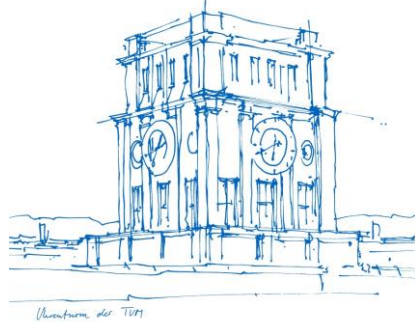


Information Processing Factory – Conquering MPSoC Complexity with Self-Aware Computing Platforms

Andreas Herkersdorf – TU München
Nikil Dutt, Fadi Kurdahi – UC Irvine
Rolf Ernst – TU Braunschweig



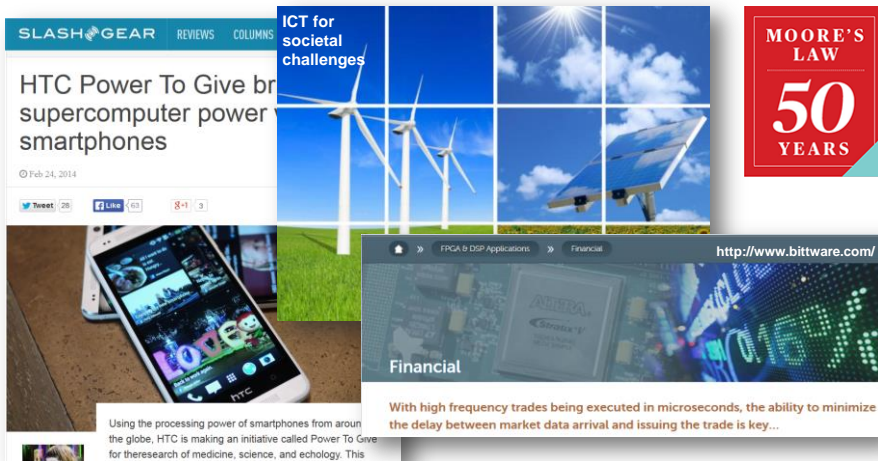
MPSoC Forum 2017

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Many thanks for their valuable contributions to and generous support for funding our projects go to:

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- the German Research Foundation (DFG), the National Science Foundation (NSF), Semiconductor Research Corp. (SRC)

Computing Platform Evolution – The Excitement



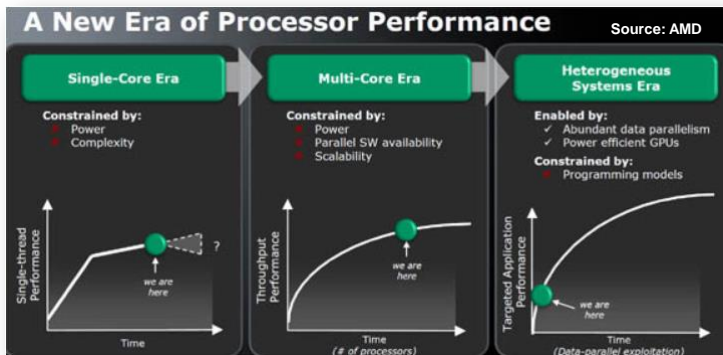
3

Computing Platform Evolution – The Excitement

- Massive increase in terms of number of functions per device and sophistication per application
- Increasing demand for adopting (heterogeneous) multi-cores
- Many different form factors:
 - Compute performance
 - Power / energy budget
 - Safety, Security
 - Hard real-time
 - Reliability
 - Cost



Computing Platform Evolution – The Challenges



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Computing Platform Evolution – The Challenges

IEEE MICRO, November – December 2005


DESIGNING RELIABLE SYSTEMS FROM UNRELIABLE COMPONENTS: THE CHALLENGES OF TRANSISTOR VARIABILITY AND DEGRADATION

Shekhar Borkar
Intel Corp.

AS TECHNOLOGY SCALES, VARIABILITY IN TRANSISTOR PERFORMANCE WILL CONTINUE TO INCREASE, MAKING TRANSISTORS LESS AND LESS RELIABLE.

Appears in the Proceedings of the 38th International Symposium on Computer Architecture (ISCA '11)

Dark Silicon and the End of Multicore Scaling



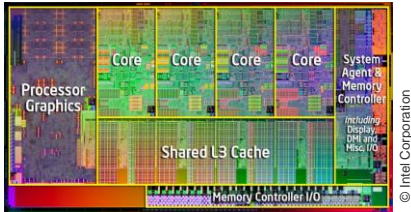
Hadi Esmaeilzadeh¹ Emily Blem¹ Renée St. Amant² Karthikeyan Sankaralingam³ Doug Burger⁴

¹University of Washington ²University of Wisconsin-Madison
³The University of Texas at Austin ⁴Microsoft Research

hadiaeh@cs.washington.edu blem@cs.wisc.edu stamant@cs.utexas.edu karu@cs.wisc.edu dburger@microsoft.com

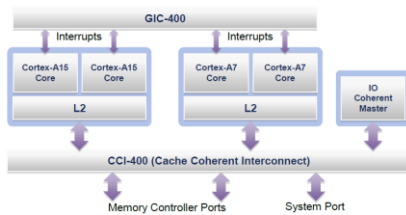
6

Heterogeneity ⇔ Complexity

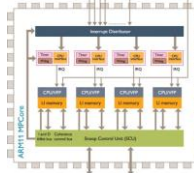


Intel Core i7 (Sandy Bridge)

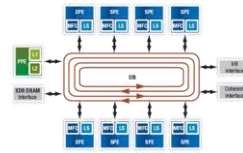
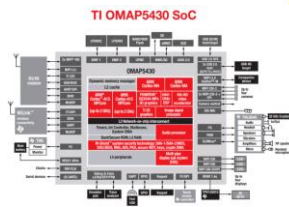
© Intel Corporation



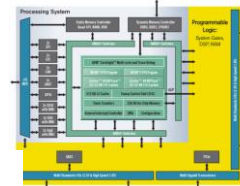
ARM Big.LITTLE



ARM MPcore



IBM CELL

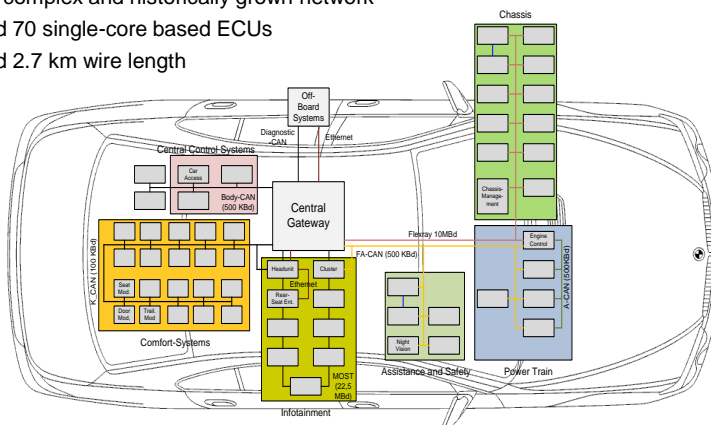


XILINX Zynq

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State-of-the-Art Automotive Embedded System (of Systems)

- Highly complex and historically grown network
- Around 70 single-core based ECUs
- Around 2.7 km wire length

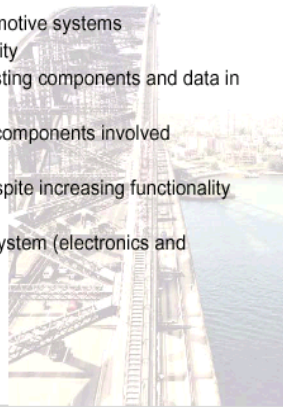


[Michel 2013] **Taming multicores for safe transportation: ARAMIS in the automotive domain**
Workshop on the Integration of mixed-criticality subsystems on multi-core processors at HiPEAC 2013

Automotive Electronics

Key Challenges for Automotive Electronics

- **Increasing complexity** of networked automotive systems
 - Subsystems with increasing functionality
 - New functions realised by utilizing existing components and data in other subsystems
 - Various suppliers of subsystems and components involved
- **Affordability** of automotive electronics despite increasing functionality
- **Quality and reliability** of a very complex system (electronics and mechanics) in a harsh environment
- **Long term supply** of the aftermarket



Automotive Electronics

10 Dr. Claus Schmitt, AEM/E | 9/10/2006 | © Robert Bosch GmbH reserves all rights even in the event of industrial property rights. We reserve all rights of disposal such as copying and passing on to third parties.



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Reliability Requirements in Car Systems

Warranty Goal: 100.000 Meilen/10 Years

ECU failure rate (field)	10 ppm
Failure rate modules und sensors	< 10 ppm
ASIC failure rate	< 1 ppm
Standard-IC failure rate	<< 1 ppm
Discrete components	< 0.5 ppm

→ Goal for ASICs: To develop and produce (→ deliver) **zero defects** for the whole production volume

Automotive Electronics

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Challenges for Future Embedded / CPS Computing Platforms

- **Programming and application partitioning for efficient utilization of nominally available processing resources**
 - Migration (with and without parallelization) of existing legacy code onto multicore processors
 - Model-based design, programming models and tools for the design and validation of multicore processor hardware and applications
- **Guarantees for extra-functional requirements**
 - Real-time, energy & power efficiency, security, safety
 - Mixed-criticality applications accessing shared processing resources (memory, on-chip interconnect, I/O interfaces)
 - Technology induced variability challenges
- **Overwhelming complexity** at multiple abstraction levels of Hardware/Software systems

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Self-Aware / Self-Organizing Information Processing Factory



- Scalability of control through higher sub-system autonomy ...
- ... while operating within a corridor of guaranteed objectives and operation parameters

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Objectives of a Self-Aware Information Processing Factory

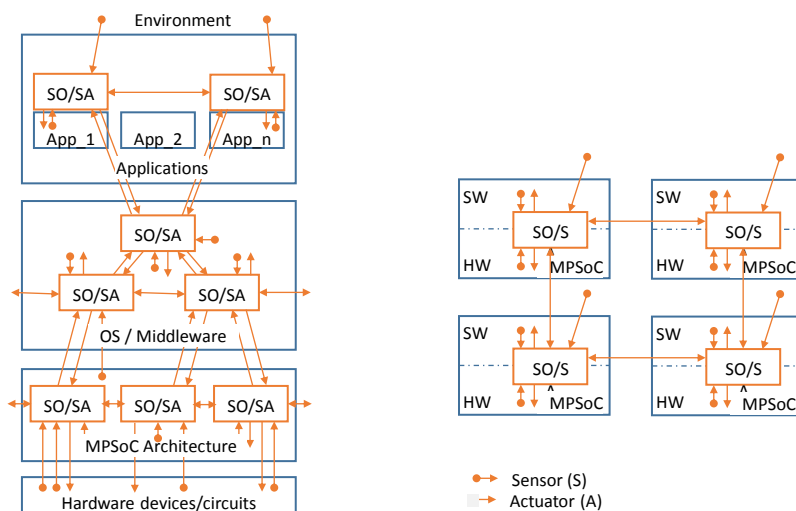
- **Envision a holistic, hierarchically structured platform control**
 - As modular and decentralized as possible, ...
 - ... as much centralized as necessary
 - Scalability and dynamic elasticity to react on short/long term workload fluctuation and platform uncertainties

- **Orthogonal functional and control complexity**
 - Self-awareness through ubiquitous sensing of platform and environment
 - Self-organized local actions
 - Inspired by self-organization and emergent phenomena in nature

- **Predictive guarantees for critical tasks / functions**
 - Long term planning and logistics

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Self-Aware / Self-Organizing Information Processing Factory



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IPF Use Case: ECU Platform for Automated Driving

Perception

- Surround sensing (sensors)
- Online map data (internet)
- Grid fusion (uncertainty)

Orientation

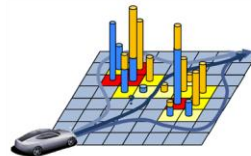
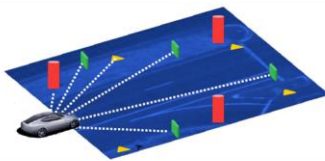
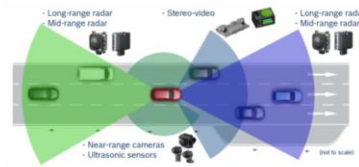
- Location sensing (GPS)
- Image processing (landmarks)
- Online map data (landmarks)
- Data fusion (GPS+landmarks)

Intelligence

- Trajectory calculation and assessment
- Target trajectory

Motion

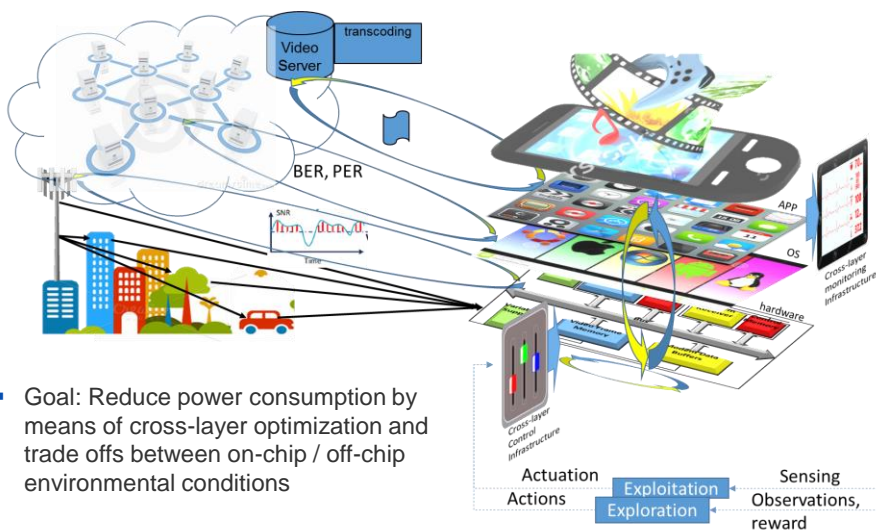
- Motion control



Source: Michael Fausten, Bosch, ESWEEK 2015

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IPF Use Case: Self-Aware SmartPhone Platform



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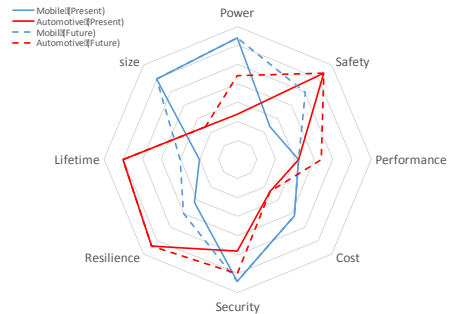
Comparison on Use Case Requirements

Automated Driving

- Safety, lifetime and resilience dominated
- Foreseeable future challenges with power, security and performance

Mobile Devices

- Performance / W, size, security and cost are main challenges
- Safety in context of medical applications expected to rise



Trend: System evolution and convergence (SmartPhones as integrated devices in future cars) will lead to requirements convergence

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Related Work

There is a rich portfolio of related work from which we plan to adopt proven concepts and enhance wherever relevant to our work

Coarse classification of relevant related work:

- Autonomous Computing
 - Primarily dealing with large scale, self-organizational IT systems
- Self-aware Computing for Control
- Multi-agent Systems in services and operation

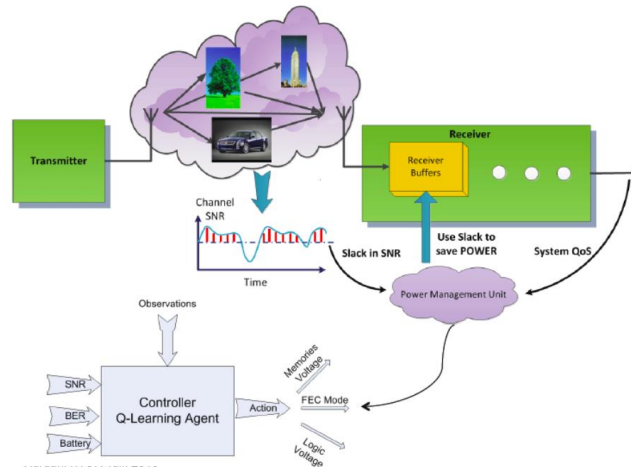
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Prior Art: Cognitive Power Management

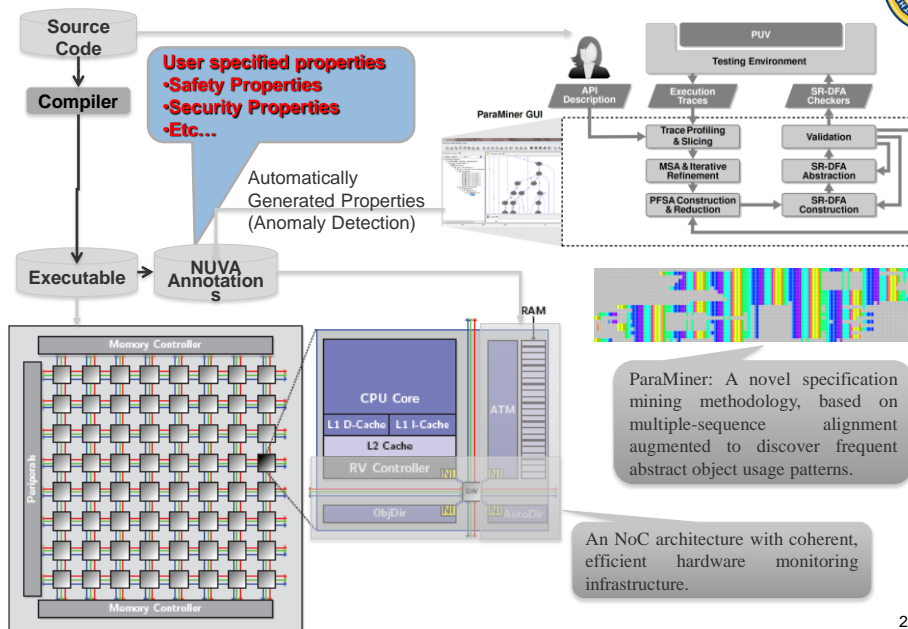
Reactive, channel-aware power management

- Learning-based cognitive control across multiple layers and multiple applications within one layer



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NUVA – Runtime Verification Architecture



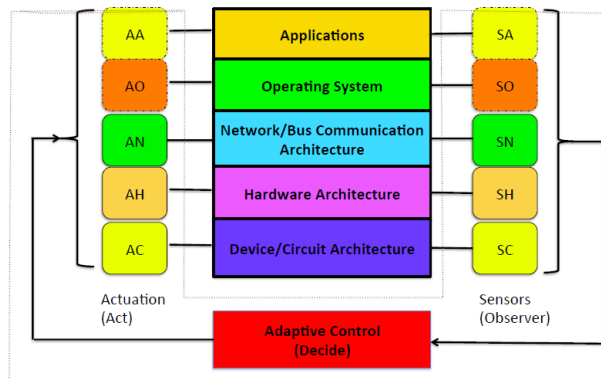
20



Prior Art: CPSoC - Cyber Physical System on Chip

Sensor/Actor rich SoC with software enabled adaptive control of platform resources

- Self-aware, reflective (observe-decide-adapt) architecture to achieve closed loop system control
- Dynamic characterization of platform variability across multiple levels of system stack



See next presentation for in depth treatment

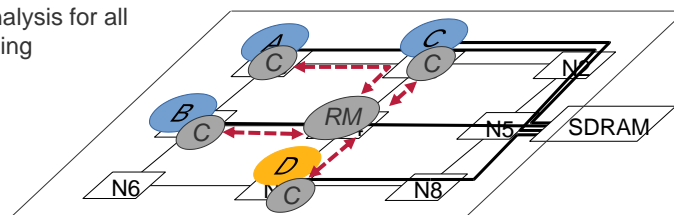
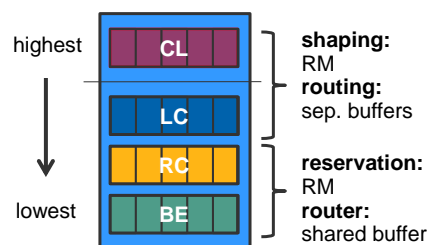
21



Prior Art: IDAMC – Dependable Architecture for Many-Cores

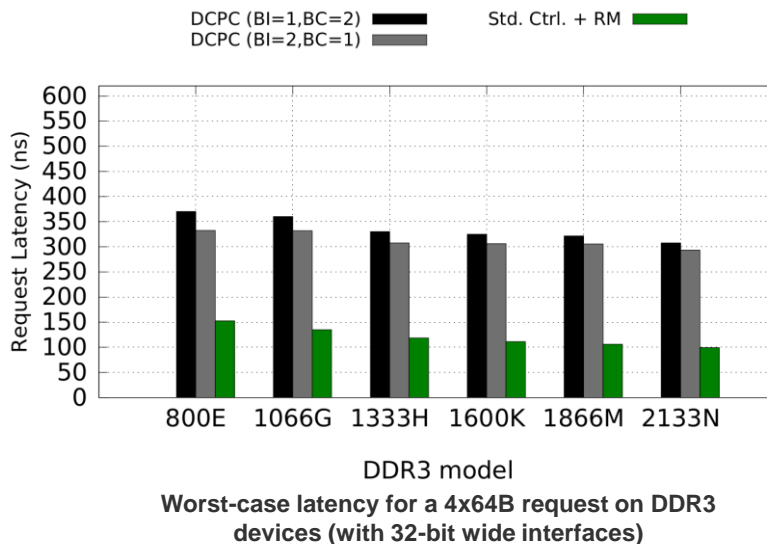
Configurable NoC with central Resource Manager provisioning VC-based interconnect channel assignments and memory accesses for safety critical applications

- Decoupled data flow and control protocol
- Protocol based synchronization
- Predictable SDRAM scheduling
- Worst case timing analysis for all traffic levels and routing mechanisms



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Resource Managers and SDRAM scheduling



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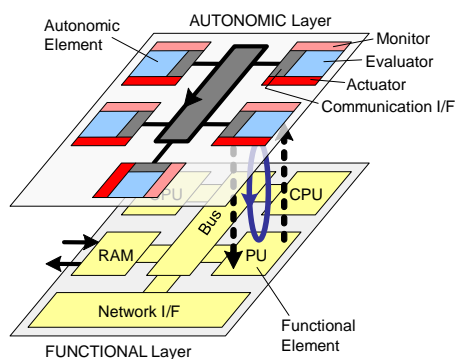
Prior Art: ASoC - Autonomic System on Chip

Evolutionary, platform-centric approach with compatibility to SoC design method:

- Functional layer containing conventional IPs
- Autonomic layer extends IPs with self-x properties
 - Improved Reliability
 - Performance / Power optimization at runtime

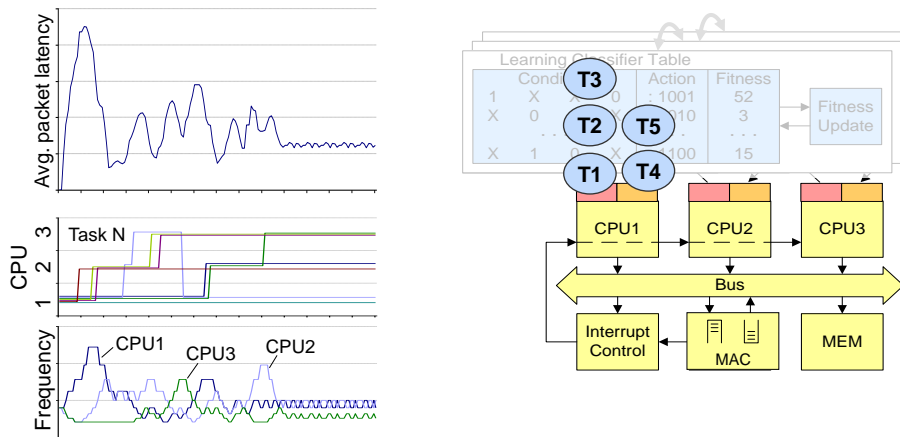
Dedicate part of chip capacity to self-x abilities at autonomic layer

Future SoC shall have the ability to learn to live with environmentally imposed variations or work around defects autonomously



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ASoC: Self-Optimization through Runtime Learning



Self-Aware IPF Platform Integration

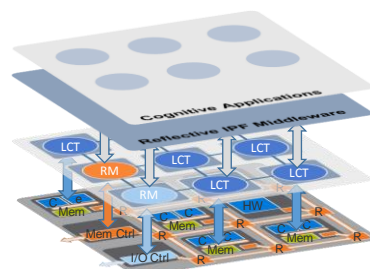


Moving long term, robust and interdependent system operation in the focus of platform design

- Reuse, converge and enrich existing HW/SW building blocks
 - Interworking between TUBS RM and TUM LCT, ...
 - ... as well as with UCI CPSoC middleware
 - and cognitive control within applications

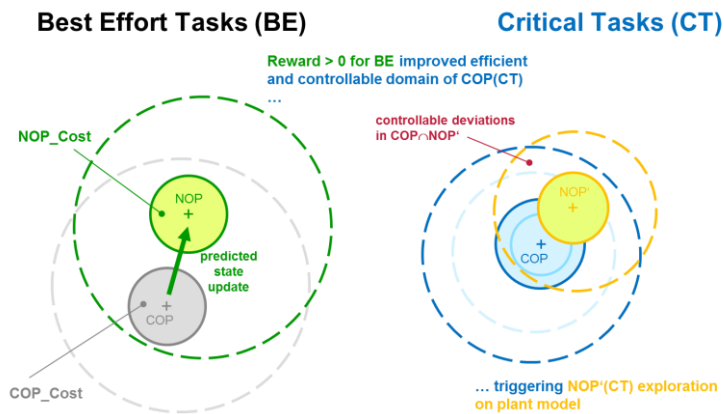
Facilitate

- Exploitation of emergent control efficiency, ...
- ... with hard guarantees for critical tasks
- Stable and effective coexistence of HW/SW machine learning entities at different layers



Relevant IPF Research Challenges

- Ensure robust, predictable system properties with a hybrid combination of self-aware / self-organizing emergent control and classical WC-oriented control?



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Relevant IPF Research Challenges

- Ensure robust, predictable system properties with a hybrid combination of self-aware / self-organizing emergent control and classical WC-oriented control?
- How to combine various self-aware individual system constituents into higher-layer group awareness?
 - What type and amount of sensor information to transfer among different SO/SA levels?
- What cost/overhead for a holistic IPF control framework is realistic?
- On a more general perspective: What can we learn from logistics and organization of factories given our societal experience in this field?

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Thanks!